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MATH 311 Exam 2 Fall 2001
 Section 200 Solutions P. Yasskin

1	/10	4	/10
2	/10	5	/60
3	/10		

1. (10 points) Let P_1 be the vector space of polynomials of degree ≤ 1 . Suppose $L : P_1 \rightarrow \mathbf{R}$ is a linear map which satisfies

$$L(2 + 3t) = 1, \quad L(1 + 4t) = -2.$$

Compute $L(5 - 2t)$.

$$5 - 2t = a(2 + 3t) + b(1 + 4t) = (2a + b) + (3a + 4b)t$$

$$\begin{aligned} 2a + b &= 5 \\ 3a + 4b &= -2 \end{aligned} \quad \begin{pmatrix} 2 & 1 \\ 3 & 4 \end{pmatrix} \begin{pmatrix} a \\ b \end{pmatrix} = \begin{pmatrix} 5 \\ -2 \end{pmatrix}$$

$$\begin{pmatrix} a \\ b \end{pmatrix} = \begin{pmatrix} 2 & 1 \\ 3 & 4 \end{pmatrix}^{-1} \begin{pmatrix} 5 \\ -2 \end{pmatrix} = \frac{1}{8-3} \begin{pmatrix} 4 & -1 \\ -3 & 2 \end{pmatrix} \begin{pmatrix} 5 \\ -2 \end{pmatrix} = \frac{1}{5} \begin{pmatrix} 22 \\ -19 \end{pmatrix}$$

$$5 - 2t = \frac{22}{5}(2 + 3t) - \frac{19}{5}(1 + 4t)$$

$$L(5 - 2t) = \frac{22}{5}L(2 + 3t) - \frac{19}{5}L(1 + 4t) = \frac{22}{5} \cdot 1 - \frac{19}{5}(-2) = \frac{22 + 38}{5} = 12$$

2. (10 points) Which of the following is not a subspace of $C^1[-1, 1]$? Why?

$$P = \{f \in C^1[-1, 1] \mid f(-1) = f(1)\} \quad Q = \left\{f \in C^1[-1, 1] \mid \frac{f(-1) + f(1)}{2} = f(0)\right\}$$

$$R = \left\{f \in C^1[-1, 1] \mid \int_0^1 f(t) dt = 1\right\} \quad S = \{f \in C^1[-1, 1] \mid f'(0) = f(0)\}$$

R is not a subspace because if $f, g \in R$, then $\int_0^1 f(t) dt = 1$ and $\int_0^1 g(t) dt = 1$

but $\int_0^1 (f+g)(t) dt = 2$. So $f+g \notin R$.

3. (10 points) Duke Skywalker is flying the Millennium Eagle through the Asteroid Belt. At the current time, his position is $\vec{r} = (4, -1, 2)$ and his velocity is $\vec{v} = (3, 2, -1)$. He measures that the electric field and its Jacobian are currently

$$\vec{E} = \begin{pmatrix} 12 \\ 2 \\ 9 \end{pmatrix} \quad \text{and} \quad J\vec{E} = \begin{pmatrix} 2 & 0 & 1 \\ 0 & 4 & 3 \\ 1 & 2 & 9 \end{pmatrix}.$$

Use a linear (affine) approximation to estimate what the electric field will be 2 sec from now.

$$\begin{aligned} \vec{E}(\vec{r}(t)) &\approx \vec{E}(\vec{r}(t_0)) + J\vec{E} \cdot (\vec{r}(t) - \vec{r}(t_0)) \approx \vec{E}(\vec{r}(t_0)) + J\vec{E} \cdot \vec{v}(t_0)(t - t_0) \\ &\approx \begin{pmatrix} 12 \\ 2 \\ 9 \end{pmatrix} + \begin{pmatrix} 2 & 0 & 1 \\ 0 & 4 & 3 \\ 1 & 2 & 9 \end{pmatrix} \cdot \begin{pmatrix} 3 \\ 2 \\ -1 \end{pmatrix} (2) = \begin{pmatrix} 12 \\ 2 \\ 9 \end{pmatrix} + 2 \begin{pmatrix} 5 \\ 5 \\ -2 \end{pmatrix} = \begin{pmatrix} 22 \\ 12 \\ 5 \end{pmatrix} \end{aligned}$$

4. (10 points) Let $L : R^5 \rightarrow R^4$ be a linear map whose matrix is A . If A is row reduced, one obtains the matrix

$$\begin{pmatrix} 1 & 3 & 0 & 0 & 2 \\ 0 & 0 & 1 & 0 & -1 \\ 0 & 0 & 0 & 1 & 2 \\ 0 & 0 & 0 & 0 & 0 \end{pmatrix}$$

What is the dimension of the kernel of L ? What is the dimension of the image of L ?

