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Math 304 Final Exam Spring 2017
Section 501 Solutions P. Yasskin

Points indicated. Show all work.

1	/20	3	/15
2	/32	4	/35
		Total	/102

You do not need to prove any basis is linearly independent in any problem.

1. (20 points) Consider the vector space $P_3 = \{\text{polynomials of degree } < 3\}$.

- a. Take the standard basis to be $e_1 = 1 \quad e_2 = x \quad e_3 = x^2$.

Find the components of $p = 2 + 3x + 4x^2$ relative to the e basis.

$$p = 2e_1 + 3e_2 + 4e_3$$

$$p_e = \begin{pmatrix} 2 \\ 3 \\ 4 \end{pmatrix}$$

- b. Another basis is $f_1 = 1 + x \quad f_2 = 1 + x^2 \quad f_3 = 2 + x$.

Find the change of basis matrix from the f basis to the e basis.

$$f_1 = 1 + x = 1e_1 + 1e_2 + 0e_3$$

$$f_2 = 1 + x^2 = 1e_1 + 0e_2 + 1e_3$$

$$f_3 = 2 + x = 2e_1 + 1e_2 + 0e_3$$

$$C_{e \leftarrow f} = \begin{pmatrix} 1 & 1 & 2 \\ 1 & 0 & 1 \\ 0 & 1 & 0 \end{pmatrix}$$

- c. Find the change of basis matrix from the e basis to the f basis.

$$\begin{pmatrix} 1 & 1 & 2 \\ 1 & 0 & 1 \\ 0 & 1 & 0 \end{pmatrix}$$

\Rightarrow

$$\begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} -1 & 2 & 1 \\ 0 & 0 & 1 \\ 1 & -1 & -1 \end{pmatrix}$$

$$C_{f \leftarrow e} = \begin{pmatrix} -1 & 2 & 1 \\ 0 & 0 & 1 \\ 1 & -1 & -1 \end{pmatrix}$$

- d. Find the components of $p = 2 + 3x + 4x^2$ relative to the f basis.

$$p_f = C_{f \leftarrow e} p_e = \begin{pmatrix} -1 & 2 & 1 \\ 0 & 0 & 1 \\ 1 & -1 & -1 \end{pmatrix} \begin{pmatrix} 2 \\ 3 \\ 4 \end{pmatrix} = \begin{pmatrix} -2 + 6 + 4 \\ 0 + 0 + 4 \\ 2 - 3 - 4 \end{pmatrix}$$

$$p_f = \begin{pmatrix} 8 \\ 4 \\ -5 \end{pmatrix}$$

- e. Find the polynomial q whose components relative to the f basis are $q_f = \begin{pmatrix} 3 \\ 2 \\ 1 \end{pmatrix}$

$$q_f = \begin{pmatrix} 3 \\ 2 \\ 1 \end{pmatrix}$$

Simplify fully.

$$q = 3f_1 + 2f_2 + 1f_3 = 3(1 + x) + 2(1 + x^2) + 1(2 + x)$$

$$q = 7 + 4x + 2x^2$$

2. (32 points) Let $P_2 = \{ \text{polynomials of degree } < 2 \}$ and $P_3 = \{ \text{polynomials of degree } < 3 \}$.

Consider the linear map $L : P_2 \rightarrow P_3$ given by $L(p) = 2 \int_1^x p dx$.

For example: $L(3 + 4x) = 2 \int_1^x (3 + 4x) dx = 2[3x + 2x^2]_1^x = 2(3x + 2x^2 - 5) = -10 + 6x + 4x^2$.

a. Find the image of L . What is its dimension?

HINT: Take the general element of P_2 to be $p = a + bx$.

$$L(p) = 2 \int_1^x (a + bx) dx = 2 \left[ax + b \frac{x^2}{2} \right]_1^x = 2ax + bx^2 - 2a - b$$

$$\begin{aligned} \text{Im}(L) &= \{L(p)\} = \{2ax + bx^2 - 2a - b\} \\ &= \{a(2x - 2) + b(x^2 - 1)\} = \text{Span}(2x - 2, x^2 - 1) \end{aligned}$$

$\text{Im}(L) = \text{Span}(2x - 2, x^2 - 1)$

$\dim \text{Im}(L) = 2$

b. Find the kernel of L . What is its dimension?

$$\begin{aligned} \text{Ker}(L) &= \{p : L(p) = 2ax + bx^2 - 2a - b = 0\} \\ \Rightarrow 2a &= 0 \quad b = 0 \quad -2a - b = 0 \\ \Rightarrow a &= b = 0 \quad \Rightarrow p = 0 \end{aligned}$$

$\text{Ker}(L) = \{0\}$

$\dim \text{Ker}(L) = 0$

c. Is L onto? Why?

Because $\text{Im}(L) = \text{Span}(2x - 2, x^2 - 1) \neq \text{Co-Dom}(L) = P_3$

Equivalently, because $\dim \text{Im}(L) = 2 \neq \dim \text{Co-Dom}(L) = 3$

Circle one:

Yes	No
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d. Is L one-to-one? Why?

