

MATH 311

Topics in Applied Mathematics I

**Lecture 34:**

**Line integrals.**

**Green's theorem.**

## Path

*Definition.* A **path** in  $\mathbb{R}^n$  is a continuous function  $\mathbf{x} : [a, b] \rightarrow \mathbb{R}^n$ .

Paths provide parametrizations for curves.

Length of the path  $\mathbf{x}$  is defined as

$L = \sup_P \sum_{j=1}^k \|\mathbf{x}(t_j) - \mathbf{x}(t_{j-1})\|$  over all partitions  $P = \{t_0, t_1, \dots, t_k\}$  of the interval  $[a, b]$ .

**Theorem** The length of a smooth path

$\mathbf{x} : [a, b] \rightarrow \mathbb{R}^n$  is  $\int_a^b \|\mathbf{x}'(t)\| dt$ .

Arclength parameter:  $s(t) = \int_a^t \|\mathbf{x}'(\tau)\| d\tau$ .

## Scalar line integral

Scalar line integral is an integral of a scalar function  $f$  over a path  $\mathbf{x} : [a, b] \rightarrow \mathbb{R}^n$  of finite length relative to the arclength. It is defined as a limit of Riemann sums

$$\mathcal{S}(f, P, \tau_j) = \sum_{j=1}^k f(\mathbf{x}(\tau_j)) (s(t_j) - s(t_{j-1})),$$

where  $P = \{t_0, t_1, \dots, t_k\}$  is a partition of  $[a, b]$ ,  $\tau_j \in [t_j, t_{j-1}]$  for  $1 \leq j \leq k$ , and  $s$  is the arclength parameter of the path  $\mathbf{x}$ .

**Theorem** Let  $\mathbf{x} : [a, b] \rightarrow \mathbb{R}^n$  be a smooth path and  $f$  be a function defined on the image of this path. Then

$$\int_{\mathbf{x}} f ds = \int_a^b f(\mathbf{x}(t)) \|\mathbf{x}'(t)\| dt.$$

$ds$  is referred to as the arclength element.

## Vector line integral

Vector line integral is an integral of a vector field over a smooth path. It is a scalar.

*Definition.* Let  $\mathbf{x} : [a, b] \rightarrow \mathbb{R}^n$  be a smooth path and  $\mathbf{F}$  be a vector field defined on the image of this path. Then 
$$\int_{\mathbf{x}} \mathbf{F} \cdot d\mathbf{s} = \int_a^b \mathbf{F}(\mathbf{x}(t)) \cdot \mathbf{x}'(t) dt.$$

Alternatively, the integral of  $\mathbf{F}$  over  $\mathbf{x}$  can be represented as the integral of a **differential form**

$$\int_{\mathbf{x}} F_1 dx_1 + F_2 dx_2 + \cdots + F_n dx_n,$$

where  $\mathbf{F} = (F_1, F_2, \dots, F_n)$  and  $dx_i = x_i'(t) dt$ .

## Applications of line integrals

- Mass of a wire

If  $f$  is the density on a wire  $C$ , then  $\int_C f \, ds$  is the mass of  $C$ .

- Work of a force

If  $\mathbf{F}$  is a force field, then  $\int_{\mathbf{x}} \mathbf{F} \cdot d\mathbf{s}$  is the work done by  $\mathbf{F}$  on a particle that moves along the path  $\mathbf{x}$ .

- Circulation of fluid

If  $\mathbf{F}$  is the velocity field of a planar fluid, then the circulation of the fluid across a closed curve  $C$  is  $\oint_C \mathbf{F} \cdot d\mathbf{s}$ .

- Flux of fluid

If  $\mathbf{F}$  is the velocity field of a planar fluid, then the flux of the fluid across a closed curve  $C$  is  $\oint_C \mathbf{F} \cdot \mathbf{n} \, ds$ , where  $\mathbf{n}$  is the outward unit normal vector to  $C$ .

## Line integrals and reparametrization

Given a path  $\mathbf{x} : [a, b] \rightarrow \mathbb{R}^n$ , we say that another path  $\mathbf{y} : [c, d] \rightarrow \mathbb{R}^n$  is a **reparametrization** of  $\mathbf{x}$  if there exists a continuous invertible function  $u : [c, d] \rightarrow [a, b]$  such that  $\mathbf{y}(t) = \mathbf{x}(u(t))$  for all  $t \in [c, d]$ .

The reparametrization may be orientation-preserving (when  $u$  is increasing) or orientation-reversing (when  $u$  is decreasing).

