MATH 304

Linear Algebra

**Lecture 29:
Orthogonal projection (continued).
Least squares problems.**

Orthogonal complement

Definition. Let $S \subset \mathbb{R}^n$. The **orthogonal complement** of S, denoted $S^\perp$, is the set of all vectors $\mathbf{x} \in \mathbb{R}^n$ that are orthogonal to S.

Theorem 1 (i) $S^\perp$ is a subspace of $\mathbb{R}^n$.
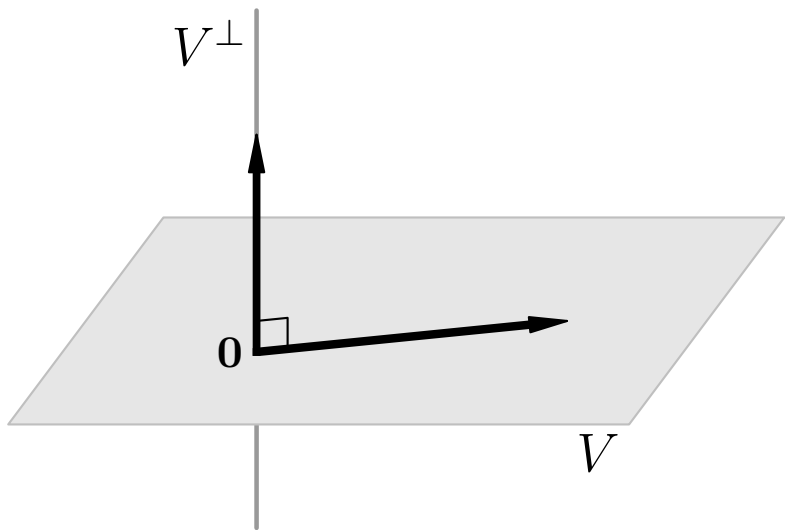**(ii)** $(S^\perp)^\perp = \mathrm{Span}(S)$.

Theorem 2 If V is a subspace of $\mathbb{R}^n$, then
(i) $(V^\perp)^\perp = V$,
(ii) $V \cap V^\perp = \{\mathbf{0}\}$,
(iii) $\dim V + \dim V^\perp = n$.

Theorem 3 If V is the row space of a matrix, then $V^\perp$ is the nullspace of the same matrix.
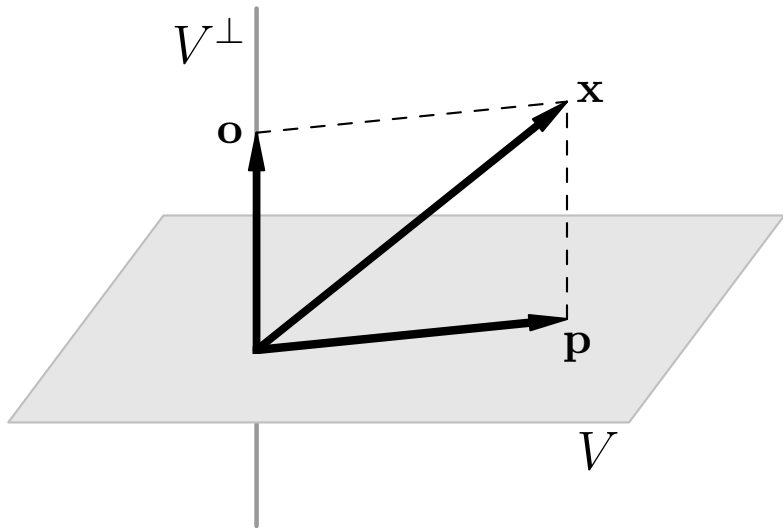
Orthogonal projection

Theorem 1 Let V be a subspace of $\mathbb{R}^n$. Then any vector $\mathbf{x} \in \mathbb{R}^n$ is uniquely represented as $\mathbf{x} = \mathbf{p} + \mathbf{o}$, where $\mathbf{p} \in V$ and $\mathbf{o} \in V^\perp$.

In the above expansion, $\mathbf{p}$ is called the **orthogonal projection** of the vector $\mathbf{x}$ onto the subspace V.

