

MATH 311

Topics in Applied Mathematics

Lecture 18:

Least squares problems.

Norms and inner products.

Overdetermined system of linear equations:

$$\begin{cases} x + 2y = 3 \\ 3x + 2y = 5 \\ x + y = 2.09 \end{cases} \iff \begin{cases} x + 2y = 3 \\ -4y = -4 \\ -y = -0.91 \end{cases}$$

No solution: inconsistent system

Assume that a solution (x_0, y_0) does exist but the system is not quite accurate, namely, there may be some errors in the right-hand sides.

Problem. Find a good approximation of (x_0, y_0) .

One approach is the **least squares fit**. Namely, we look for a pair (x, y) that minimizes the sum $(x + 2y - 3)^2 + (3x + 2y - 5)^2 + (x + y - 2.09)^2$.

Least squares solution

System of linear equations:

$$\begin{cases} a_{11}x_1 + a_{12}x_2 + \cdots + a_{1n}x_n = b_1 \\ a_{21}x_1 + a_{22}x_2 + \cdots + a_{2n}x_n = b_2 \\ \dots\dots\dots \\ a_{m1}x_1 + a_{m2}x_2 + \cdots + a_{mn}x_n = b_m \end{cases} \iff \mathbf{Ax} = \mathbf{b}$$

For any $\mathbf{x} \in \mathbb{R}^n$ define a **residual** $r(\mathbf{x}) = \mathbf{b} - \mathbf{Ax}$.

The **least squares solution** \mathbf{x} to the system is the one that minimizes $\|r(\mathbf{x})\|$ (or, equivalently, $\|r(\mathbf{x})\|^2$).

$$\|r(\mathbf{x})\|^2 = \sum_{i=1}^m (a_{i1}x_1 + a_{i2}x_2 + \cdots + a_{in}x_n - b_i)^2$$

Let A be an $m \times n$ matrix and let $\mathbf{b} \in \mathbb{R}^m$.

Theorem A vector $\hat{\mathbf{x}}$ is a least squares solution of the system $A\mathbf{x} = \mathbf{b}$ if and only if it is a solution of the associated **normal system** $A^T A\mathbf{x} = A^T \mathbf{b}$.

Proof: $A\mathbf{x}$ is an arbitrary vector in $R(A)$, the column space of A . Hence the length of $r(\mathbf{x}) = \mathbf{b} - A\mathbf{x}$ is minimal if $A\mathbf{x}$ is the orthogonal projection of \mathbf{b} onto $R(A)$. That is, if $r(\mathbf{x})$ is orthogonal to $R(A)$.

We know that $R(A)^\perp = N(A^T)$, the nullspace of the transpose matrix. Thus $\hat{\mathbf{x}}$ is a least squares solution if and only if

$$A^T r(\hat{\mathbf{x}}) = \mathbf{0} \iff A^T(\mathbf{b} - A\hat{\mathbf{x}}) = \mathbf{0} \iff A^T A\hat{\mathbf{x}} = A^T \mathbf{b}.$$

Problem. Find the least squares solution to

$$\begin{cases} x + 2y = 3 \\ 3x + 2y = 5 \\ x + y = 2.09 \end{cases}$$

$$\begin{pmatrix} 1 & 2 \\ 3 & 2 \\ 1 & 1 \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} 3 \\ 5 \\ 2.09 \end{pmatrix}$$

$$\begin{pmatrix} 1 & 3 & 1 \\ 2 & 2 & 1 \end{pmatrix} \begin{pmatrix} 1 & 2 \\ 3 & 2 \\ 1 & 1 \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} 1 & 3 & 1 \\ 2 & 2 & 1 \end{pmatrix} \begin{pmatrix} 3 \\ 5 \\ 2.09 \end{pmatrix}$$

$$\begin{pmatrix} 11 & 9 \\ 9 & 9 \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} 20.09 \\ 18.09 \end{pmatrix} \iff \begin{cases} x = 1 \\ y = 1.01 \end{cases}$$

