

MATH 304

Linear Algebra

Lecture 31:

Eigenvalues and eigenvectors (continued).

Characteristic equation.

Eigenvalues and eigenvectors

Definition. Let A be an $n \times n$ matrix. A number $\lambda \in \mathbb{R}$ is called an **eigenvalue** of the matrix A if $A\mathbf{v} = \lambda\mathbf{v}$ for a nonzero column vector $\mathbf{v} \in \mathbb{R}^n$.

The vector \mathbf{v} is called an **eigenvector** of A belonging to (or associated with) the eigenvalue λ .

Remarks.

- Alternative notation:
eigenvalue = **characteristic value**,
eigenvector = **characteristic vector**.

- The zero vector is never considered an eigenvector.

Let A be an $n \times n$ matrix. Consider a linear operator $L : \mathbb{R}^n \rightarrow \mathbb{R}^n$ given by $L(\mathbf{x}) = A\mathbf{x}$.

Let $\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_n$ be a nonstandard basis for \mathbb{R}^n and B be the matrix of the operator L with respect to this basis.

Theorem The matrix B is diagonal if and only if vectors $\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_n$ are eigenvectors of A .

If this is the case, then the diagonal entries of the matrix B are the corresponding eigenvalues of A .

$$A\mathbf{v}_i = \lambda_i\mathbf{v}_i \iff B = \begin{pmatrix} \lambda_1 & & & 0 \\ & \lambda_2 & & \\ & & \ddots & \\ 0 & & & \lambda_n \end{pmatrix}$$

Eigenspaces

Let A be an $n \times n$ matrix. Let \mathbf{v} be an eigenvector of A belonging to an eigenvalue λ .

Then $A\mathbf{v} = \lambda\mathbf{v} \implies A\mathbf{v} = (\lambda I)\mathbf{v} \implies (A - \lambda I)\mathbf{v} = \mathbf{0}$.

Hence $\mathbf{v} \in N(A - \lambda I)$, the nullspace of the matrix $A - \lambda I$.

Conversely, if $\mathbf{x} \in N(A - \lambda I)$ then $A\mathbf{x} = \lambda\mathbf{x}$.

Thus the eigenvectors of A belonging to the eigenvalue λ are nonzero vectors from $N(A - \lambda I)$.

Definition. If $N(A - \lambda I) \neq \{\mathbf{0}\}$ then it is called the **eigenspace** of the matrix A corresponding to the eigenvalue λ .

How to find eigenvalues and eigenvectors?

Theorem Given a square matrix A and a scalar λ , the following statements are equivalent:

- λ is an eigenvalue of A ,
- $N(A - \lambda I) \neq \{\mathbf{0}\}$,
- the matrix $A - \lambda I$ is singular,
- $\det(A - \lambda I) = 0$.

Definition. $\det(A - \lambda I) = 0$ is called the **characteristic equation** of the matrix A .

Eigenvalues λ of A are roots of the characteristic equation. Associated eigenvectors of A are nonzero solutions of the equation $(A - \lambda I)\mathbf{x} = \mathbf{0}$.

Example. $A = \begin{pmatrix} a & b \\ c & d \end{pmatrix}.$

$$\begin{aligned} \det(A - \lambda I) &= \begin{vmatrix} a - \lambda & b \\ c & d - \lambda \end{vmatrix} \\ &= (a - \lambda)(d - \lambda) - bc \\ &= \lambda^2 - (a + d)\lambda + (ad - bc). \end{aligned}$$

Example. $A = \begin{pmatrix} a_{11} & a_{12} & a_{13} \\ a_{21} & a_{22} & a_{23} \\ a_{31} & a_{32} & a_{33} \end{pmatrix}.$

$$\det(A - \lambda I) = \begin{vmatrix} a_{11} - \lambda & a_{12} & a_{13} \\ a_{21} & a_{22} - \lambda & a_{23} \\ a_{31} & a_{32} & a_{33} - \lambda \end{vmatrix}$$
$$= -\lambda^3 + c_1\lambda^2 - c_2\lambda + c_3,$$

where $c_1 = a_{11} + a_{22} + a_{33}$ (the *trace* of A),

$$c_2 = \begin{vmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{vmatrix} + \begin{vmatrix} a_{11} & a_{13} \\ a_{31} & a_{33} \end{vmatrix} + \begin{vmatrix} a_{22} & a_{23} \\ a_{32} & a_{33} \end{vmatrix},$$

$$c_3 = \det A.$$

Theorem. Let $A = (a_{ij})$ be an $n \times n$ matrix.

Then $\det(A - \lambda I)$ is a polynomial of λ of degree n :

$$\det(A - \lambda I) = (-1)^n \lambda^n + c_1 \lambda^{n-1} + \cdots + c_{n-1} \lambda + c_n.$$

Furthermore, $(-1)^{n-1} c_1 = a_{11} + a_{22} + \cdots + a_{nn}$
and $c_n = \det A$.

Definition. The polynomial $p(\lambda) = \det(A - \lambda I)$ is called the **characteristic polynomial** of the matrix A .

Corollary Any $n \times n$ matrix has at most n eigenvalues.

Example. $A = \begin{pmatrix} 2 & 1 \\ 1 & 2 \end{pmatrix}$.

Characteristic equation: $\begin{vmatrix} 2 - \lambda & 1 \\ 1 & 2 - \lambda \end{vmatrix} = 0$.

$$(2 - \lambda)^2 - 1 = 0 \implies \lambda_1 = 1, \lambda_2 = 3.$$

$$(A - I)\mathbf{x} = \mathbf{0} \iff \begin{pmatrix} 1 & 1 \\ 1 & 1 \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$$

$$\iff \begin{pmatrix} 1 & 1 \\ 0 & 0 \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix} \iff x + y = 0.$$

The general solution is $(-t, t) = t(-1, 1)$, $t \in \mathbb{R}$.

