

# The Discrete Fourier Transform\*

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October 4, 2005

## 1 Motivation

We want to numerically approximate coefficients in a Fourier series. The first step is to see how the trapezoidal rule applies when numerically computing the integral  $(2\pi)^{-1} \int_0^{2\pi} F(t)dt$ , where  $F(t)$  is a continuous,  $2\pi$ -periodic function. Applying the trapezoidal rule with the stepsize taken to be  $h = 2\pi/n$  for some integer  $n \geq 1$  results in

$$(2\pi)^{-1} \int_0^{2\pi} F(t)dt \approx \frac{1}{n} \sum_{j=0}^{n-1} Y_j,$$

where  $Y_j := F(hj) = F(2\pi j/n)$ ,  $j = 1 \dots n-1$ . We remark that we made use of  $Y_n = F(2\pi) = F(0) = Y_0$  in employing the trapezoidal rule to arrive at the right hand side of the equation above. Recall that the coefficients in a Fourier series expansion for a continuous,  $2\pi$ -periodic function  $f(t)$  have the form

$$c_k = \frac{1}{2\pi} \int_0^{2\pi} f(t) \exp(-ikt)dt.$$

We can apply the version of the trapezoidal rule derived above to approximately calculate the  $c_k$ 's, since  $f(t) \exp(-ikt)$  is  $2\pi$ -periodic. Doing so yields

$$c_k \approx \frac{1}{n} \sum_{j=0}^{n-1} f(2\pi j/n) \exp(-2\pi ijk/n) = \frac{1}{n} \sum_{j=0}^{n-1} y_j \bar{w}^{jk},$$

where  $y_j = f(2\pi j/n)$  and  $w = \exp(2\pi i/n)$ . If we replace  $k$  by  $k+n$ , the right hand side of the last equation is unchanged, for  $\bar{w}^n = \exp(-2\pi i) = 1$ .

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\*These notes are based on [1, Chapter 3].

Consequently, only the approximations to  $c_k$  for  $k = 0 \dots n - 1$  need be calculated. Given these approximations, however, one may recover  $y_j$ ,  $j = 0 \dots n - 1$ . To see this, let

$$\hat{y}_k = \sum_{j=0}^{n-1} y_j \bar{w}^{jk},$$

so that  $c_k \approx \hat{y}_k/n$ . Multiply both sides by  $w^{k\ell}$  and sum over  $k$ :

$$\sum_{k=0}^{n-1} \hat{y}_k w^{k\ell} = \sum_{j=0}^{n-1} y_j \sum_{k=0}^{n-1} w^{(\ell-j)k}.$$

The sum over  $k$  on the right can be evaluated via the algebraic identity

$$\sum_{k=0}^{n-1} z^k = \begin{cases} \frac{z^n - 1}{z - 1} & \text{if } z \neq 1 \\ n & \text{if } z = 1. \end{cases}$$

Recalling that  $w^n = 1$ , setting  $z = w^{j-\ell}$  above, and noting that  $w^{j-\ell} \neq 1$  unless  $j = \ell$ , one gets

$$\sum_{k=0}^{n-1} w^{(\ell-j)k} = \begin{cases} 0 & \text{if } j \neq \ell \\ n & \text{if } j = \ell. \end{cases}$$

Consequently, we find that

$$\frac{1}{n} \sum_{k=0}^{n-1} \hat{y}_k w^{k\ell} = y_\ell.$$

Thus the  $y$ 's can be calculated if we know the  $c$ 's or  $\hat{y}$ 's .

## 2 Definition

Let  $\mathcal{S}_n$  be the set of periodic sequences of complex numbers with period  $n$ . The set  $\mathcal{S}_n$  forms a complex vector space under the operations of entry-by-entry addition and entry-by-entry multiplication by a scalar. Let  $y = \{y_j\}_{j=-\infty}^{\infty} \in \mathcal{S}_n$ , so that  $y_{j+n} = y_j$  for all  $j$ . We can associate to each  $y$  a new sequence  $\hat{y}$  via

$$\hat{y}_k = \sum_{j=0}^{n-1} y_j \bar{w}^{jk}.$$

This is the same formula that we used to find  $\hat{y}_k$  in §1; the only differences are that the  $y_j$ 's are do not necessarily come from a continuous function, and that the index  $k$  above is not restricted to  $\{0, \dots, n-1\}$ . The sequence  $\hat{y}$  is periodic with period  $n$ . To see this, note that

$$\begin{aligned}\hat{y}_{k+n} &= \sum_{j=0}^{n-1} y_j \bar{w}^{j(k+n)} = \sum_{j=0}^{n-1} y_j \bar{w}^{jk} \bar{w}^{nj} \\ &= \sum_{j=0}^{n-1} y_j \bar{w}^{jk} \quad [\bar{w}^n = e^{-(2\pi i/n)n} = 1] \\ &= \hat{y}_k\end{aligned}$$