Problem. Find the constant function that is the least square fit to the following data

x	0	1	2	3
$f(x)$	1	0	1	2

$$f(x) = c \implies \begin{cases} c = 1 \\ c = 0 \\ c = 1 \\ c = 2 \end{cases} \implies \begin{pmatrix} 1 \\ 1 \\ 1 \\ 1 \end{pmatrix} (c) = \begin{pmatrix} 1 \\ 0 \\ 1 \\ 2 \end{pmatrix}$$

$$(1, 1, 1, 1) \begin{pmatrix} 1 \\ 1 \\ 1 \\ 1 \end{pmatrix} (c) = (1, 1, 1, 1) \begin{pmatrix} 1 \\ 0 \\ 1 \\ 2 \end{pmatrix}$$

$$c = \frac{1}{4}(1 + 0 + 1 + 2) = 1 \quad (\text{mean arithmetic value})$$

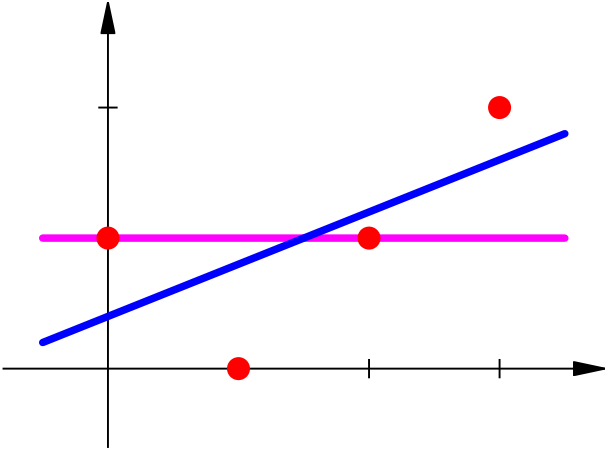
Problem. Find the linear polynomial that is the least square fit to the following data

x	0	1	2	3
$f(x)$	1	0	1	2

$$f(x) = c_1 + c_2x \implies \begin{cases} c_1 = 1 \\ c_1 + c_2 = 0 \\ c_1 + 2c_2 = 1 \\ c_1 + 3c_2 = 2 \end{cases} \implies \begin{pmatrix} 1 & 0 \\ 1 & 1 \\ 1 & 2 \\ 1 & 3 \end{pmatrix} \begin{pmatrix} c_1 \\ c_2 \end{pmatrix} = \begin{pmatrix} 1 \\ 0 \\ 1 \\ 2 \end{pmatrix}$$

$$\begin{pmatrix} 1 & 1 & 1 & 1 \\ 0 & 1 & 2 & 3 \end{pmatrix} \begin{pmatrix} 1 & 0 \\ 1 & 1 \\ 1 & 2 \\ 1 & 3 \end{pmatrix} \begin{pmatrix} c_1 \\ c_2 \end{pmatrix} = \begin{pmatrix} 1 & 1 & 1 & 1 \\ 0 & 1 & 2 & 3 \end{pmatrix} \begin{pmatrix} 1 \\ 0 \\ 1 \\ 2 \end{pmatrix}$$

$$\begin{pmatrix} 4 & 6 \\ 6 & 14 \end{pmatrix} \begin{pmatrix} c_1 \\ c_2 \end{pmatrix} = \begin{pmatrix} 4 \\ 8 \end{pmatrix} \iff \begin{cases} c_1 = 0.4 \\ c_2 = 0.4 \end{cases}$$



Norm

The notion of *norm* generalizes the notion of length of a vector in \mathbb{R}^n .

Definition. Let V be a vector space. A function $\alpha : V \rightarrow \mathbb{R}$ is called a **norm** on V if it has the following properties:

- (i) $\alpha(\mathbf{x}) \geq 0$, $\alpha(\mathbf{x}) = 0$ only for $\mathbf{x} = \mathbf{0}$ (positivity)
- (ii) $\alpha(r\mathbf{x}) = |r| \alpha(\mathbf{x})$ for all $r \in \mathbb{R}$ (homogeneity)
- (iii) $\alpha(\mathbf{x} + \mathbf{y}) \leq \alpha(\mathbf{x}) + \alpha(\mathbf{y})$ (triangle inequality)

Notation. The norm of a vector $\mathbf{x} \in V$ is usually denoted $\|\mathbf{x}\|$. Different norms on V are distinguished by subscripts, e.g., $\|\mathbf{x}\|_1$ and $\|\mathbf{x}\|_2$.