Theorem 2 $\|\mathbf{x} - \mathbf{v}\| > \|\mathbf{x} - \mathbf{p}\|$ for any $\mathbf{v} \neq \mathbf{p}$ in V.
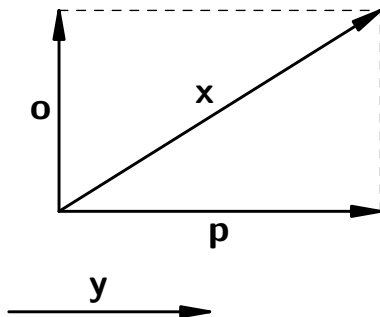
Thus $\|\mathbf{o}\| = \|\mathbf{x} - \mathbf{p}\| = \min_{\mathbf{v} \in V} \|\mathbf{x} - \mathbf{v}\|$ is the **distance** from the vector $\mathbf{x}$ to the subspace V.

Orthogonal projection onto a vector

Let $\mathbf{x}, \mathbf{y} \in \mathbb{R}^n$, with $\mathbf{y} \neq \mathbf{0}$.

Then there exists a unique decomposition $\mathbf{x} = \mathbf{p} + \mathbf{o}$
such that $\mathbf{p}$ is parallel to $\mathbf{y}$ and $\mathbf{o}$ is orthogonal to $\mathbf{y}$.

$\mathbf{p}$ = orthogonal projection of $\mathbf{x}$ onto $\mathbf{y}$

Orthogonal projection onto a vector

Let $\mathbf{x}, \mathbf{y} \in \mathbb{R}^n$, with $\mathbf{y} \neq \mathbf{0}$.

Then there exists a unique decomposition $\mathbf{x} = \mathbf{p} + \mathbf{o}$ such that $\mathbf{p}$ is parallel to $\mathbf{y}$ and $\mathbf{o}$ is orthogonal to $\mathbf{y}$.

We have $\mathbf{p} = \alpha\mathbf{y}$ for some $\alpha \in \mathbb{R}$. Then

$$0 = \mathbf{o} \cdot \mathbf{y} = (\mathbf{x} - \alpha\mathbf{y}) \cdot \mathbf{y} = \mathbf{x} \cdot \mathbf{y} - \alpha\mathbf{y} \cdot \mathbf{y}.$$

$$\implies \quad \alpha = \frac{\mathbf{x} \cdot \mathbf{y}}{\mathbf{y} \cdot \mathbf{y}} \quad \implies \quad \boxed{\mathbf{p} = \frac{\mathbf{x} \cdot \mathbf{y}}{\mathbf{y} \cdot \mathbf{y}} \mathbf{y}}$$

Problem. Find the distance from the point $\mathbf{x} = (3, 1)$ to the line spanned by $\mathbf{y} = (2, -1)$.

Consider the decomposition $\mathbf{x} = \mathbf{p} + \mathbf{o}$, where $\mathbf{p}$ is parallel to $\mathbf{y}$ while $\mathbf{o} \perp \mathbf{y}$. The required distance is the length of the orthogonal component $\mathbf{o}$.

$$\mathbf{p} = \frac{\mathbf{x} \cdot \mathbf{y}}{\mathbf{y} \cdot \mathbf{y}} \mathbf{y} = \frac{5}{5} (2, -1) = (2, -1),$$

$$\mathbf{o} = \mathbf{x} - \mathbf{p} = (3, 1) - (2, -1) = (1, 2), \quad \|\mathbf{o}\| = \sqrt{5}.$$

Problem. Find the point on the line $y = -x$ that is closest to the point $(3, 4)$.

The required point is the projection $\mathbf{p}$ of $\mathbf{v} = (3, 4)$ on the vector $\mathbf{w} = (1, -1)$ spanning the line $y = -x$.

$$\mathbf{p} = \frac{\mathbf{v} \cdot \mathbf{w}}{\mathbf{w} \cdot \mathbf{w}} \mathbf{w} = \frac{-1}{2} (1, -1) = \left(-\frac{1}{2}, \frac{1}{2} \right).$$

Problem. Let Π be the plane spanned by vectors $\mathbf{v}_1 = (1, 1, 0)$ and $\mathbf{v}_2 = (0, 1, 1)$.