Put another way,  $\hat{y} \in \mathcal{S}_n$ . The mapping  $y \in \mathcal{S}_n \mapsto \hat{y} \in \mathcal{S}_n$  defines the discrete Fourier transform. We will write  $\hat{y} = \mathcal{F}[y]$ . In addition, the formula derived in §1 giving  $y_j$ 's in terms of  $\hat{y}_k$ 's certainly applies here as well. Thus, after changing the “dummy” indices, one gets this formula for  $y_j$ 's in terms of  $\hat{y}_k$ 's:

$$y_j = \frac{1}{n} \sum_{k=0}^{n-1} \hat{y}_k w^{jk}.$$

This is the inversion formula for the DFT. We denote the inverse correspondence  $\hat{y} \in \mathcal{S}_n \mapsto y \in \mathcal{S}_n$  by  $y = \mathcal{F}^{-1}[\hat{y}]$ .

Both  $\mathcal{F}$  and  $\mathcal{F}^{-1}$  are linear transformations from  $\mathcal{S}_n$  to itself. Here are some additional properties that you can verify as exercises.

1. Shifts. If  $z$  is the periodic sequence formed from  $y \in \mathcal{S}_n$  via  $z_j = y_{j+1}$ , then  $\mathcal{F}[z]_k = w^k \mathcal{F}[y]_k$ .
2. Convolutions. If  $y \in \mathcal{S}_n$  and  $z \in \mathcal{S}_n$ , then the sequence defined by  $[y * z]_j := \sum_{m=0}^{n-1} y_m z_{j-m}$  is also in  $\mathcal{S}_n$ . The sequence  $y * z$  is called the *convolution* of  $y$  and  $z$ .
3. The Convolution Theorem:  $\mathcal{F}[y * z]_k = \mathcal{F}[y]_k \mathcal{F}[z]_k$ .

### 3 An application

Consider the differential equation

$$u'' + au' + bu = f(t),$$

where  $f$  is a continuous,  $2\pi$ -periodic function of  $t$ . There is a well-known analytical method for finding the unique periodic solution to this equation

(cf. Boyce & DiPrima, fifth edition, §3.7.2—forced vibrations), provided  $f$  is known for all  $t$ . On the other hand, if we only know  $f$  at the points  $t_j = jh$ , where again  $h = 2\pi/n$  for some integer  $n \geq 1$ , this method is no longer applicable.

Instead of directly trying to work with the differential equation itself, we will work with a discretized version of it. There are many ways of discretizing; the one that we will use here amounts to making these replacements:

$$\begin{aligned} u'(t) &\longrightarrow \frac{u(t) - u(t-h)}{h}, \\ u''(t) &\longrightarrow \frac{u(t+h) + u(t-h) - 2u(t)}{h^2}. \end{aligned}$$

Replacing  $u'$  and  $u''$  in the differential equation and setting  $t = 2\pi j/n$ , we get the following difference equation for the sequence  $u_j = u(2\pi j/n)$ :

$$u_{j+1} + \alpha u_j + \beta u_{j-1} = h^2 f_j,$$

where  $f_j = f(2\pi j/n)$ ,  $\alpha = bh^2 + ah - 2$ , and  $\beta = 1 - ah$ .

Let  $u \in \mathcal{S}_n$  be a solution to the difference equation derived above, and let  $\hat{u} = \mathcal{F}[u]$ . In addition, let  $\hat{f} = \mathcal{F}[f]$ . From the inversion formula for the DFT, we have

$$u_j = \frac{1}{n} \sum_{k=0}^{n-1} \hat{u}_k w^{jk} \quad \text{and} \quad f_j = \frac{1}{n} \sum_{k=0}^{n-1} \hat{f}_k w^{jk}.$$

Inserting these in the difference equation then yields, after multiplying by  $n$ ,

$$\sum_{k=0}^{n-1} \hat{u}_k w^{k(j+1)} + \alpha \sum_{k=0}^{n-1} \hat{u}_k w^{jk} + \beta \sum_{k=0}^{n-1} \hat{u}_k w^{k(j-1)} = \sum_{k=0}^{n-1} h^2 \hat{f}_k w^{jk}.$$

Combining terms and doing an algebraic manipulation then results in this:

$$\sum_{k=0}^{n-1} (w^k + \alpha + \beta \bar{w}^k) \hat{u}_k w^{jk} = \sum_{k=0}^{n-1} h^2 \hat{f}_k w^{jk}.$$

Taking the inverse DFT of both sides and dividing by  $w^j + \alpha + \beta \bar{w}^j$ , which we assume is never 0, we find that

$$\hat{u}_k = h^2 (w^k + \alpha + \beta \bar{w}^k)^{-1} \hat{f}_k.$$

Thus we have found the DFT of  $u$ . Inverting this then recovers  $u$  itself. In the next section we will discuss methods for fast computation of the DFT and its inverse.