Be sure to explain why.

$Ker(L) = \{X \mid AX = 0\}$ This has 2 free parameters since there are 2 columns without leading 1's.
So $\dim Ker(L) = 2$.

$\dim Im(L) = \#$ linearly independent columns = column rank = row rank
= $\#$ linearly independent rows = $\#$ leading 1's = 3.

It is OK to do one of these and then use the Nullity-Rank Theorem:

$$\dim Ker(L) + \dim Im(L) = \dim Dom(L) = 5.$$

5. (60 points) Let $M(2,2)$ be the vector space of 2×2 matrices. Let P_2 be the vector space of polynomials of degree ≤ 2 . Consider the linear map $L : M(2,2) \rightarrow P_2$ given by

$$L(M) = (1 \ x)M \begin{pmatrix} 1 \\ x \end{pmatrix}$$

Hint: For some parts it may be useful to write $M = \begin{pmatrix} a & b \\ c & d \end{pmatrix}$ and/or $p(x) = a + \beta x + \gamma x^2$.

- a. (3) Identify the domain of L , a basis for the domain, and the dimension of the domain.

$$\text{Dom}(L) = M(2,2) \quad \text{Basis}_{\text{Dom}}(L) = \left\{ \begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix}, \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix}, \begin{pmatrix} 0 & 0 \\ 1 & 0 \end{pmatrix}, \begin{pmatrix} 0 & 0 \\ 0 & 1 \end{pmatrix} \right\}$$

$$\dim \text{Dom}(L) = 4$$

- b. (3) Identify the codomain of L , a basis for the codomain, and the dimension of the codomain.

$$\text{Codom}(L) = P_2 \quad \text{Basis}_{\text{Codom}}(L) = \{1, x, x^2\} \quad \dim \text{Codom}(L) = 3$$

- c. (6) Identify the kernel of L , a basis for the kernel, and the dimension of the kernel.

$$L \left(\begin{pmatrix} a & b \\ c & d \end{pmatrix} \right) = (1 \ x) \begin{pmatrix} a & b \\ c & d \end{pmatrix} \begin{pmatrix} 1 \\ x \end{pmatrix} = (1 \ x) \begin{pmatrix} a + bx \\ c + dx \end{pmatrix} = a + (b+c)x + dx^2$$

$$\text{Ker}(L) = \{M \mid L(M) = 0\} = \left\{ \begin{pmatrix} a & b \\ c & d \end{pmatrix} \mid a + (b+c)x + dx^2 = 0 \right\} = \left\{ \begin{pmatrix} 0 & b \\ -b & 0 \end{pmatrix} \right\}$$

$$= \text{Span} \left\{ \begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix} \right\} \quad \text{Basis}_{\text{Ker}}(L) = \left\{ \begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix} \right\} \quad \dim \text{Ker}(L) = 1$$

- d. (6) Identify the image of L , a basis for the image, and the dimension of the image.

$$\text{Im}(L) = \{L(M)\} = \{a + (b+c)x + dx^2\} = \text{Span}\{1, x, x^2\} = P_2$$

$$\text{Basis}_{\text{Im}}(L) = \{1, x, x^2\} \quad \dim \text{Im}(L) = 3$$

- e. (2) Is the function L one-to-one? Why?

L is not one-to-one because $\text{Ker}(L) \neq \{0\}$.

- f. (2) Is the function L onto? Why?

L is onto because $\text{Im}(L) = P_2 = \text{Codom}(L)$.