(i) Find the orthogonal projection of the vector $\mathbf{x} = (4, 0, -1)$ onto the plane Π.

(ii) Find the distance from $\mathbf{x}$ to Π.

We have $\mathbf{x} = \mathbf{p} + \mathbf{o}$, where $\mathbf{p} \in \Pi$ and $\mathbf{o} \perp \Pi$. Then the orthogonal projection of $\mathbf{x}$ onto Π is $\mathbf{p}$ and the distance from $\mathbf{x}$ to Π is $\|\mathbf{o}\|$.

We have $\mathbf{p} = \alpha \mathbf{v}_1 + \beta \mathbf{v}_2$ for some $\alpha, \beta \in \mathbb{R}$.

Then $\mathbf{o} = \mathbf{x} - \mathbf{p} = \mathbf{x} - \alpha \mathbf{v}_1 - \beta \mathbf{v}_2$.

$$\begin{cases} \mathbf{o} \cdot \mathbf{v}_1 = 0 \\ \mathbf{o} \cdot \mathbf{v}_2 = 0 \end{cases} \iff \begin{cases} \alpha(\mathbf{v}_1 \cdot \mathbf{v}_1) + \beta(\mathbf{v}_2 \cdot \mathbf{v}_1) = \mathbf{x} \cdot \mathbf{v}_1 \\ \alpha(\mathbf{v}_1 \cdot \mathbf{v}_2) + \beta(\mathbf{v}_2 \cdot \mathbf{v}_2) = \mathbf{x} \cdot \mathbf{v}_2 \end{cases}$$

$$\mathbf{x} = (4, 0, -1), \ \mathbf{v}_1 = (1, 1, 0), \ \mathbf{v}_2 = (0, 1, 1)$$

$$\begin{cases} \alpha(\mathbf{v}_1 \cdot \mathbf{v}_1) + \beta(\mathbf{v}_2 \cdot \mathbf{v}_1) = \mathbf{x} \cdot \mathbf{v}_1 \\ \alpha(\mathbf{v}_1 \cdot \mathbf{v}_2) + \beta(\mathbf{v}_2 \cdot \mathbf{v}_2) = \mathbf{x} \cdot \mathbf{v}_2 \end{cases}$$

$$\iff \begin{cases} 2\alpha + \beta = 4 \\ \alpha + 2\beta = -1 \end{cases} \iff \begin{cases} \alpha = 3 \\ \beta = -2 \end{cases}$$

$$\mathbf{p} = 3\mathbf{v}_1 - 2\mathbf{v}_2 = (3, 1, -2)$$
$$\mathbf{o} = \mathbf{x} - \mathbf{p} = (1, -1, 1)$$
$$\|\mathbf{o}\| = \sqrt{3}$$

Problem. Let Π be the plane spanned by vectors $\mathbf{v}_1 = (1, 1, 0)$ and $\mathbf{v}_2 = (0, 1, 1)$.

 (i) Find the orthogonal projection of the vector $\mathbf{x} = (4, 0, -1)$ onto the plane Π.

 (ii) Find the distance from $\mathbf{x}$ to Π.

Alternative solution: We have $\mathbf{x} = \mathbf{p} + \mathbf{o}$, where $\mathbf{p} \in \Pi$ and $\mathbf{o} \perp \Pi$. Then the orthogonal projection of $\mathbf{x}$ onto Π is $\mathbf{p}$ and the distance from $\mathbf{x}$ to Π is $\|\mathbf{o}\|$.

Notice that $\mathbf{o}$ is the orthogonal projection of $\mathbf{x}$ onto the orthogonal complement $\Pi^{\perp}$. In the previous lecture, we found that $\Pi^{\perp}$ is the line spanned by the vector $\mathbf{y} = (1, -1, 1)$. It follows that

$$\mathbf{o} = \frac{\mathbf{x} \cdot \mathbf{y}}{\mathbf{y} \cdot \mathbf{y}} \mathbf{y} = \frac{3}{3}(1, -1, 1) = (1, -1, 1).$$

Then $\mathbf{p} = \mathbf{x} - \mathbf{o} = (4, 0, -1) - (1, -1, 1) = (3, 1, -2)$ and $\|\mathbf{o}\| = \sqrt{3}$.