## 4 The Fast Fourier Transform

Let us consider the DFT of a periodic sequence  $y$  with period  $n = 2N$ . The  $\hat{y}_k$ 's are calculated via

$$\hat{y}_k = \sum_{j=0}^{2N-1} y_j \bar{w}^{jk}.$$

Splitting the sum above into a sum over even and odd integers yields

$$\begin{aligned} \hat{y}_k &= \sum_{j=0}^{N-1} y_{2j} \bar{w}^{2jk} + \sum_{j=0}^{N-1} y_{2j+1} \bar{w}^{(2j+1)k} \\ &= \sum_{j=0}^{N-1} y_{2j} \bar{W}^{jk} + \bar{w}^k \left( \sum_{j=0}^{N-1} y_{2j+1} \bar{W}^{jk} \right), \end{aligned}$$

where  $W := \exp(2\pi i/N) = w^2$ . We may rewrite this in terms of DFT's with  $n \rightarrow N$ :

$$\hat{y}_k = \mathcal{F}[\{y_0, y_2, \dots, y_{2N-2}\}]_k + \bar{w}^k \mathcal{F}[\{y_1, y_3, \dots, y_{2N-1}\}]_k.$$

A further savings is possible. In the last equation, let  $k \rightarrow k + N$  and use these facts: (1)  $\mathcal{F}[y^{\text{even}}]$  and  $\mathcal{F}[y^{\text{odd}}]$  both have period  $N$ . (2)  $\bar{w}^{k+N} = \bar{w}^k \exp(-\pi i) = -\bar{w}^k$ . The result is that for  $0 \leq k \leq N-1$  we have

$$\begin{cases} \hat{y}_k = & \mathcal{F}[\{y_0, y_2, \dots, y_{2N-2}\}]_k + \bar{w}^k \mathcal{F}[\{y_1, y_3, \dots, y_{2N-1}\}]_k \\ \hat{y}_{k+N} = & \mathcal{F}[\{y_0, y_2, \dots, y_{2N-2}\}]_k - \bar{w}^k \mathcal{F}[\{y_1, y_3, \dots, y_{2N-1}\}]_k. \end{cases}$$

Similar formulas can be derived for the inverse DFT; they are:

$$\begin{cases} y_k = & \frac{1}{2} \{ \mathcal{F}^{-1}[\{\hat{y}_0, \hat{y}_2, \dots, \hat{y}_{2N-2}\}]_k + w^k \mathcal{F}^{-1}[\{\hat{y}_1, \hat{y}_3, \dots, \hat{y}_{2N-1}\}]_k \} \\ y_{k+N} = & \frac{1}{2} \{ \mathcal{F}^{-1}[\{\hat{y}_0, \hat{y}_2, \dots, \hat{y}_{2N-2}\}]_k - w^k \mathcal{F}^{-1}[\{\hat{y}_1, \hat{y}_3, \dots, \hat{y}_{2N-1}\}]_k \}. \end{cases}$$

(The factor of  $\frac{1}{2}$  appears because the inversion formula has a “ $1/n$ ” in it.)

What is the computational “cost” of using the formulas above versus ordinary matrix methods, where there are  $4n^2$  real multiplications used in the computation? Set  $n = 2^L$  and let  $K_L$  be the number of real multiplications required to compute  $\mathcal{F}[y]$  by the method above. From the formulas derived above, one sees that to compute  $\mathcal{F}[y]$ , one needs to compute  $\mathcal{F}[y^{\text{even}}]$  and  $\mathcal{F}[y^{\text{odd}}]$ . This takes  $2K_{L-1}$  real multiplications. In addition, one must multiply  $\bar{w}^k$  and  $\mathcal{F}[y^{\text{odd}}]_k$ , for  $k = 0, \dots, 2^{L-1} - 1$ , which requires  $4 \times 2^{L-1}$  real multiplications. The result is that  $K_L$  is related to  $K_{L-1}$  via

$$K_L = 2K_{L-1} + 2^{L+1}$$

When  $L = 0$ ,  $n = 2^0 = 1$  and no multiplications are required; thus,  $K_0 = 0$ . Inserting  $L = 1$  in the last equation, we find that  $K_1 = 1 \times 2^2$ . Similarly, setting  $L = 2$  then yields  $K_2 = 2 \times 2^3$ . Similarly, one finds that  $K_3 = 3 \times 2^4$ ,  $K_4 = 4 \times 2^5$ , and so on. The general formula is  $K_L = L \times 2^{L+1} = 2L \times 2^L$ . Again setting  $n = 2^L$  and noting that  $L = \log_2 n$ , we see that the number of real multiplications required is  $2n \log_2 n$ .

To get an idea of how much faster than matrix multiplication this method is, suppose that we want to take the DFT of data with  $n = 2^{12} = 4,096$  points. The conventional method requires  $2^{26} \approx 7 \times 10^7$  real multiplications. Using the FFT method to get the DFT requires  $2 \times 2^{12} \times 12 \approx 10^5$  real multiplications, making the FFT roughly 700 times as fast.

We remark that similar algorithms can be obtained for  $n = N_1 N_2 \cdots N_m$ , although the fastest one is obtained in the case discussed above. For a discussion of this and related topics, one should consult the references below.

Previous: Pointwise convergence of Fourier series

Next: Splines and finite element spaces

## References

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