Examples. $V = \mathbb{R}^n$, $\mathbf{x} = (x_1, x_2, \dots, x_n) \in \mathbb{R}^n$.

- $\|\mathbf{x}\|_\infty = \max(|x_1|, |x_2|, \dots, |x_n|)$.

Positivity and homogeneity are obvious.

The triangle inequality:

$$\begin{aligned} |x_i + y_i| &\leq |x_i| + |y_i| \leq \max_j |x_j| + \max_j |y_j| \\ \implies \max_j |x_j + y_j| &\leq \max_j |x_j| + \max_j |y_j| \end{aligned}$$

- $\|\mathbf{x}\|_1 = |x_1| + |x_2| + \dots + |x_n|$.

Positivity and homogeneity are obvious.

The triangle inequality: $|x_i + y_i| \leq |x_i| + |y_i|$

$$\implies \sum_j |x_j + y_j| \leq \sum_j |x_j| + \sum_j |y_j|$$

Examples. $V = \mathbb{R}^n$, $\mathbf{x} = (x_1, x_2, \dots, x_n) \in \mathbb{R}^n$.

- $\|\mathbf{x}\|_p = (|x_1|^p + |x_2|^p + \dots + |x_n|^p)^{1/p}$, $p > 0$.

Theorem $\|\mathbf{x}\|_p$ is a norm on \mathbb{R}^n for any $p \geq 1$.

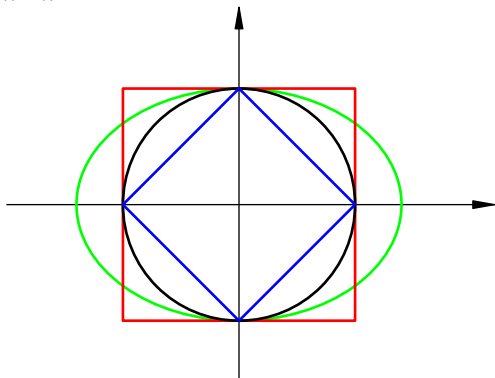
Remark. $\|\mathbf{x}\|_2 =$ Euclidean length of \mathbf{x} .

Definition. A **normed vector space** is a vector space endowed with a norm.

The norm defines a distance function on the normed vector space: $\text{dist}(\mathbf{x}, \mathbf{y}) = \|\mathbf{x} - \mathbf{y}\|$.

Then we say that a sequence $\mathbf{x}_1, \mathbf{x}_2, \dots$ converges to a vector \mathbf{x} if $\text{dist}(\mathbf{x}, \mathbf{x}_n) \rightarrow 0$ as $n \rightarrow \infty$.

Unit circle: $\|\mathbf{x}\| = 1$



$$\|\mathbf{x}\| = (x_1^2 + x_2^2)^{1/2} \quad \text{black}$$

$$\|\mathbf{x}\| = \left(\frac{1}{2}x_1^2 + x_2^2\right)^{1/2} \quad \text{green}$$

$$\|\mathbf{x}\| = |x_1| + |x_2| \quad \text{blue}$$

$$\|\mathbf{x}\| = \max(|x_1|, |x_2|) \quad \text{red}$$

Examples. $V = C[a, b]$, $f : [a, b] \rightarrow \mathbb{R}$.

- $\|f\|_\infty = \max_{a \leq x \leq b} |f(x)|$.

- $\|f\|_1 = \int_a^b |f(x)| dx$.

- $\|f\|_p = \left(\int_a^b |f(x)|^p dx \right)^{1/p}$, $p > 0$.

Theorem $\|f\|_p$ is a norm on $C[a, b]$ for any $p \geq 1$.

Inner product

The notion of *inner product* generalizes the notion of dot product of vectors in \mathbb{R}^n .