Overdetermined system of linear equations:

$$\begin{cases} x + 2y = 3 \\ 3x + 2y = 5 \\ x + y = 2.09 \end{cases} \iff \begin{cases} x + 2y = 3 \\ -4y = -4 \\ -y = -0.91 \end{cases}$$

No solution: inconsistent system

Assume that a solution (x_0, y_0) does exist but the system is not quite accurate, namely, there may be some errors in the right-hand sides.

Problem. Find a good approximation of (x_0, y_0).

One approach is the **least squares fit**. Namely, we look for a pair (x, y) that minimizes the sum $(x + 2y - 3)^2 + (3x + 2y - 5)^2 + (x + y - 2.09)^2$.

Least squares solution

System of linear equations:
$$\begin{cases} a_{11}x_1 + a_{12}x_2 + \cdots + a_{1n}x_n = b_1 \\ a_{21}x_1 + a_{22}x_2 + \cdots + a_{2n}x_n = b_2 \\ \qquad \cdots\cdots\cdots \\ a_{m1}x_1 + a_{m2}x_2 + \cdots + a_{mn}x_n = b_m \end{cases} \iff A\mathbf{x} = \mathbf{b}$$

For any $\mathbf{x} \in \mathbb{R}^n$ define a **residual** $r(\mathbf{x}) = \mathbf{b} - A\mathbf{x}$.

The **least squares solution x** to the system is the one that minimizes $\|r(\mathbf{x})\|$ (or, equivalently, $\|r(\mathbf{x})\|^2$).

$$\|r(\mathbf{x})\|^2 = \sum_{i=1}^{m} \left(a_{i1}x_1 + a_{i2}x_2 + \cdots + a_{in}x_n - b_i\right)^2$$

Let A be an $m \times n$ matrix and let $\mathbf{b} \in \mathbb{R}^m$.

Theorem A vector $\hat{\mathbf{x}}$ is a least squares solution of the system $A\mathbf{x} = \mathbf{b}$ if and only if it is a solution of the associated **normal system** $\boxed{A^T A \mathbf{x} = A^T \mathbf{b}.}$

Proof: $A\mathbf{x}$ is an arbitrary vector in $R(A)$, the column space of A. Hence the length of $r(\mathbf{x}) = \mathbf{b} - A\mathbf{x}$ is minimal if $A\mathbf{x}$ is the orthogonal projection of $\mathbf{b}$ onto $R(A)$. That is, if $r(\mathbf{x})$ is orthogonal to $R(A)$.

We know that $\{\text{row space}\}^\perp = \{\text{nullspace}\}$ for any matrix. In particular, $R(A)^\perp = N(A^T)$, the nullspace of the transpose matrix of A. Thus $\hat{\mathbf{x}}$ is a least squares solution if and only if

$$A^T r(\hat{\mathbf{x}}) = \mathbf{0} \iff A^T(\mathbf{b} - A\hat{\mathbf{x}}) = \mathbf{0} \iff A^T A\hat{\mathbf{x}} = A^T \mathbf{b}.$$

Corollary The normal system $A^T A \mathbf{x} = A^T \mathbf{b}$ is always consistent.

Problem. Find the least squares solution to

$$\begin{cases} x + 2y = 3 \\ 3x + 2y = 5 \\ x + y = 2.09 \end{cases}$$

$$\begin{pmatrix} 1 & 2 \\ 3 & 2 \\ 1 & 1 \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} 3 \\ 5 \\ 2.09 \end{pmatrix}$$

$$\begin{pmatrix} 1 & 3 & 1 \\ 2 & 2 & 1 \end{pmatrix} \begin{pmatrix} 1 & 2 \\ 3 & 2 \\ 1 & 1 \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} 1 & 3 & 1 \\ 2 & 2 & 1 \end{pmatrix} \begin{pmatrix} 3 \\ 5 \\ 2.09 \end{pmatrix}$$

$$\begin{pmatrix} 11 & 9 \\ 9 & 9 \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} 20.09 \\ 18.09 \end{pmatrix} \iff \begin{cases} x = 1 \\ y = 1.01 \end{cases}$$