

SECTION 3 EXERCISES

1. Find the least squares solution of each of the following systems:

$$\begin{array}{ll} \text{(a)} & \begin{array}{l} x_1 + x_2 = 3 \\ 2x_1 - 3x_2 = 1 \\ 0x_1 + 0x_2 = 2 \end{array} \\ \text{(b)} & \begin{array}{l} -x_1 + x_2 = 10 \\ 2x_1 + x_2 = 5 \\ x_1 - 2x_2 = 20 \end{array} \end{array}$$

$$\text{(c)} \quad \begin{array}{l} x_1 + x_2 + x_3 = 4 \\ -x_1 + x_2 + x_3 = 0 \\ -x_2 + x_3 = 1 \\ x_1 + x_3 = 2 \end{array}$$

2. For each of your solutions $\hat{\mathbf{x}}$ in Exercise 1,

- determine the projection $\mathbf{p} = A\hat{\mathbf{x}}$.
- calculate the residual $r(\hat{\mathbf{x}})$.
- verify that $r(\hat{\mathbf{x}}) \in N(A^T)$.

3. For each of the following systems $A\mathbf{x} = \mathbf{b}$, find all least squares solutions:

$$\text{(a)} \quad A = \begin{bmatrix} 1 & 2 \\ 2 & 4 \\ -1 & -2 \end{bmatrix}, \quad \mathbf{b} = \begin{bmatrix} 3 \\ 2 \\ 1 \end{bmatrix}$$

$$\text{(b)} \quad A = \begin{bmatrix} 1 & 1 & 3 \\ -1 & 3 & 1 \\ 1 & 2 & 4 \end{bmatrix}, \quad \mathbf{b} = \begin{bmatrix} -2 \\ 0 \\ 8 \end{bmatrix}$$

4. For each of the systems in Exercise 3, determine the projection \mathbf{p} of \mathbf{b} onto $R(A)$ and verify that $\mathbf{b} - \mathbf{p}$ is orthogonal to each of the column vectors of A .

5. (a) Find the best least squares fit by a linear function to the data

$$\begin{array}{c|c|c|c|c} x & -1 & 0 & 1 & 2 \\ \hline y & 0 & 1 & 3 & 9 \end{array}$$

(b) Plot your linear function from part (a) along with the data on a coordinate system.

6. Find the best least squares fit to the data in Exercise 5 by a quadratic polynomial. Plot the points $x = -1, 0, 1, 2$ for your function and sketch the graph.

7. Given a collection of points $(x_1, y_1), (x_2, y_2), \dots, (x_n, y_n)$, let

$$\mathbf{x} = (x_1, x_2, \dots, x_n)^T \quad \mathbf{y} = (y_1, y_2, \dots, y_n)^T$$

$$\bar{x} = \frac{1}{n} \sum_{i=1}^n x_i \quad \bar{y} = \frac{1}{n} \sum_{i=1}^n y_i$$

and let $y = c_0 + c_1x$ be the linear function that gives the best least squares fit to the points. Show that if $\bar{x} = 0$, then

$$c_0 = \bar{y} \quad \text{and} \quad c_1 = \frac{\mathbf{x}^T \mathbf{y}}{\mathbf{x}^T \mathbf{x}}$$

8. The point (\bar{x}, \bar{y}) is the *center of mass* for the collection of points in Exercise 7. Show that the least squares line must pass through the center of mass. [Hint: Use a change of variables $z = x - \bar{x}$ to translate the problem so that the new independent variable has mean 0.]

9. Let A be an $m \times n$ matrix of rank n and let $P = A(A^T A)^{-1} A^T$.

- Show that $P\mathbf{b} = \mathbf{b}$ for every $\mathbf{b} \in R(A)$. Explain this property in terms of projections.
- If $\mathbf{b} \in R(A)^\perp$, show that $P\mathbf{b} = \mathbf{0}$.
- Give a geometric illustration of parts (a) and (b) if $R(A)$ is a plane through the origin in \mathbb{R}^3 .

10. Let A be an 8×5 matrix of rank 3, and let \mathbf{b} be a nonzero vector in $N(A^T)$.

- Show that the system $A\mathbf{x} = \mathbf{b}$ must be inconsistent.
- How many least squares solutions will the system $A\mathbf{x} = \mathbf{b}$ have? Explain.

11. Let $P = A(A^T A)^{-1} A^T$, where A is an $m \times n$ matrix of rank n .

- Show that $P^2 = P$.
- Prove that $P^k = P$ for $k = 1, 2, \dots$.
- Show that P is symmetric. [Hint: If B is nonsingular, then $(B^{-1})^T = (B^T)^{-1}$.]

12. Show that if

$$\begin{bmatrix} A & I \\ O & A^T \end{bmatrix} \begin{bmatrix} \hat{\mathbf{x}} \\ \mathbf{r} \end{bmatrix} = \begin{bmatrix} \mathbf{b} \\ \mathbf{0} \end{bmatrix}$$

then $\hat{\mathbf{x}}$ is a least squares solution of the system $A\mathbf{x} = \mathbf{b}$ and \mathbf{r} is the residual vector.

13. Let $A \in \mathbb{R}^{m \times n}$ and let $\hat{\mathbf{x}}$ be a solution of the least squares problem $A\mathbf{x} = \mathbf{b}$. Show that a vector $\mathbf{y} \in \mathbb{R}^n$ will also be a solution if and only if $\mathbf{y} = \hat{\mathbf{x}} + \mathbf{z}$, for some vector $\mathbf{z} \in N(A)$.

[Hint: $N(A^T A) = N(A)$.]

14. Find the equation of the circle that gives the best least squares circle fit to the points $(-1, -2)$, $(0, 2.4)$, $(1.1, -4)$, and $(2.4, -1.6)$.