

Linear precision for parametric patches

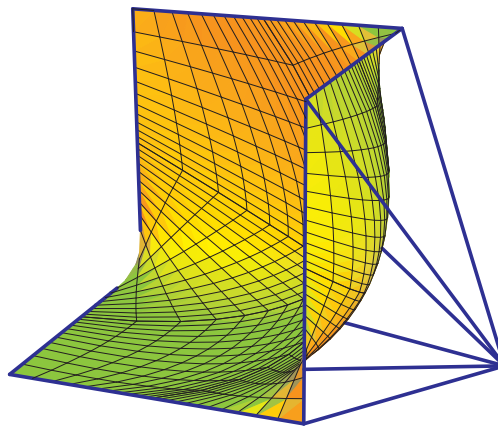
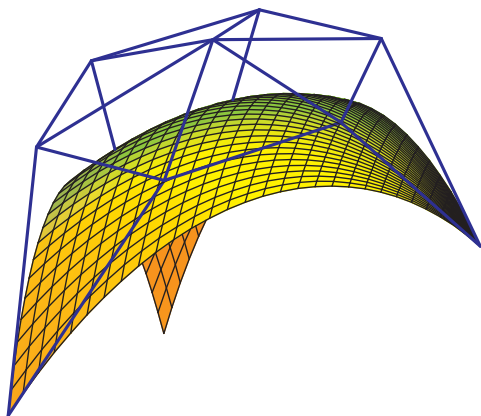
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Overview

(With L. Garcia, K. Ranestad, and H.C. Graf v. Bothmer)

Linear precision, the ability of a patch to replicate affine functions, has interesting properties and connections to other areas of mathematics.

- Any patch has a unique reparametrization (possibly non-rational) with linear precision. This reparametrization is the maximum likelihood estimator from algebraic statistics.
- This reparametrization for toric patches is computed by iterative proportional fitting, an algorithm from statistics.
- Linear precision has an interesting mathematical formulation for toric patches, which leads to a classification, using algebraic geometry, of toric surface patches having linear precision.

(Control-point) patch schemes

Let $\mathcal{A} \subset \mathbb{R}^d$ (e.g. $d = 2$) be a finite set with convex hull Δ , and $\beta := \{\beta_{\mathbf{a}}: \Delta \rightarrow \mathbb{R}_{\geq 0} \mid \mathbf{a} \in \mathcal{A}\}$, *basis functions* with $1 = \sum_{\mathbf{a}} \beta_{\mathbf{a}}(x)$.

Given *control points* $\{\mathbf{b}_{\mathbf{a}} \mid \mathbf{a} \in \mathcal{A}\} \subset \mathbb{R}^{\ell}$ (e.g. $\ell = 3$), get a map

$$\varphi : \Delta \rightarrow \mathbb{R}^{\ell} \quad x \longmapsto \sum \beta_{\mathbf{a}}(x) \mathbf{b}_{\mathbf{a}}$$

Image of φ is a patch with shape Δ . Call (β, \mathcal{A}) is a *patch*.

Affine invariance and the *convex hull property* are built into definition.

Linear precision is the ability to replicate linear functions.

We will adopt a precise, but restrictive definition.

Linear Precision

Let \mathcal{A} be the control points, ($\mathbf{b}_a = \mathbf{a}$), to get the *tautological map*,

$$\tau : x \longmapsto \sum \beta_a(x) \mathbf{a} \quad \tau : \Delta \rightarrow \Delta.$$

(β, \mathcal{A}) has *linear precision* if and only if $\tau = \text{identity map}$.