Because $\text{Ker}(L) = \{0\}$

Circle one:

Yes	No
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e. Find the matrix of L relative to the standard bases.

$$\begin{array}{lll} e_1 = 1 & e_2 = x & \text{for } P_2 \\ E_1 = 1 & E_2 = x & E_3 = x^2 \quad \text{for } P_3 \end{array}$$

$$L(e_1) = L(1) = 2 \int_1^x (1) dx = \left[2x \right]_1^x = 2x - 2 = -2E_1 + 2E_2$$

$$L(e_2) = L(x) = 2 \int_1^x (x) dx = \left[x^2 \right]_1^x = x^2 - 1 = -1E_1 + E_3$$

$$A = \begin{pmatrix} -2 & -1 \\ 2 & 0 \\ 0 & 1 \end{pmatrix}_{E \leftarrow e}$$

f. Find the null space of A . What is its dimension?

Solve $A\vec{x} = \vec{0}$:

$$\left(\begin{array}{cc|c} -2 & -1 & 0 \\ -2 & 0 & 0 \\ 0 & 1 & 0 \end{array} \right) \Rightarrow \left(\begin{array}{cc|c} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{array} \right) \Rightarrow \vec{x} = \vec{0}$$

Equivalently, $\text{Ker}(L) = \{0\} \Rightarrow \text{Null}(A) = \{\vec{0}\}$

$\text{Null}(A) = \{\vec{0}\}$

$\dim \text{Null}(A) = 0$

g. Find the column space of A . What is its dimension?

It is spanned by the columns of A .

$$Col(A) = Span\left(\left(\begin{array}{c} -2 \\ 2 \\ 0 \end{array}\right), \left(\begin{array}{c} -1 \\ 0 \\ 1 \end{array}\right)\right)$$

$$\dim Col(A) = 2$$

h. Find the row space of A . What is its dimension?

It is spanned by the rows of A .

$$Row(A) = Span((-2, -1), (2, 0), (0, 1))$$

$$\text{but } (-2, -1) = -(2, 0) - (0, 1)$$

$$Row(A) = Span((2, 0), (0, 1))$$

$$\dim Row(A) = 2$$

3. (15 points) Consider the polynomial vector space $V = Span(x, x^2)$ with the inner product

$$\langle f, g \rangle = \int_0^1 \frac{fg}{x} dx$$

a. Find the angle between $v_1 = x$ and $v_2 = x^2$.

$$\langle v_1, v_2 \rangle = \int_0^1 \frac{xx^2}{x} d\theta = \int_0^1 x^2 dx = \left[\frac{x^3}{3} \right]_0^1 = \frac{1}{3}$$

$$\langle v_1, v_1 \rangle = \int_0^1 \frac{(x)^2}{x} dx = \int_0^1 x dx = \left[\frac{x^2}{2} \right]_0^1 = \frac{1}{2} \quad |v_1| = \frac{1}{\sqrt{2}}$$

$$\langle v_2, v_2 \rangle = \int_0^1 \frac{(x^2)^2}{x} dx = \int_0^1 x^3 dx = \left[\frac{x^4}{4} \right]_0^1 = \frac{1}{4} \quad |v_2| = \frac{1}{2}$$

$$\cos \theta = \frac{\langle v_1, v_2 \rangle}{|v_1| |v_2|} = \frac{\frac{1}{3}}{\frac{1}{\sqrt{2}} \frac{1}{2}} = \frac{2\sqrt{2}}{3}$$

$$\theta = \arccos \frac{2\sqrt{2}}{3}$$

b. Start with the basis $v_1 = x$ and $v_2 = x^2$ and use the Gram-Schmidt procedure to produce an orthogonal basis w_1 and w_2 and an orthonormal basis u_1 and u_2 .

$$w_1 = v_1$$

$$w_1 = x$$

$$\langle w_1, w_1 \rangle = \langle v_1, v_1 \rangle = \frac{1}{2} \quad |w_1| = \frac{1}{\sqrt{2}}$$

$$u_1 = \frac{w_1}{|w_1|}$$

$$u_1 = \sqrt{2}x$$

$$\langle v_2, w_1 \rangle = \langle v_2, v_1 \rangle = \frac{1}{3}$$

$$w_2 = v_2 - \frac{\langle v_2, w_1 \rangle}{\langle w_1, w_1 \rangle} w_1 = x^2 - \frac{\frac{1}{3}}{\frac{1}{2}} x$$

$$w_2 = x^2 - \frac{2}{3}x$$

$$\begin{aligned} \langle w_2, w_2 \rangle &= \int_0^1 \frac{\left(x^2 - \frac{2}{3}x\right)^2}{x} dx = \int_0^1 \frac{x^4 - \frac{4}{3}x^3 + \frac{4}{9}x^2}{x} dx = \int_0^1 \left(x^3 - \frac{4}{3}x^2 + \frac{4}{9}x\right) dx \\ &= \left[\frac{x^4}{4} - \frac{4}{3} \frac{x^3}{3} + \frac{4}{9} \frac{x^2}{2} \right]_0^1 = \frac{1}{4} - \frac{4}{9} + \frac{2}{9} = \frac{9-8}{36} = \frac{1}{36} \quad |w_2| = \frac{1}{6} \end{aligned}$$

$$u_2 = \frac{w_2}{|w_2|} = 6\left(x^2 - \frac{2}{3}x\right)$$

$$u_2 = 6x^2 - 4x$$

4. (35 points) Consider the matrix $A = \begin{pmatrix} 4 & 2 \\ -1 & 1 \end{pmatrix}$.