Definition. Let V be a vector space. A function $\beta : V \times V \rightarrow \mathbb{R}$, usually denoted $\beta(\mathbf{x}, \mathbf{y}) = \langle \mathbf{x}, \mathbf{y} \rangle$, is called an **inner product** on V if it is positive, symmetric, and bilinear. That is, if

- (i) $\langle \mathbf{x}, \mathbf{x} \rangle \geq 0$, $\langle \mathbf{x}, \mathbf{x} \rangle = 0$ only for $\mathbf{x} = \mathbf{0}$ (positivity)
- (ii) $\langle \mathbf{x}, \mathbf{y} \rangle = \langle \mathbf{y}, \mathbf{x} \rangle$ (symmetry)
- (iii) $\langle r\mathbf{x}, \mathbf{y} \rangle = r\langle \mathbf{x}, \mathbf{y} \rangle$ (homogeneity)
- (iv) $\langle \mathbf{x} + \mathbf{y}, \mathbf{z} \rangle = \langle \mathbf{x}, \mathbf{z} \rangle + \langle \mathbf{y}, \mathbf{z} \rangle$ (distributive law)

An **inner product space** is a vector space endowed with an inner product.

Examples. $V = \mathbb{R}^n$.

- $\langle \mathbf{x}, \mathbf{y} \rangle = \mathbf{x} \cdot \mathbf{y} = x_1y_1 + x_2y_2 + \cdots + x_ny_n$.

- $\langle \mathbf{x}, \mathbf{y} \rangle = d_1x_1y_1 + d_2x_2y_2 + \cdots + d_nx_ny_n$,
where $d_1, d_2, \dots, d_n > 0$.

- $\langle \mathbf{x}, \mathbf{y} \rangle = (D\mathbf{x}) \cdot (D\mathbf{y})$,

where D is an invertible $n \times n$ matrix.

Remarks. (a) Invertibility of D is necessary to show that $\langle \mathbf{x}, \mathbf{x} \rangle = 0 \implies \mathbf{x} = \mathbf{0}$.

(b) The second example is a particular case of the third one when $D = \text{diag}(d_1^{1/2}, d_2^{1/2}, \dots, d_n^{1/2})$.

Problem. Find an inner product on \mathbb{R}^2 such that $\langle \mathbf{e}_1, \mathbf{e}_1 \rangle = 2$, $\langle \mathbf{e}_2, \mathbf{e}_2 \rangle = 3$, and $\langle \mathbf{e}_1, \mathbf{e}_2 \rangle = -1$, where $\mathbf{e}_1 = (1, 0)$, $\mathbf{e}_2 = (0, 1)$.

Let $\mathbf{x} = (x_1, x_2)$, $\mathbf{y} = (y_1, y_2) \in \mathbb{R}^2$.

Then $\mathbf{x} = x_1\mathbf{e}_1 + x_2\mathbf{e}_2$, $\mathbf{y} = y_1\mathbf{e}_1 + y_2\mathbf{e}_2$.

Using bilinearity, we obtain

$$\begin{aligned}\langle \mathbf{x}, \mathbf{y} \rangle &= \langle x_1\mathbf{e}_1 + x_2\mathbf{e}_2, y_1\mathbf{e}_1 + y_2\mathbf{e}_2 \rangle \\ &= x_1\langle \mathbf{e}_1, y_1\mathbf{e}_1 + y_2\mathbf{e}_2 \rangle + x_2\langle \mathbf{e}_2, y_1\mathbf{e}_1 + y_2\mathbf{e}_2 \rangle \\ &= x_1y_1\langle \mathbf{e}_1, \mathbf{e}_1 \rangle + x_1y_2\langle \mathbf{e}_1, \mathbf{e}_2 \rangle + x_2y_1\langle \mathbf{e}_2, \mathbf{e}_1 \rangle + x_2y_2\langle \mathbf{e}_2, \mathbf{e}_2 \rangle \\ &= 2x_1y_1 - x_1y_2 - x_2y_1 + 3x_2y_2.\end{aligned}$$

Examples. $V = C[a, b]$.

- $\langle f, g \rangle = \int_a^b f(x)g(x) dx.$

- $\langle f, g \rangle = \int_a^b f(x)g(x)w(x) dx,$

where w is bounded, piecewise continuous, and $w > 0$ everywhere on $[a, b]$.

w is called the **weight** function.