Thus $\mathbf{v}_1 = (-1, 1)$ is an eigenvector associated with the eigenvalue 1. The corresponding eigenspace is the line spanned by \mathbf{v}_1 .

$$(A - 3I)\mathbf{x} = \mathbf{0} \iff \begin{pmatrix} -1 & 1 \\ 1 & -1 \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$$
$$\iff \begin{pmatrix} 1 & -1 \\ 0 & 0 \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix} \iff x - y = 0.$$

The general solution is $(t, t) = t(1, 1)$, $t \in \mathbb{R}$.

Thus $\mathbf{v}_2 = (1, 1)$ is an eigenvector associated with the eigenvalue 3. The corresponding eigenspace is the line spanned by \mathbf{v}_2 .

Summary. $A = \begin{pmatrix} 2 & 1 \\ 1 & 2 \end{pmatrix}$.

- The matrix A has two eigenvalues: 1 and 3.
- The eigenspace of A associated with the eigenvalue 1 is the line $t(-1, 1)$.
- The eigenspace of A associated with the eigenvalue 3 is the line $t(1, 1)$.
- Eigenvectors $\mathbf{v}_1 = (-1, 1)$ and $\mathbf{v}_2 = (1, 1)$ of the matrix A form an orthogonal basis for \mathbb{R}^2 .
- Geometrically, the mapping $\mathbf{x} \mapsto A\mathbf{x}$ is a stretch by a factor of 3 away from the line $x + y = 0$ in the orthogonal direction.

Example. $A = \begin{pmatrix} 1 & 1 & -1 \\ 1 & 1 & 1 \\ 0 & 0 & 2 \end{pmatrix}.$

Characteristic equation:

$$\begin{vmatrix} 1 - \lambda & 1 & -1 \\ 1 & 1 - \lambda & 1 \\ 0 & 0 & 2 - \lambda \end{vmatrix} = 0.$$

Expand the determinant by the 3rd row:

$$(2 - \lambda) \begin{vmatrix} 1 - \lambda & 1 \\ 1 & 1 - \lambda \end{vmatrix} = 0.$$

$$\begin{aligned} ((1 - \lambda)^2 - 1)(2 - \lambda) &= 0 \iff -\lambda(2 - \lambda)^2 = 0 \\ \implies \lambda_1 &= 0, \lambda_2 = 2. \end{aligned}$$

$$A\mathbf{x} = \mathbf{0} \iff \begin{pmatrix} 1 & 1 & -1 \\ 1 & 1 & 1 \\ 0 & 0 & 2 \end{pmatrix} \begin{pmatrix} x \\ y \\ z \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix}$$

Convert the matrix to reduced row echelon form:

$$\begin{pmatrix} 1 & 1 & -1 \\ 1 & 1 & 1 \\ 0 & 0 & 2 \end{pmatrix} \rightarrow \begin{pmatrix} 1 & 1 & -1 \\ 0 & 0 & 2 \\ 0 & 0 & 2 \end{pmatrix} \rightarrow \begin{pmatrix} 1 & 1 & 0 \\ 0 & 0 & 1 \\ 0 & 0 & 0 \end{pmatrix}$$

$$A\mathbf{x} = \mathbf{0} \iff \begin{cases} x + y = 0, \\ z = 0. \end{cases}$$

The general solution is $(-t, t, 0) = t(-1, 1, 0)$, $t \in \mathbb{R}$. Thus $\mathbf{v}_1 = (-1, 1, 0)$ is an eigenvector associated with the eigenvalue 0. The corresponding eigenspace is the line spanned by \mathbf{v}_1 .

$$(A - 2I)\mathbf{x} = \mathbf{0} \iff \begin{pmatrix} -1 & 1 & -1 \\ 1 & -1 & 1 \\ 0 & 0 & 0 \end{pmatrix} \begin{pmatrix} x \\ y \\ z \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix}$$

$$\iff \begin{pmatrix} 1 & -1 & 1 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix} \begin{pmatrix} x \\ y \\ z \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix} \iff x - y + z = 0.$$

The general solution is $x = t - s$, $y = t$, $z = s$, where $t, s \in \mathbb{R}$. Equivalently,

$$\mathbf{x} = (t - s, t, s) = t(1, 1, 0) + s(-1, 0, 1).$$

Thus $\mathbf{v}_2 = (1, 1, 0)$ and $\mathbf{v}_3 = (-1, 0, 1)$ are eigenvectors associated with the eigenvalue 2.

The corresponding eigenspace is the plane spanned by \mathbf{v}_2 and \mathbf{v}_3 .

Summary. $A = \begin{pmatrix} 1 & 1 & -1 \\ 1 & 1 & 1 \\ 0 & 0 & 2 \end{pmatrix}$.

- The matrix A has two eigenvalues: 0 and 2.
- The eigenvalue 0 is *simple*: the corresponding eigenspace is a line.
- The eigenvalue 2 is of *multiplicity* 2: the corresponding eigenspace is a plane.
- Eigenvectors $\mathbf{v}_1 = (-1, 1, 0)$, $\mathbf{v}_2 = (1, 1, 0)$, and $\mathbf{v}_3 = (-1, 0, 1)$ of the matrix A form a basis for \mathbb{R}^3 .
- Geometrically, the map $\mathbf{x} \mapsto A\mathbf{x}$ is the projection on the plane $\text{Span}(\mathbf{v}_2, \mathbf{v}_3)$ along the lines parallel to \mathbf{v}_1 with the subsequent scaling by a factor of 2.