

Sample problems for Test 1: Solutions

Any problem may be altered or replaced by a different one!

Problem 1 (15 pts.) Find the point of intersection of the planes $x + 2y - z = 1$, $x - 3y = -5$, and $2x + y + z = 0$ in \mathbb{R}^3 .

The intersection point (x, y, z) is a solution of the system

$$\begin{cases} x + 2y - z = 1, \\ x - 3y = -5, \\ 2x + y + z = 0. \end{cases}$$

To solve the system, we convert its augmented matrix into reduced row echelon form using elementary row operations:

$$\begin{aligned} \left(\begin{array}{ccc|c} 1 & 2 & -1 & 1 \\ 1 & -3 & 0 & -5 \\ 2 & 1 & 1 & 0 \end{array} \right) &\rightarrow \left(\begin{array}{ccc|c} 1 & 2 & -1 & 1 \\ 0 & -5 & 1 & -6 \\ 2 & 1 & 1 & 0 \end{array} \right) \rightarrow \left(\begin{array}{ccc|c} 1 & 2 & -1 & 1 \\ 0 & -5 & 1 & -6 \\ 0 & -3 & 3 & -2 \end{array} \right) \rightarrow \left(\begin{array}{ccc|c} 1 & 2 & -1 & 1 \\ 0 & -3 & 3 & -2 \\ 0 & -5 & 1 & -6 \end{array} \right) \\ &\rightarrow \left(\begin{array}{ccc|c} 1 & 2 & -1 & 1 \\ 0 & 1 & -1 & \frac{2}{3} \\ 0 & -5 & 1 & -6 \end{array} \right) \rightarrow \left(\begin{array}{ccc|c} 1 & 2 & -1 & 1 \\ 0 & 1 & -1 & \frac{2}{3} \\ 0 & 0 & -4 & -\frac{10}{3} \end{array} \right) \rightarrow \left(\begin{array}{ccc|c} 1 & 2 & -1 & 1 \\ 0 & 1 & -1 & \frac{2}{3} \\ 0 & 0 & 1 & \frac{5}{3} \end{array} \right) \\ &\rightarrow \left(\begin{array}{ccc|c} 1 & 2 & -1 & 1 \\ 0 & 1 & 0 & \frac{4}{3} \\ 0 & 0 & 1 & \frac{2}{3} \end{array} \right) \rightarrow \left(\begin{array}{ccc|c} 1 & 2 & 0 & \frac{5}{3} \\ 0 & 1 & 0 & \frac{4}{3} \\ 0 & 0 & 1 & \frac{2}{3} \end{array} \right) \rightarrow \left(\begin{array}{ccc|c} 1 & 0 & 0 & -1 \\ 0 & 1 & 0 & \frac{4}{3} \\ 0 & 0 & 1 & \frac{2}{3} \end{array} \right). \end{aligned}$$

Thus the three planes intersect at the point $(-1, \frac{4}{3}, \frac{2}{3})$.

Alternative solution: The intersection point (x, y, z) is a solution of the system

$$\begin{cases} x + 2y - z = 1, \\ x - 3y = -5, \\ 2x + y + z = 0. \end{cases}$$

Adding all three equations, we obtain $4x = -4$. Hence $x = -1$. Substituting $x = -1$ into the second equation, we obtain $y = \frac{4}{3}$. Substituting $x = -1$ and $y = \frac{4}{3}$ into the third equation, we obtain $z = \frac{2}{3}$. It is easy to check that $x = -1$, $y = \frac{4}{3}$, $z = \frac{2}{3}$ is indeed a solution of the system. Thus $(-1, \frac{4}{3}, \frac{2}{3})$ is the unique intersection point.

Problem 2 (25 pts.) Let $A = \begin{pmatrix} 1 & -2 & 4 & 1 \\ 2 & 3 & 2 & 0 \\ 2 & 0 & -1 & 1 \\ 2 & 0 & 0 & 1 \end{pmatrix}$.

(i) Evaluate the determinant of the matrix A .

