

MATH 323

Linear Algebra

Lecture 18a:

Similar matrices (continued).

Similarity of matrices

Definition. An $n \times n$ matrix B is said to be **similar** to an $n \times n$ matrix A if $B = S^{-1}AS$ for some nonsingular $n \times n$ matrix S .

Remark. Two $n \times n$ matrices are similar if and only if they represent the same linear operator on \mathbb{R}^n with respect to different bases.

Theorem Similarity is an *equivalence relation*, which means that

- (i) any square matrix A is similar to itself;
- (ii) if B is similar to A , then A is similar to B ;
- (iii) if A is similar to B and B is similar to C , then A is similar to C .

Corollary The set of $n \times n$ matrices is partitioned into disjoint subsets (called *similarity classes*) such that all matrices in the same subset are similar to each other while matrices from different subsets are never similar.

Theorem Similarity is an *equivalence relation*, i.e.,

- (i) any square matrix A is similar to itself;
- (ii) if B is similar to A , then A is similar to B ;
- (iii) if A is similar to B and B is similar to C , then A is similar to C .

Proof: (i) $A = I^{-1}AI$.

(ii) If $B = S^{-1}AS$ then $A = SBS^{-1} = (S^{-1})^{-1}BS^{-1} = S_1^{-1}BS_1$, where $S_1 = S^{-1}$.

(iii) If $A = S^{-1}BS$ and $B = T^{-1}CT$ then
 $A = S^{-1}(T^{-1}CT)S = (S^{-1}T^{-1})C(TS) = (TS)^{-1}C(TS) = S_2^{-1}CS_2$, where $S_2 = TS$.

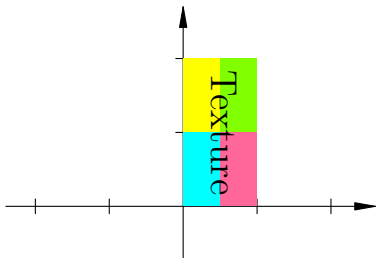
Theorem If A and B are similar matrices then they have the same (i) determinant, (ii) trace = the sum of diagonal entries, (iii) rank, and (iv) nullity.

Linear transformations of \mathbb{R}^2

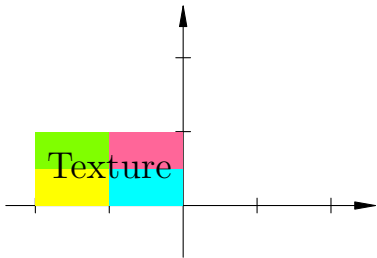
Any linear mapping $f : \mathbb{R}^2 \rightarrow \mathbb{R}^2$ is represented as multiplication of a 2-dimensional column vector by a 2×2 matrix: $f(\mathbf{x}) = A\mathbf{x}$ or

$$f \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} a & b \\ c & d \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix}.$$

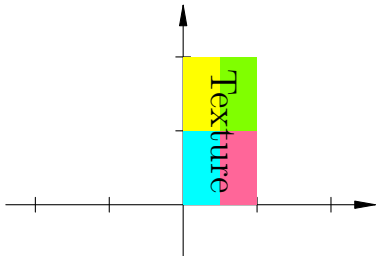
Linear transformations corresponding to particular matrices can have various geometric properties.



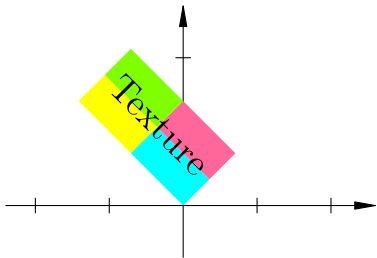
$$A = \begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix}$$



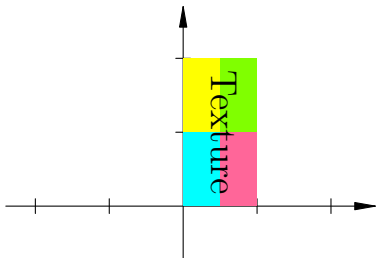
Rotation by 90°



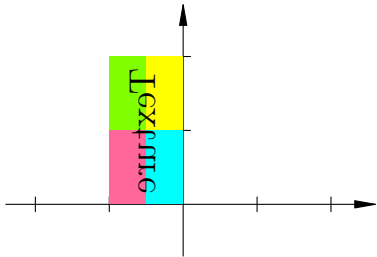
$$A = \begin{pmatrix} \frac{1}{\sqrt{2}} & -\frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \end{pmatrix}$$



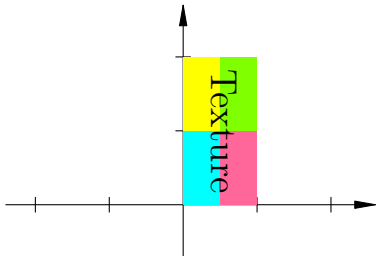
Rotation by 45°



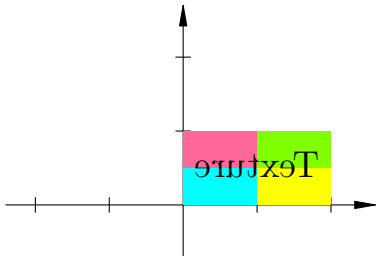
$$A = \begin{pmatrix} -1 & 0 \\ 0 & 1 \end{pmatrix}$$