- g. (2) Verify the dimensions in a, b, c and d agree with the Nullity-Rank Theorem.

$$\dim \text{Ker}(L) + \dim \text{Im}(L) = \dim \text{Dom}(L) \quad 1 + 3 = 4$$

h. (6) Find the matrix of L relative to the standard bases: (Call it A .)

$$e_1 = \begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix}, \quad e_2 = \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix}, \quad e_3 = \begin{pmatrix} 0 & 0 \\ 1 & 0 \end{pmatrix}, \quad e_4 = \begin{pmatrix} 0 & 0 \\ 0 & 1 \end{pmatrix} \quad \text{for } M(2,2)$$

and $E_1 = 1, \quad E_2 = x, \quad E_3 = x^2$ for P_2

$$L\left(\begin{pmatrix} a & b \\ c & d \end{pmatrix}\right) = (1 \ x) \begin{pmatrix} a & b \\ c & d \end{pmatrix} \begin{pmatrix} 1 \\ x \end{pmatrix} = (1 \ x) \begin{pmatrix} a+bx \\ c+dx \end{pmatrix} = a + (b+c)x + dx^2$$

$$\begin{aligned} L(e_1) &= 1 = E_1 \\ L(e_2) &= x = E_2 \\ L(e_3) &= x = E_2 \\ L(e_4) &= x^2 = E_3 \end{aligned} \quad A = \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix}$$

i. (6) Another basis for P_2 is $F_1 = 1 + x, \quad F_2 = 1 + x^2, \quad F_3 = x + x^2$. Find the change of basis matrices between the E and F bases. (Call them C and C .) Be sure to identify which is which!

$$\begin{aligned} F_1 &= 1 + x = E_1 + E_2 \\ F_2 &= 1 + x^2 = E_1 + E_3 \\ F_3 &= x + x^2 = E_2 + E_3 \end{aligned} \quad C = \begin{pmatrix} 1 & 1 & 0 \\ 1 & 0 & 1 \\ 0 & 1 & 1 \end{pmatrix}$$

$$\begin{pmatrix} 1 & 1 & 0 & | & 1 & 0 & 0 \\ 1 & 0 & 1 & | & 0 & 1 & 0 \\ 0 & 1 & 1 & | & 0 & 0 & 1 \end{pmatrix} \xrightarrow{\substack{R_2 \\ R_3 \\ R_1}} \begin{pmatrix} 1 & 0 & 1 & | & 0 & 1 & 0 \\ 0 & 1 & 1 & | & 0 & 0 & 1 \\ 1 & 1 & 0 & | & 1 & 0 & 0 \end{pmatrix} \xrightarrow{R_3 - R_1 - R_2} \begin{pmatrix} 1 & 0 & 1 & | & 0 & 1 & 0 \\ 0 & 1 & 1 & | & 0 & 0 & 1 \\ 0 & 0 & -2 & | & 1 & -1 & -1 \end{pmatrix}$$

$$\xrightarrow{\frac{-1}{2}R_3} \begin{pmatrix} 1 & 0 & 1 & | & 0 & 1 & 0 \\ 0 & 1 & 1 & | & 0 & 0 & 1 \\ 0 & 0 & 1 & | & \frac{-1}{2} & \frac{1}{2} & \frac{1}{2} \end{pmatrix} \xrightarrow{\substack{R_1 - R_3 \\ R_2 - R_3}} \begin{pmatrix} 1 & 0 & 0 & | & \frac{1}{2} & \frac{1}{2} & \frac{-1}{2} \\ 0 & 1 & 0 & | & \frac{1}{2} & \frac{-1}{2} & \frac{1}{2} \\ 0 & 0 & 1 & | & \frac{-1}{2} & \frac{1}{2} & \frac{1}{2} \end{pmatrix}$$

$$C = \begin{pmatrix} \frac{1}{2} & \frac{1}{2} & \frac{-1}{2} \\ \frac{1}{2} & \frac{-1}{2} & \frac{1}{2} \\ \frac{-1}{2} & \frac{1}{2} & \frac{1}{2} \end{pmatrix}$$

j. (6) Consider the polynomial $q = 2 + 4x$. Find $[q]_E$ and $[q]_F$, the components of q relative to the E and F bases, respectively. Check $[q]_F$.

$$q = 2E_1 + 4E_2 \quad [q]_E = \begin{pmatrix} 2 \\ 4 \\ 0 \end{pmatrix} \quad [q]_F = C \begin{pmatrix} 2 \\ 4 \\ 0 \end{pmatrix} = \begin{pmatrix} \frac{1}{2} & \frac{1}{2} & \frac{-1}{2} \\ \frac{1}{2} & \frac{-1}{2} & \frac{1}{2} \\ \frac{-1}{2} & \frac{1}{2} & \frac{1}{2} \end{pmatrix} \begin{pmatrix} 2 \\ 4 \\ 0 \end{pmatrix} = \begin{pmatrix} 3 \\ -1 \\ 1 \end{pmatrix}$$

$$3F_1 - 1F_2 + 1F_3 = 3(1+x) - 1(1+x^2) + 1(x+x^2) = 2 + 4x = q$$

- k. (5) Find the matrix of L relative to the e basis for $M(2,2)$ and the F basis for P_2 . (Call it B .)