First let us subtract 2 times the fourth column of A from the first column:

$$\begin{vmatrix} 1 & -2 & 4 & 1 \\ 2 & 3 & 2 & 0 \\ 2 & 0 & -1 & 1 \\ 2 & 0 & 0 & 1 \end{vmatrix} = \begin{vmatrix} -1 & -2 & 4 & 1 \\ 2 & 3 & 2 & 0 \\ 0 & 0 & -1 & 1 \\ 0 & 0 & 0 & 1 \end{vmatrix}.$$

Now the determinant can be easily expanded by the fourth row:

$$\begin{vmatrix} -1 & -2 & 4 & 1 \\ 2 & 3 & 2 & 0 \\ 0 & 0 & -1 & 1 \\ 0 & 0 & 0 & 1 \end{vmatrix} = \begin{vmatrix} -1 & -2 & 4 \\ 2 & 3 & 2 \\ 0 & 0 & -1 \end{vmatrix}.$$

The 3×3 determinant is easily expanded by the third row:

$$\begin{vmatrix} -1 & -2 & 4 \\ 2 & 3 & 2 \\ 0 & 0 & -1 \end{vmatrix} = (-1) \begin{vmatrix} -1 & -2 \\ 2 & 3 \end{vmatrix}.$$

Thus

$$\det A = - \begin{vmatrix} -1 & -2 \\ 2 & 3 \end{vmatrix} = -1.$$

Another way to evaluate $\det A$ is to reduce the matrix A to the identity matrix using elementary row operations (see below). This requires much more work but we are going to do it anyway, to find the inverse of A .

(ii) Find the inverse matrix A^{-1} .

First we merge the matrix A with the identity matrix into one 4×8 matrix

$$(A|I) = \left(\begin{array}{cccc|cccc} 1 & -2 & 4 & 1 & 1 & 0 & 0 & 0 \\ 2 & 3 & 2 & 0 & 0 & 1 & 0 & 0 \\ 2 & 0 & -1 & 1 & 0 & 0 & 1 & 0 \\ 2 & 0 & 0 & 1 & 0 & 0 & 0 & 1 \end{array} \right).$$

Then we apply elementary row operations to this matrix until the left part becomes the identity matrix.

Subtract 2 times the first row from the second row:

$$\left(\begin{array}{cccc|cccc} 1 & -2 & 4 & 1 & 1 & 0 & 0 & 0 \\ 2 & 3 & 2 & 0 & 0 & 1 & 0 & 0 \\ 2 & 0 & -1 & 1 & 0 & 0 & 1 & 0 \\ 2 & 0 & 0 & 1 & 0 & 0 & 0 & 1 \end{array} \right) \rightarrow \left(\begin{array}{cccc|cccc} 1 & -2 & 4 & 1 & 1 & 0 & 0 & 0 \\ 0 & 7 & -6 & -2 & -2 & 1 & 0 & 0 \\ 2 & 0 & -1 & 1 & 0 & 0 & 1 & 0 \\ 2 & 0 & 0 & 1 & 0 & 0 & 0 & 1 \end{array} \right).$$

Subtract 2 times the first row from the third row:

$$\left(\begin{array}{cccc|cccc} 1 & -2 & 4 & 1 & 1 & 0 & 0 & 0 \\ 0 & 7 & -6 & -2 & -2 & 1 & 0 & 0 \\ 2 & 0 & -1 & 1 & 0 & 0 & 1 & 0 \\ 2 & 0 & 0 & 1 & 0 & 0 & 0 & 1 \end{array} \right) \rightarrow \left(\begin{array}{cccc|cccc} 1 & -2 & 4 & 1 & 1 & 0 & 0 & 0 \\ 0 & 7 & -6 & -2 & -2 & 1 & 0 & 0 \\ 0 & 4 & -9 & -1 & -2 & 0 & 1 & 0 \\ 2 & 0 & 0 & 1 & 0 & 0 & 0 & 1 \end{array} \right).$$

Subtract 2 times the first row from the fourth row:

$$\left(\begin{array}{cccc|cccc} 1 & -2 & 4 & 1 & 1 & 0 & 0 & 0 \\ 0 & 7 & -6 & -2 & -2 & 1 & 0 & 0 \\ 0 & 4 & -9 & -1 & -2 & 0 & 1 & 0 \\ 2 & 0 & 0 & 1 & 0 & 0 & 0 & 1 \end{array} \right) \rightarrow \left(\begin{array}{cccc|cccc} 1 & -2 & 4 & 1 & 1 & 0 & 0 & 0 \\ 0 & 7 & -6 & -2 & -2 & 1 & 0 & 0 \\ 0 & 4 & -9 & -1 & -2 & 0 & 1 & 0 \\ 0 & 4 & -8 & -1 & -2 & 0 & 0 & 1 \end{array} \right).$$