Theorem (G-S). *If τ is a homeomorphism, the patch $\{\beta_a \mid \mathbf{a} \in \mathcal{A}\}$ has a unique reparametrization with linear precision, $\{\beta_a \circ \tau^{-1} \mid \mathbf{a} \in \mathcal{A}\}$.*

How to compute τ^{-1} ? The map τ factors

$$\begin{array}{ccccc} \varphi : \Delta & \xrightarrow{\beta} & \mathbb{RP}^A & & \xrightarrow{\mu} \Delta \\ x \longmapsto & [1, \beta_a(x) \mid \mathbf{a} \in \mathcal{A}] & [0, \dots, 1, \dots, 0] & \longmapsto & \mathbf{a} \end{array}$$

Note $\beta \circ \tau^{-1} = \mu^{-1} : \Delta \rightarrow X_\beta$, where $X_\beta := \text{image } \beta(\Delta) \subset \mathbb{RP}^A$.

We shall see that μ^{-1} is the key.

Toric patches (After Krasauskas)

A polytope Δ with integer vertices is given by **facet** inequalities

$$\Delta = \{x \in \mathbb{R}^d \mid h_i(x) \geq 0 \ i = 1, \dots, n\},$$

where h_i is linear with integer coefficients.

For each $\mathbf{a} \in \mathcal{A} := \Delta \cap \mathbb{Z}^d$, there is a **toric Bézier function**

$$\beta_{\mathbf{a}}(x) := h_1(x)^{h_1(\mathbf{a})} \cdots h_n(x)^{h_n(\mathbf{a})}.$$

Let $w = \{w_{\mathbf{a}} \mid \mathbf{a} \in \mathcal{A}\} \subset \mathbb{R}_{>}$ be positive weights. The **toric patch** (w, \mathcal{A}) has blending functions $\{w_{\mathbf{a}}\beta_{\mathbf{a}} \mid \mathbf{a} \in \mathcal{A}\}$. Write $X_{w, \mathcal{A}}$ for its image in \mathbb{RP}^A , which is the positive part of a toric variety.

The map $\mu: X_{w, \mathcal{A}} \rightarrow \Delta$ is the **algebraic moment map**.

Example: Bézier triangles

Bézier triangles are toric surface patches.

Set $\mathcal{A} := \{(i, j) \in \mathbb{N}^2 \mid i \geq 0, j \geq 0, n - i - j \geq 0\}$, then

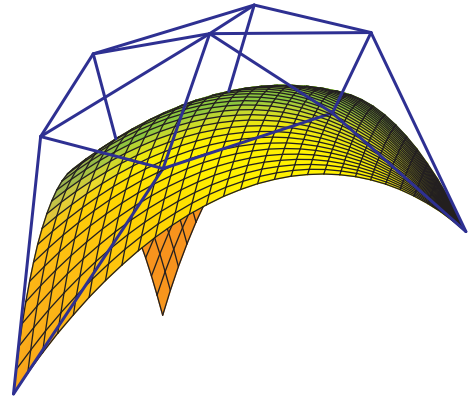
$$w_{(i,j)} \beta_{(i,j)} := \frac{n!}{i!j!(n-i-j)!} x^i y^j (n-x-y)^{n-i-j}.$$

These are essentially the Bernstein polynomials, which have linear precision.

The corresponding toric variety is the Veronese surface of degree n .

Choosing control points, get Bézier triangle of degree n .

This picture is a cubic Bézier triangle.



Digression: algebraic statistics

In algebraic statistics, the probability simplex $= \mathbb{RP}_{>}^n$, the positive part of \mathbb{RP}^n , and its subvarieties $X_{w,\mathcal{A}}$ are called *toric statistical models*.

For example, the subvariety corresponding to the Bézier triangle is the *trinomial distribution*.

The algebraic moment map $\mu: \mathbb{RP}_{>}^n \rightarrow \Delta$ is called the *expectation map*, and, for $p \in \mathbb{RP}_{>}^n$, the point $\mu^{-1}(\mu(p)) \in X_{w,\mathcal{A}}$ is the *maximum likelihood estimator*, the distribution in $X_{w,\mathcal{A}}$ which ‘best’ explains p .

Iterative proportional fitting (IPF) is a fast numerical algorithm to compute μ^{-1} . IPF may be useful in modeling.

Linear precision means maximum likelihood degree 1. Many statistical models have MLD 1.