$$B_{F \leftarrow e} = C_{F \leftarrow E} A_{E \leftarrow e} = \begin{pmatrix} \frac{1}{2} & \frac{1}{2} & \frac{-1}{2} \\ \frac{1}{2} & \frac{-1}{2} & \frac{1}{2} \\ \frac{-1}{2} & \frac{1}{2} & \frac{1}{2} \end{pmatrix} \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix} = \begin{pmatrix} \frac{1}{2} & \frac{1}{2} & \frac{1}{2} & \frac{-1}{2} \\ \frac{1}{2} & \frac{-1}{2} & \frac{-1}{2} & \frac{1}{2} \\ \frac{-1}{2} & \frac{1}{2} & \frac{1}{2} & \frac{1}{2} \end{pmatrix}$$

- l. (5) Find B by a second method.

$$\begin{aligned} L(e_1) = 1 &= aF_1 + bF_2 + cF_3 = a(1+x) + b(1+x^2) + c(x+x^2) = \frac{1}{2}(1+x) + \frac{1}{2}(1+x^2) - \frac{1}{2}(x+x^2) \\ L(e_2) = x &= dF_1 + eF_2 + fF_3 = d(1+x) + e(1+x^2) + f(x+x^2) = \frac{1}{2}(1+x) - \frac{1}{2}(1+x^2) + \frac{1}{2}(x+x^2) \\ L(e_3) = x &= dF_1 + eF_2 + fF_3 = d(1+x) + e(1+x^2) + f(x+x^2) = \frac{1}{2}(1+x) - \frac{1}{2}(1+x^2) + \frac{1}{2}(x+x^2) \\ L(e_4) = x^2 &= gF_1 + hF_2 + iF_3 = g(1+x) + h(1+x^2) + i(x+x^2) = -\frac{1}{2}(1+x) + \frac{1}{2}(1+x^2) + \frac{1}{2}(x+x^2) \end{aligned}$$

$$B_{F \leftarrow e} = \begin{pmatrix} \frac{1}{2} & \frac{1}{2} & \frac{1}{2} & \frac{-1}{2} \\ \frac{1}{2} & \frac{-1}{2} & \frac{-1}{2} & \frac{1}{2} \\ \frac{-1}{2} & \frac{1}{2} & \frac{1}{2} & \frac{1}{2} \end{pmatrix}$$

- m. (6) Consider the matrix $N = \begin{pmatrix} 1 & 2 \\ 3 & 4 \end{pmatrix}$. Find $[N]_e$, the components of N relative to the e -basis and $[L(N)]_F$, the components of $L(N)$ relative to the F basis. Use $[L(N)]_F$ to find $L(N)$?

$$N = \begin{pmatrix} 1 & 2 \\ 3 & 4 \end{pmatrix} = 1e_1 + 2e_2 + 3e_3 + 4e_4 \quad [N]_e = \begin{pmatrix} 1 \\ 2 \\ 3 \\ 4 \end{pmatrix}$$

$$[L(N)]_F = B_{F \leftarrow e} [N]_e = \begin{pmatrix} \frac{1}{2} & \frac{1}{2} & \frac{1}{2} & \frac{-1}{2} \\ \frac{1}{2} & \frac{-1}{2} & \frac{-1}{2} & \frac{1}{2} \\ \frac{-1}{2} & \frac{1}{2} & \frac{1}{2} & \frac{1}{2} \end{pmatrix} \begin{pmatrix} 1 \\ 2 \\ 3 \\ 4 \end{pmatrix} = \begin{pmatrix} 1 \\ 0 \\ 4 \end{pmatrix}$$

$$L(N) = 1F_1 + 4F_3 = 1(1+x) + 4(x+x^2) = 1 + 5x + 4x^2$$

- n. (2) Recompute $L(N)$ using the definition of L .

$$L(N) = (1 \ x) \begin{pmatrix} 1 & 2 \\ 3 & 4 \end{pmatrix} \begin{pmatrix} 1 \\ x \end{pmatrix} = 1 + 5x + 4x^2$$