Multiply the second, the third, and the fourth rows by -1 :

$$\left(\begin{array}{cccc|cccc} 1 & 0 & 0 & 0 & 3 & 2 & 16 & -19 \\ 0 & -1 & 0 & 0 & 2 & 1 & 10 & -12 \\ 0 & 0 & -1 & 0 & 0 & 0 & 1 & -1 \\ 0 & 0 & 0 & -1 & 6 & 4 & 32 & -39 \end{array} \right) \rightarrow \left(\begin{array}{cccc|cccc} 1 & 0 & 0 & 0 & 3 & 2 & 16 & -19 \\ 0 & 1 & 0 & 0 & -2 & -1 & -10 & 12 \\ 0 & 0 & 1 & 0 & 0 & 0 & -1 & 1 \\ 0 & 0 & 0 & 1 & -6 & -4 & -32 & 39 \end{array} \right).$$

Finally the left part of our 4×8 matrix is transformed into the identity matrix. Therefore the current right part is the inverse matrix of A . Thus

$$A^{-1} = \begin{pmatrix} 1 & -2 & 4 & 1 \\ 2 & 3 & 2 & 0 \\ 2 & 0 & -1 & 1 \\ 2 & 0 & 0 & 1 \end{pmatrix}^{-1} = \begin{pmatrix} 3 & 2 & 16 & -19 \\ -2 & -1 & -10 & 12 \\ 0 & 0 & -1 & 1 \\ -6 & -4 & -32 & 39 \end{pmatrix}.$$

As a byproduct, we can evaluate the determinant of A . We have transformed A into the identity matrix using elementary row operations. These included no row exchanges and three row multiplications, each time by -1 . It follows that $\det I = (-1)^3 \det A$. Hence $\det A = -\det I = -1$.

Problem 3 (20 pts.) Determine which of the following subsets of \mathbb{R}^3 are subspaces. Briefly explain.

- (i) The set S_1 of vectors $(x, y, z) \in \mathbb{R}^3$ such that $xyz = 0$.
- (ii) The set S_2 of vectors $(x, y, z) \in \mathbb{R}^3$ such that $x + y + z = 0$.
- (iii) The set S_3 of vectors $(x, y, z) \in \mathbb{R}^3$ such that $y^2 + z^2 = 0$.
- (iv) The set S_4 of vectors $(x, y, z) \in \mathbb{R}^3$ such that $y^2 - z^2 = 0$.

A subset of \mathbb{R}^3 is a subspace if it is closed under addition and scalar multiplication. Besides, a subspace must not be empty.

It is easy to see that each of the sets S_1 , S_2 , S_3 , and S_4 contains the zero vector $(0, 0, 0)$ and all these sets are closed under scalar multiplication.

The set S_1 is the union of three planes $x = 0$, $y = 0$, and $z = 0$. It is not closed under addition as the following example shows: $(1, 1, 0) + (0, 0, 1) = (1, 1, 1)$.

S_2 is a plane passing through the origin. Obviously, it is closed under addition.

The condition $y^2 + z^2 = 0$ is equivalent to $y = z = 0$. Hence S_3 is a line passing through the origin. It is closed under addition.

Since $y^2 - z^2 = (y - z)(y + z)$, the set S_4 is the union of two planes $y - z = 0$ and $y + z = 0$. The following example shows that S_4 is not closed under addition: $(0, 1, 1) + (0, 1, -1) = (0, 2, 0)$.

Thus S_2 and S_3 are subspaces of \mathbb{R}^3 while S_1 and S_4 are not.

Problem 4 (30 pts.) Let $B = \begin{pmatrix} 0 & -1 & 4 & 1 \\ 1 & 1 & 2 & -1 \\ -3 & 0 & -1 & 0 \\ 2 & -1 & 0 & 1 \end{pmatrix}$.

- (i) Find the rank and the nullity of the matrix B .

The rank (dimension of the row space) and the nullity (dimension of the nullspace) of a matrix are preserved under elementary row operations. We apply such operations to convert the matrix B into row echelon form.

First interchange the first row with the second row:

$$\begin{pmatrix} 0 & -1 & 4 & 1 \\ 1 & 1 & 2 & -1 \\ -3 & 0 & -1 & 0 \\ 2 & -1 & 0 & 1 \end{pmatrix} \rightarrow \begin{pmatrix} 1 & 1 & 2 & -1 \\ 0 & -1 & 4 & 1 \\ -3 & 0 & -1 & 0 \\ 2 & -1 & 0 & 1 \end{pmatrix}.$$

Add 3 times the first row to the third row, then subtract 2 times the first row from the fourth row:

$$\begin{pmatrix} 1 & 1 & 2 & -1 \\ 0 & -1 & 4 & 1 \\ -3 & 0 & -1 & 0 \\ 2 & -1 & 0 & 1 \end{pmatrix} \rightarrow \begin{pmatrix} 1 & 1 & 2 & -1 \\ 0 & -1 & 4 & 1 \\ 0 & 3 & 5 & -3 \\ 2 & -1 & 0 & 1 \end{pmatrix} \rightarrow \begin{pmatrix} 1 & 1 & 2 & -1 \\ 0 & -1 & 4 & 1 \\ 0 & 3 & 5 & -3 \\ 0 & -3 & -4 & 3 \end{pmatrix}.$$

