

Name \_\_\_\_\_

Math 311      Exam 2 Version A      Spring 2015

Section 503      P. Yasskin

Points indicated. Show all work.

1	/15	4	/27
2	/38	5 E.C.	/10
3	/25	Total	/115

1. (15 points) Let  $P_5$  be the vector space of polynomials of degree less than 5.

Consider the subspace  $V = \text{Span}(v_1, v_2, v_3, v_4)$  where

$$v_1 = 2 + 3x^2, \quad v_2 = x - 3x^3, \quad v_3 = 2 - x + 3x^4, \quad v_4 = x^2 + x^3 - x^4$$

Find a basis for  $V$ . What is  $\dim V$ ?

2. (38 points) Consider the vector space  $V = \text{Span}(\sin^2(x), \cos^2(x), \sin(x)\cos(x))$  with the usual addition and scalar multiplication of functions. Two bases are:

$$e_1 = \sin^2(x) \quad e_2 = \cos^2(x) \quad e_3 = \sin(x)\cos(x) \quad \text{and} \quad E_1 = 1 \quad E_2 = \sin(2x) \quad E_3 = \cos(2x)$$

Note: You do NOT need to prove they are bases.

Hints: Here are some useful identities:

$$\sin(2x) = 2\sin(x)\cos(x), \quad \cos(2x) = \cos^2(x) - \sin^2(x), \quad \sin^2(x) = \frac{1 - \cos(2x)}{2}, \quad \cos^2(x) = \frac{1 + \cos(2x)}{2}$$

a. (5) Find the change of basis matrix  $C_{E \leftarrow e}$  from the  $e$  basis to the  $E$  basis by using the identities.

b. (5) Find the change of basis matrix  $C_{e \leftarrow E}$  from the  $E$  basis to the  $e$  basis by using the identities.

c. (2) Verify  $C_{E \leftarrow e}$  and  $C_{e \leftarrow E}$  are inverses.

d. (4) For the function  $f = \cos(2x) + 4\cos^2(x)$ , what are its components  $(f)_e$  and  $(f)_E$ ?

e. (5) Find the matrix  $A_{e \leftarrow e}$  of the derivative operator  $D = \frac{d}{dx}$  relative to the  $e$  basis.

f. (5) Find the matrix  $B_{E \leftarrow E}$  of the derivative operator  $D = \frac{d}{dx}$  relative to the  $E$  basis.  
Do NOT use the change of basis matrices.

g. (2)  $A$  and  $B$  are related by a similarity transformation:  $B = SAS^{-1}$ . What is  $S$ ?

h. (3) What is  $\text{Im}(D)$ ? Give a basis. What is  $\dim(\text{Im}(D))$ ?  
HINT: Let  $f = a \cdot 1 + b \cdot \sin(2x) + c \cdot \cos(2x)$ .

i. (3) What is  $\text{Ker}(D)$ ? Give a basis. What is  $\dim(\text{Ker}(D))$ ?

j. (2) Is  $D$  onto? Why or why not?

k. (2) Is  $D$  1-1? Why or why not?

3. (25 points) Consider the vector space  $S$  of symmetric  $2 \times 2$  matrices. The following are symmetric, bilinear forms on  $S$ . Which one(s) are inner products? Why or why not? You do not need to check they are symmetric or bilinear, just that they are positive definite.

HINTS: Let  $A = \begin{pmatrix} a & b \\ b & d \end{pmatrix}$ . Compute  $\langle A, A \rangle$ . Look for perfect squares or complete the squares.

a. (9)  $\langle A, B \rangle = \text{tr}(AGB^T)$  where  $G = \begin{pmatrix} 1 & 1 \\ 1 & 1 \end{pmatrix}$

b. (8)  $\langle A, B \rangle = \text{tr}(AGB^T)$  where  $G = \begin{pmatrix} 4 & 1 \\ 1 & 1 \end{pmatrix}$

c. (8)  $\langle A, B \rangle = \text{tr}(AGB^T)$  where  $G = \begin{pmatrix} 1 & 3 \\ 3 & 1 \end{pmatrix}$

4. (27 points) Consider the vector space  $S$  of symmetric  $2 \times 2$  matrices with the inner product

$$\langle A, B \rangle = \text{tr}(AGB^T) \quad \text{where } G = \begin{pmatrix} 1 & 0 \\ 0 & 4 \end{pmatrix}.$$

a. (8) Find the angle between the matrices  $A = \begin{pmatrix} 4 & 3 \\ 3 & 4 \end{pmatrix}$  and  $B = \begin{pmatrix} 3 & 4 \\ 4 & 3 \end{pmatrix}$ .

b. (19) A basis for  $S$  is  $V_1 = \begin{pmatrix} 3 & 0 \\ 0 & 2 \end{pmatrix}$   $V_2 = \begin{pmatrix} 3 & 2 \\ 2 & 2 \end{pmatrix}$   $V_3 = \begin{pmatrix} 5 & 0 \\ 0 & -5 \end{pmatrix}$ .

Apply the Gram-Schmidt Procedure to the  $(V_1, V_2, V_3)$  basis to produce an orthogonal basis  $(W_1, W_2, W_3)$  and an orthonormal basis  $(U_1, U_2, U_3)$ .





5. (10 points EC) Consider the vector space  $V = (\mathbb{R}^+)^2 = \{(x_1, x_2) \mid x_1 > 0 \text{ and } x_2 > 0\}$  consisting of ordered pairs of positive numbers with addition and multiplication defined by

$$(x_1, x_2) \oplus (y_1, y_2) = (x_1 y_1, x_2 y_2) \text{ and } a \odot (x_1, x_2) = (x_1^a, x_2^a)$$

So vector addition is real number multiplication of corresponding components and scalar multiplication is real number exponentiation of each component. Note the zero vector is  $\vec{0} = (1, 1)$ .

- a. (5) Is  $u_1 = (1, 3)$  and  $u_2 = (2, 1)$  a basis? Why or why not?

- b. (5) Is  $v_1 = (1, 1)$  and  $v_2 = (2, 1)$  a basis? Why or why not?