a. Find the eigenvalues of A . List them in ascending order.

$$|A - \lambda \mathbf{1}| = \begin{vmatrix} 4 - \lambda & 2 \\ -1 & 1 - \lambda \end{vmatrix} = (4 - \lambda)(1 - \lambda) + 2 = \lambda^2 - 5\lambda + 6 \\ = (\lambda - 2)(\lambda - 3) = 0$$

$$\lambda_1 = 2 \quad \lambda_2 = 3$$

b. Find the eigenvectors of A .

$$\boxed{\lambda_1 = 2:} \quad \left(\begin{array}{cc|c} 2 & 2 & 0 \\ -1 & -1 & 0 \end{array} \right) \Rightarrow \left(\begin{array}{cc|c} 1 & 1 & 0 \\ 0 & 0 & 0 \end{array} \right) \Rightarrow a + b = 0$$

$$\Rightarrow \vec{x} = \begin{pmatrix} a \\ b \end{pmatrix} = \begin{pmatrix} -r \\ r \end{pmatrix} = r \begin{pmatrix} -1 \\ 1 \end{pmatrix}$$

$$\boxed{e_1 = \begin{pmatrix} -1 \\ 1 \end{pmatrix}}$$

$$\boxed{\lambda_2 = 3:} \quad \left(\begin{array}{cc|c} 1 & 2 & 0 \\ -1 & -2 & 0 \end{array} \right) \Rightarrow \left(\begin{array}{cc|c} 1 & 2 & 0 \\ 0 & 0 & 0 \end{array} \right) \Rightarrow a + 2b = 0$$

$$\Rightarrow \vec{x} = \begin{pmatrix} a \\ b \end{pmatrix} = \begin{pmatrix} -2r \\ r \end{pmatrix} = r \begin{pmatrix} -2 \\ 1 \end{pmatrix}$$

$$\boxed{e_2 = \begin{pmatrix} -2 \\ 1 \end{pmatrix}}$$

c. Find a diagonal matrix D and an invertible matrix X so that $A = XDX^{-1}$.

A is a matrix relative to standard basis \hat{i} .

D is a matrix relative to the eigenbasis e whose diagonal entries are the eigenvalues.

$$\underset{\hat{i} \leftarrow \hat{i}}{A} = \underset{\hat{i} \leftarrow e}{C} \underset{e \leftarrow e}{D} \underset{e \leftarrow \hat{i}}{C} = XDX^{-1} \quad \text{So} \quad X = \underset{\hat{i} \leftarrow e}{C} \quad \text{which}$$

$$\boxed{D = \begin{pmatrix} 2 & 0 \\ 0 & 3 \end{pmatrix}}$$

is the matrix whose columns are the eigenvectors.

$$\boxed{X = \begin{pmatrix} -1 & -2 \\ 1 & 1 \end{pmatrix}}$$

d. Find X^{-1} .

$$\left(\begin{array}{cc} a & c \\ b & d \end{array} \right)^{-1} = \frac{1}{ad - bc} \left(\begin{array}{cc} d & -c \\ -b & a \end{array} \right) \quad X^{-1} = \frac{1}{-1+2} \left(\begin{array}{cc} 1 & 2 \\ -1 & -1 \end{array} \right)$$

$$\boxed{X^{-1} = \begin{pmatrix} 1 & 2 \\ -1 & -1 \end{pmatrix}}$$

e. Compute $\cos(\pi A)$.

HINT: If $D = \begin{pmatrix} \alpha & 0 \\ 0 & \beta \end{pmatrix}$, then $\pi D = \begin{pmatrix} \alpha\pi & 0 \\ 0 & \beta\pi \end{pmatrix}$. What is $\cos(\pi D)$?

$$\cos(\pi D) = \begin{pmatrix} \cos(2\pi) & 0 \\ 0 & \cos(3\pi) \end{pmatrix} = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}$$

$$\cos(\pi A) = \cos(X\pi DX^{-1}) = X \cos(\pi D) X^{-1} = \begin{pmatrix} -1 & -2 \\ 1 & 1 \end{pmatrix} \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} \begin{pmatrix} 1 & 2 \\ -1 & -1 \end{pmatrix}$$

$$= \begin{pmatrix} -1 & 2 \\ 1 & -1 \end{pmatrix} \begin{pmatrix} 1 & 2 \\ -1 & -1 \end{pmatrix} = \begin{pmatrix} -1-2 & -2-2 \\ 1+1 & 2+1 \end{pmatrix}$$

$$\boxed{\cos(\pi A) = \begin{pmatrix} -3 & -4 \\ 2 & 3 \end{pmatrix}}$$