Theorem Suppose $\langle \mathbf{x}, \mathbf{y} \rangle$ is an inner product on a vector space V . Then

$$\langle \mathbf{x}, \mathbf{y} \rangle^2 \leq \langle \mathbf{x}, \mathbf{x} \rangle \langle \mathbf{y}, \mathbf{y} \rangle \quad \text{for all } \mathbf{x}, \mathbf{y} \in V.$$

Proof: For any $t \in \mathbb{R}$ let $\mathbf{v}_t = \mathbf{x} + t\mathbf{y}$. Then

$$\langle \mathbf{v}_t, \mathbf{v}_t \rangle = \langle \mathbf{x}, \mathbf{x} \rangle + 2t\langle \mathbf{x}, \mathbf{y} \rangle + t^2\langle \mathbf{y}, \mathbf{y} \rangle.$$

The right-hand side is a quadratic polynomial in t (provided that $\mathbf{y} \neq \mathbf{0}$). Since $\langle \mathbf{v}_t, \mathbf{v}_t \rangle \geq 0$ for all t , the discriminant D is nonpositive. But

$$D = 4\langle \mathbf{x}, \mathbf{y} \rangle^2 - 4\langle \mathbf{x}, \mathbf{x} \rangle \langle \mathbf{y}, \mathbf{y} \rangle.$$

Cauchy-Schwarz Inequality:

$$|\langle \mathbf{x}, \mathbf{y} \rangle| \leq \sqrt{\langle \mathbf{x}, \mathbf{x} \rangle} \sqrt{\langle \mathbf{y}, \mathbf{y} \rangle}.$$

Cauchy-Schwarz Inequality:

$$|\langle \mathbf{x}, \mathbf{y} \rangle| \leq \sqrt{\langle \mathbf{x}, \mathbf{x} \rangle} \sqrt{\langle \mathbf{y}, \mathbf{y} \rangle}.$$

Corollary 1 $|\mathbf{x} \cdot \mathbf{y}| \leq |\mathbf{x}| |\mathbf{y}|$ for all $\mathbf{x}, \mathbf{y} \in \mathbb{R}^n$.

Equivalently, for all $x_i, y_i \in \mathbb{R}$,

$$(x_1 y_1 + \cdots + x_n y_n)^2 \leq (x_1^2 + \cdots + x_n^2)(y_1^2 + \cdots + y_n^2).$$

Corollary 2 For any $f, g \in C[a, b]$,

$$\left(\int_a^b f(x)g(x) dx \right)^2 \leq \int_a^b |f(x)|^2 dx \cdot \int_a^b |g(x)|^2 dx.$$

Norms induced by inner products

Theorem Suppose $\langle \mathbf{x}, \mathbf{y} \rangle$ is an inner product on a vector space V . Then $\|\mathbf{x}\| = \sqrt{\langle \mathbf{x}, \mathbf{x} \rangle}$ is a norm.

Proof: Positivity is obvious. Homogeneity:

$$\|r\mathbf{x}\| = \sqrt{\langle r\mathbf{x}, r\mathbf{x} \rangle} = \sqrt{r^2 \langle \mathbf{x}, \mathbf{x} \rangle} = |r| \sqrt{\langle \mathbf{x}, \mathbf{x} \rangle}.$$

Triangle inequality (follows from Cauchy-Schwarz's):

$$\begin{aligned} \|\mathbf{x} + \mathbf{y}\|^2 &= \langle \mathbf{x} + \mathbf{y}, \mathbf{x} + \mathbf{y} \rangle \\ &= \langle \mathbf{x}, \mathbf{x} \rangle + \langle \mathbf{x}, \mathbf{y} \rangle + \langle \mathbf{y}, \mathbf{x} \rangle + \langle \mathbf{y}, \mathbf{y} \rangle \\ &\leq \langle \mathbf{x}, \mathbf{x} \rangle + |\langle \mathbf{x}, \mathbf{y} \rangle| + |\langle \mathbf{y}, \mathbf{x} \rangle| + \langle \mathbf{y}, \mathbf{y} \rangle \\ &\leq \|\mathbf{x}\|^2 + 2\|\mathbf{x}\| \|\mathbf{y}\| + \|\mathbf{y}\|^2 = (\|\mathbf{x}\| + \|\mathbf{y}\|)^2. \end{aligned}$$