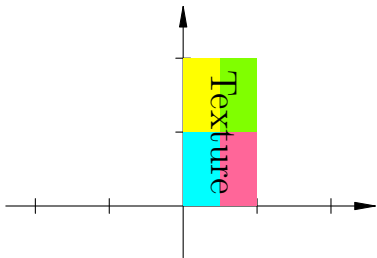
Reflection about
the vertical axis



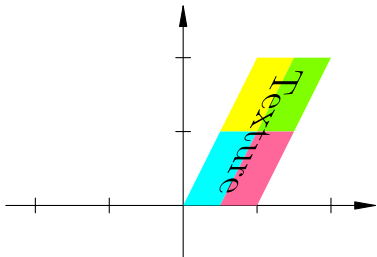
$$A = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}$$



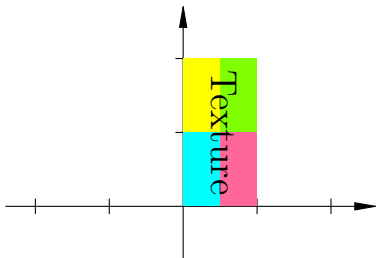
Reflection about
the line $x - y = 0$



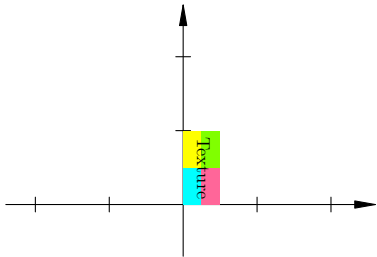
$$A = \begin{pmatrix} 1 & 1/2 \\ 0 & 1 \end{pmatrix}$$



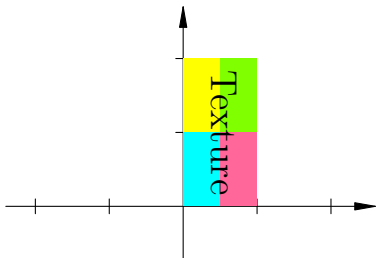
Horizontal shear



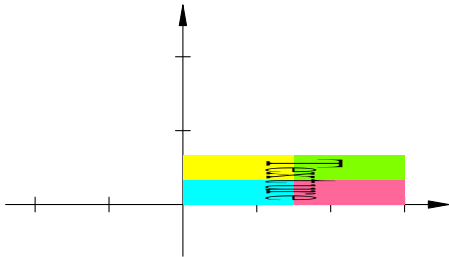
$$A = \begin{pmatrix} 1/2 & 0 \\ 0 & 1/2 \end{pmatrix}$$



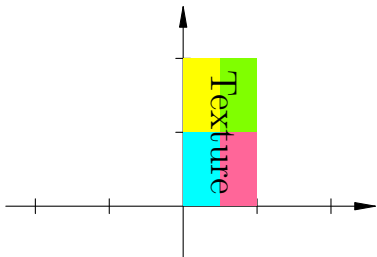
Scaling



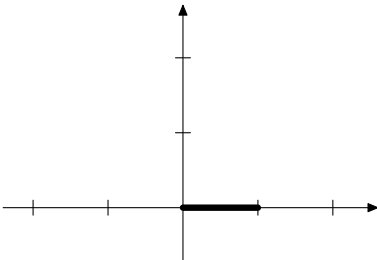
$$A = \begin{pmatrix} 3 & 0 \\ 0 & 1/3 \end{pmatrix}$$



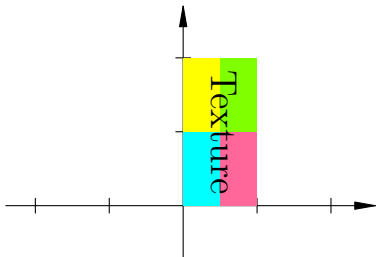
Squeeze



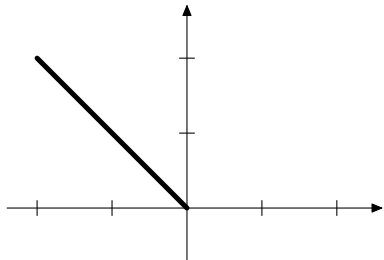
$$A = \begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix}$$



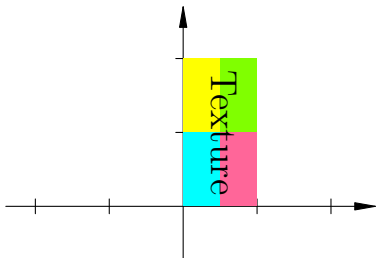
Vertical projection on
the horizontal axis



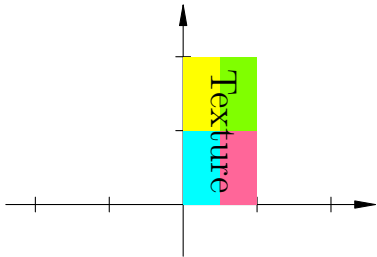
$$A = \begin{pmatrix} 0 & -1 \\ 0 & 1 \end{pmatrix}$$



Horizontal projection
on the line $x + y = 0$



$$A = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$$



Identity