Multiply the second row by -1 :

$$\begin{pmatrix} 1 & 1 & 2 & -1 \\ 0 & -1 & 4 & 1 \\ 0 & 3 & 5 & -3 \\ 0 & -3 & -4 & 3 \end{pmatrix} \rightarrow \begin{pmatrix} 1 & 1 & 2 & -1 \\ 0 & 1 & -4 & -1 \\ 0 & 3 & 5 & -3 \\ 0 & -3 & -4 & 3 \end{pmatrix}.$$

Add the fourth row to the third row:

$$\begin{pmatrix} 1 & 1 & 2 & -1 \\ 0 & 1 & -4 & -1 \\ 0 & 3 & 5 & -3 \\ 0 & -3 & -4 & 3 \end{pmatrix} \rightarrow \begin{pmatrix} 1 & 1 & 2 & -1 \\ 0 & 1 & -4 & -1 \\ 0 & 0 & 1 & 0 \\ 0 & -3 & -4 & 3 \end{pmatrix}.$$

Add 3 times the second row to the fourth row:

$$\begin{pmatrix} 1 & 1 & 2 & -1 \\ 0 & 1 & -4 & -1 \\ 0 & 0 & 1 & 0 \\ 0 & -3 & -4 & 3 \end{pmatrix} \rightarrow \begin{pmatrix} 1 & 1 & 2 & -1 \\ 0 & 1 & -4 & -1 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & -16 & 0 \end{pmatrix}.$$

Add 16 times the third row to the fourth row:

$$\begin{pmatrix} 1 & 1 & 2 & -1 \\ 0 & 1 & -4 & -1 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & -16 & 0 \end{pmatrix} \rightarrow \begin{pmatrix} 1 & 1 & 2 & -1 \\ 0 & 1 & -4 & -1 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 \end{pmatrix}.$$

Now that the matrix is in row echelon form, its rank equals the number of nonzero rows, which is 3. Since

$$(\text{rank of } B) + (\text{nullity of } B) = (\text{the number of columns of } B) = 4,$$

it follows that the nullity of B equals 1.

(ii) Find a basis for the row space of B , then extend this basis to a basis for \mathbb{R}^4 .

The row space of a matrix is invariant under elementary row operations. Therefore the row space of the matrix B is the same as the row space of its row echelon form

$$\begin{pmatrix} 1 & 1 & 2 & -1 \\ 0 & 1 & -4 & -1 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 \end{pmatrix}.$$

The nonzero rows of the latter are linearly independent so that they form a basis for its row space. Hence the vectors $\mathbf{v}_1 = (1, 1, 2, -1)$, $\mathbf{v}_2 = (0, 1, -4, -1)$, and $\mathbf{v}_3 = (0, 0, 1, 0)$ form a basis for the row space of B .

To extend the basis $\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3$ to a basis for \mathbb{R}^4 , we need a vector $\mathbf{v}_4 \in \mathbb{R}^4$ that is not a linear combination of $\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3$. It is known that at least one of the vectors $\mathbf{e}_1 = (1, 0, 0, 0)$, $\mathbf{e}_2 = (0, 1, 0, 0)$, $\mathbf{e}_3 = (0, 0, 1, 0)$, and $\mathbf{e}_4 = (0, 0, 0, 1)$ can be chosen as \mathbf{v}_4 . In particular, the vectors $\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3, \mathbf{e}_4$ form a basis for \mathbb{R}^4 . This follows from the fact that the 4×4 matrix whose rows are these vectors is not singular:

$$\begin{vmatrix} 1 & 1 & 2 & -1 \\ 0 & 1 & -4 & -1 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{vmatrix} = 1 \neq 0.$$

(iii) Find a basis for the nullspace of B .