Examples. • The length of a vector in \mathbb{R}^n ,

$$|\mathbf{x}| = \sqrt{x_1^2 + x_2^2 + \cdots + x_n^2},$$

is the norm induced by the dot product

$$\mathbf{x} \cdot \mathbf{y} = x_1y_1 + x_2y_2 + \cdots + x_ny_n.$$

• The norm $\|f\|_2 = \left(\int_a^b |f(x)|^2 dx \right)^{1/2}$ on the vector space $C[a, b]$ is induced by the inner product

$$\langle f, g \rangle = \int_a^b f(x)g(x) dx.$$

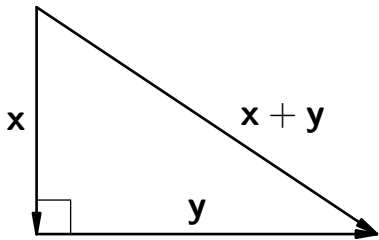
Angle

Since $|\langle \mathbf{x}, \mathbf{y} \rangle| \leq \|\mathbf{x}\| \|\mathbf{y}\|$, we can define the *angle* between nonzero vectors in any vector space with an inner product (and induced norm):

$$\angle(\mathbf{x}, \mathbf{y}) = \arccos \frac{\langle \mathbf{x}, \mathbf{y} \rangle}{\|\mathbf{x}\| \|\mathbf{y}\|}.$$

Then $\langle \mathbf{x}, \mathbf{y} \rangle = \|\mathbf{x}\| \|\mathbf{y}\| \cos \angle(\mathbf{x}, \mathbf{y})$.

In particular, vectors \mathbf{x} and \mathbf{y} are **orthogonal** (denoted $\mathbf{x} \perp \mathbf{y}$) if $\langle \mathbf{x}, \mathbf{y} \rangle = 0$.

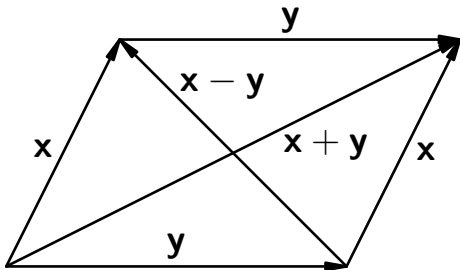


Pythagorean Theorem:

$$\mathbf{x} \perp \mathbf{y} \implies \|\mathbf{x} + \mathbf{y}\|^2 = \|\mathbf{x}\|^2 + \|\mathbf{y}\|^2$$

Proof:

$$\begin{aligned}\|\mathbf{x} + \mathbf{y}\|^2 &= \langle \mathbf{x} + \mathbf{y}, \mathbf{x} + \mathbf{y} \rangle \\ &= \langle \mathbf{x}, \mathbf{x} \rangle + \langle \mathbf{x}, \mathbf{y} \rangle + \langle \mathbf{y}, \mathbf{x} \rangle + \langle \mathbf{y}, \mathbf{y} \rangle \\ &= \langle \mathbf{x}, \mathbf{x} \rangle + \langle \mathbf{y}, \mathbf{y} \rangle = \|\mathbf{x}\|^2 + \|\mathbf{y}\|^2.\end{aligned}$$



Parallelogram Identity:

$$\|\mathbf{x} + \mathbf{y}\|^2 + \|\mathbf{x} - \mathbf{y}\|^2 = 2\|\mathbf{x}\|^2 + 2\|\mathbf{y}\|^2$$

Proof: $\|\mathbf{x} + \mathbf{y}\|^2 = \langle \mathbf{x} + \mathbf{y}, \mathbf{x} + \mathbf{y} \rangle = \langle \mathbf{x}, \mathbf{x} \rangle + \langle \mathbf{x}, \mathbf{y} \rangle + \langle \mathbf{y}, \mathbf{x} \rangle + \langle \mathbf{y}, \mathbf{y} \rangle$.

Similarly, $\|\mathbf{x} - \mathbf{y}\|^2 = \langle \mathbf{x}, \mathbf{x} \rangle - \langle \mathbf{x}, \mathbf{y} \rangle - \langle \mathbf{y}, \mathbf{x} \rangle + \langle \mathbf{y}, \mathbf{y} \rangle$.

Then $\|\mathbf{x} + \mathbf{y}\|^2 + \|\mathbf{x} - \mathbf{y}\|^2 = 2\langle \mathbf{x}, \mathbf{x} \rangle + 2\langle \mathbf{y}, \mathbf{y} \rangle = 2\|\mathbf{x}\|^2 + 2\|\mathbf{y}\|^2$.