Linear precision for toric patches

Given the data (w, \mathcal{A}) of a toric patch, define a polynomial

$$F_{w, \mathcal{A}} := \sum_{\mathbf{a} \in \mathcal{A}} w_{\mathbf{a}} x^{\mathbf{a}},$$

where $x^{\mathbf{a}}$ is the multivariate monomial.

Theorem (G-S). *A toric patch (w, \mathcal{A}) has linear precision if and only if*

$$\mathbb{C}^d \ni x \longmapsto \left(x_1 \frac{\partial F_{w, \mathcal{A}}}{\partial x_1}, x_2 \frac{\partial F_{w, \mathcal{A}}}{\partial x_2}, \dots, x_d \frac{\partial F_{w, \mathcal{A}}}{\partial x_d} \right) \quad (*)$$

defines a birational isomorphism $\mathbb{C}^d - \rightarrow \mathbb{C}^d$.

We say that F *defines a toric polar Cremona transformation*, when its toric derivatives $(*)$ define a birational map.

Linear precision for toric surface patches

Theorem (GvB-R-S). *A polynomial $F \in \mathbb{C}[x, y]$ defines a toric polar Cremona transformation if and only if it is equivalent to one of the following forms*

- $(x + y + 1)^n$ (\iff *Bézier triangle*).
- $(x + 1)^m(y + 1)^n$ (\iff *tensor-product patch*).
- $(x + 1)^m((x + 1)^d + y)^n$ (\iff *trapezoidal patch*).
- $(x^2 + y^2 + z^2 - 2(xy + xz + yz))^d$. (*no analog in modeling*).

In particular, this classifies toric surface patches that enjoy linear precision.

Ideas in proof

Using the classification of birational maps $\mathbb{P}^2 \dashrightarrow \mathbb{P}^2$ and that F lies in the linear series of toric polar derivatives, we

- Restrict the singularities of $F = 0$ to at most one node outside the axes, in which case F is contracted.
- Conclude that $F = 0$ is rational and then study/use parametrizations $\mathbb{P}^1 \rightarrow \{F = 0\}$.
- Finish it up with some local calculations.
- Almost none of these techniques are available in higher dimensions.

Bibliography

- Rimvydas Krasauskas, *Toric surface patches*, Adv. Comput. Math. **17** (2002), no. 1-2, 89–133.
- Luis Garcia-Puente and Frank Sottile, *Linear precision for parametric patches*, 2007, ArXiv:0706.2116.
- Hans-Christian Graf van Bothmer, Kristian Ranestad, and Frank Sottile, *Linear precision for toric surface patches*, 2008. ArXiv:0806.3230.

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Future work?

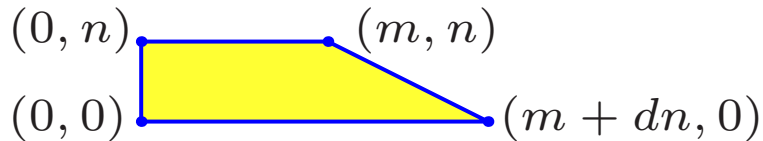
- When is it possible to tune a patch (move the points \mathcal{A}) to achieve linear precision?
- Linear precision for 3- and higher-dimensional patches.
- Algebraic statistics furnishes many higher dimensional toric patches with linear precision.
- Can iterative proportional fitting be useful to compute patches?

Trapezoidal patch

Let $n, d \geq 1$ and $m \geq 0$ be integers, and set

$$\mathcal{A} := \{(i, j) : 0 \leq j \leq n \text{ and } 0 \leq i \leq m + dn - dj\},$$

which are the integer points inside the trapezoid below.



Choose weights $w_{i,j} := \binom{n}{j} \binom{m+dn-dj}{i}$.

Then the toric Bézier functions are

$$\binom{n}{j} \binom{m+dn-dj}{i} s^i (m + dn - s - dt)^{m+dn-dj-i} t^j (n - t)^{n-j}.$$