The nullspace of B is the solution set of the system of linear homogeneous equations with B as the coefficient matrix. To solve the system, we convert the matrix B to reduced row echelon form. The row echelon form of B has been obtained earlier:

$$\begin{pmatrix} 1 & 1 & 2 & -1 \\ 0 & 1 & -4 & -1 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 \end{pmatrix}.$$

Add 4 times the third row to the second row, then subtract 2 times the third row from the first row:

$$\begin{pmatrix} 1 & 1 & 2 & -1 \\ 0 & 1 & -4 & -1 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 \end{pmatrix} \rightarrow \begin{pmatrix} 1 & 1 & 2 & -1 \\ 0 & 1 & 0 & -1 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 \end{pmatrix} \rightarrow \begin{pmatrix} 1 & 1 & 0 & -1 \\ 0 & 1 & 0 & -1 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 \end{pmatrix}.$$

Subtract the second row from the first row:

$$\begin{pmatrix} 1 & 1 & 0 & -1 \\ 0 & 1 & 0 & -1 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 \end{pmatrix} \rightarrow \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & -1 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 \end{pmatrix}.$$

We have obtained the reduced row echelon form of the matrix B . Its nullspace is the same as the nullspace of B . Hence a vector $(x_1, x_2, x_3, x_4) \in \mathbb{R}^4$ belongs to the nullspace of B if and only if

$$\begin{cases} x_1 = 0, \\ x_2 - x_4 = 0, \\ x_3 = 0 \end{cases} \iff \begin{cases} x_1 = 0, \\ x_2 = x_4, \\ x_3 = 0. \end{cases}$$

The general solution of this system is $(x_1, x_2, x_3, x_4) = (0, t, 0, t) = t(0, 1, 0, 1)$, $t \in \mathbb{R}$. Thus the nullspace of the matrix B is spanned by the vector $(0, 1, 0, 1)$. This vector forms a basis for the nullspace.

Bonus Problem 5 (15 pts.) Show that the functions $f_1(x) = x$, $f_2(x) = xe^x$, and $f_3(x) = e^{-x}$ are linearly independent in the vector space $C^\infty(\mathbb{R})$.

Suppose that $af_1(x) + bf_2(x) + cf_3(x) = 0$ for all $x \in \mathbb{R}$, where a, b, c are constants. We have to show that $a = b = c = 0$.

Differentiating the identity $af_1(x) + bf_2(x) + cf_3(x) = 0$ four times, we obtain four more identities:

$$\begin{aligned} ax + bxe^x + ce^{-x} &= 0, \\ a + be^x + bxe^x - ce^{-x} &= 0, \\ 2be^x + bxe^x + ce^{-x} &= 0, \\ 3be^x + bxe^x - ce^{-x} &= 0, \\ 4be^x + bxe^x + ce^{-x} &= 0. \end{aligned}$$

Subtracting the third identity from the fifth one, we obtain $2be^x = 0$, which implies that $b = 0$. Substituting $b = 0$ in the third identity, we obtain $ce^{-x} = 0$, which implies that $c = 0$. Substituting $b = 0$ and $c = 0$ in the second identity, we obtain $a = 0$.

Alternative solution: Suppose that $ax + bxe^x + ce^{-x} = 0$ for all $x \in \mathbb{R}$, where a, b, c are constants. We have to show that $a = b = c = 0$.

For any $x \neq 0$ divide both sides of the identity by xe^x :

$$ae^{-x} + b + cx^{-1}e^{-2x} = 0.$$

Note that $e^{-x} \rightarrow 0$ and $x^{-1}e^{-2x} \rightarrow 0$ as $x \rightarrow +\infty$. Hence the left-hand side approaches b as $x \rightarrow +\infty$. It follows that $b = 0$. Now $ax + ce^{-x} = 0$ for all $x \in \mathbb{R}$. For any $x \neq 0$ divide both sides of the latter identity by x :

$$a + cx^{-1}e^{-x} = 0.$$

Since $x^{-1}e^{-x} \rightarrow 0$ as $x \rightarrow +\infty$, the left-hand side approaches a as $x \rightarrow +\infty$. It follows that $a = 0$. Then $ce^{-x} = 0$, which implies that $c = 0$.

Bonus Problem 6 (15 pts.) Let V be a finite-dimensional vector space and V_0 be a proper subspace of V (where proper means that $V_0 \neq V$). Prove that $\dim V_0 < \dim V$.

Any linearly independent set in a vector space can be extended to a basis. Since the vector space V is finite dimensional, it does not admit infinitely many linearly independent vectors. Clearly, the same is true for the subspace V_0 . It follows that V_0 is also finite-dimensional.

Let $\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_k$ be a basis for V_0 . The vectors $\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_k$ are linearly independent in V since they are linearly independent in V_0 . Therefore we can extend this collection of vectors to a basis for V by adding some vectors $\mathbf{w}_1, \dots, \mathbf{w}_m$. As $V_0 \neq V$, we do need to add some vectors, i.e., $m \geq 1$. Thus $\dim V_0 = k$ and $\dim V = k + m > k$.