**Theorem 1** Any scalar line integral is invariant under reparametrizations.

**Theorem 2** Any vector line integral is invariant under orientation-preserving reparametrizations and changes its sign under orientation-reversing reparametrizations.

As a consequence, we can define the integral of a function over a simple curve and the integral of a vector field over a simple oriented curve.

## Green's Theorem

**Theorem** Let  $D \subset \mathbb{R}^2$  be a closed, bounded region with piecewise smooth boundary  $\partial D$  oriented so that  $D$  is on the left as one traverses  $\partial D$ . Then for any smooth vector field  $\mathbf{F} = (M, N)$  on  $D$ ,

$$\oint_{\partial D} \mathbf{F} \cdot d\mathbf{s} = \iint_D \left( \frac{\partial N}{\partial x} - \frac{\partial M}{\partial y} \right) dx dy$$

or, equivalently,

$$\oint_{\partial D} M dx + N dy = \iint_D \left( \frac{\partial N}{\partial x} - \frac{\partial M}{\partial y} \right) dx dy.$$

## Examples

Consider vector fields  $\mathbf{F}(x, y) = (-y, 0)$ ,  
 $\mathbf{G}(x, y) = (0, x)$ , and  $\mathbf{H}(x, y) = (y, x)$ .

According to Green's Theorem,

$$\oint_{\partial D} -y \, dx = \iint_D 1 \, dx \, dy = \text{area}(D),$$

$$\oint_{\partial D} x \, dy = \iint_D 1 \, dx \, dy = \text{area}(D),$$

$$\oint_{\partial D} y \, dx + x \, dy = \iint_D 0 \, dx \, dy = 0.$$



## Green's Theorem

*Proof in the case*  $D = [0, 1] \times [0, 1]$  *and*  $\mathbf{F} = (0, N)$ :

$$\int_0^1 \frac{\partial N}{\partial x}(\xi, y) d\xi = N(1, y) - N(0, y)$$

for any  $y \in [0, 1]$  due to the Fundamental Theorem of Calculus. Integrating this equality by  $y$  over  $[0, 1]$ , we obtain

$$\iint_D \frac{\partial N}{\partial x} dx dy = \int_0^1 N(1, y) dy - \int_0^1 N(0, y) dy.$$

Let  $P_1 = (0, 0)$ ,  $P_2 = (1, 0)$ ,  $P_3 = (1, 1)$ , and  $P_4 = (0, 1)$ . The first integral in the right-hand side equals the vector integral of the field  $\mathbf{F}$  over the segment  $P_2P_3$ . The second integral equals the integral of  $\mathbf{F}$  over the segment  $P_1P_4$ . Also, the integral of  $\mathbf{F}$  over any horizontal segment is 0. It follows that the entire right-hand side equals the integral of  $\mathbf{F}$  over the broken line  $P_1P_2P_3P_4P_1$ , that is, over  $\partial D$ .

## Divergence Theorem

**Theorem** Let  $D \subset \mathbb{R}^2$  be a closed, bounded region with piecewise smooth boundary  $\partial D$  oriented so that  $D$  is on the left as one traverses  $\partial D$ . Then for any smooth vector field  $\mathbf{F}$  on  $D$ ,

$$\oint_{\partial D} \mathbf{F} \cdot \mathbf{n} \, ds = \iint_D \nabla \cdot \mathbf{F} \, dA.$$

*Proof:* Let  $\mathcal{L}$  denote the rotation of the plane  $\mathbb{R}^2$  by  $90^\circ$  about the origin (counterclockwise).  $\mathcal{L}$  is a linear transformation preserving the dot product. Therefore

$$\oint_{\partial D} \mathbf{F} \cdot \mathbf{n} \, ds = \oint_{\partial D} \mathcal{L}(\mathbf{F}) \cdot \mathcal{L}(\mathbf{n}) \, ds.$$

Note that  $\mathcal{L}(\mathbf{n})$  is the unit tangent vector to  $\partial D$ . It follows that the right-hand side is the vector integral of  $\mathcal{L}(\mathbf{F})$  over  $\partial D$ . If  $\mathbf{F} = (M, N)$  then  $\mathcal{L}(\mathbf{F}) = (-N, M)$ . By Green's Theorem,

$$\oint_{\partial D} \mathcal{L}(\mathbf{F}) \cdot d\mathbf{s} = \oint_{\partial D} -N \, dx + M \, dy = \iint_D \left( \frac{\partial M}{\partial x} + \frac{\partial N}{\partial y} \right) dx \, dy.$$