

### Quiz 3: Solution

**Problem.** Let  $R$  denote a linear operator on  $\mathbb{R}^3$  that acts on vectors from the standard basis as follows:  $R(\mathbf{e}_1) = \mathbf{e}_3$ ,  $R(\mathbf{e}_2) = \mathbf{e}_1$ ,  $R(\mathbf{e}_3) = \mathbf{e}_2$ .

(i) Is  $R$  a rotation about an axis? Is  $R$  a reflection in a plane? Explain your answers.

(ii) If  $R$  is a rotation, find the axis and the angle. If  $R$  is a reflection, find the plane. If  $R$  is neither rotation nor reflection, describe the action of  $R$  in geometric terms.

The matrix of the operator  $R$  (relative to the standard basis) is

$$A = \begin{pmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 1 & 0 & 0 \end{pmatrix}.$$

This matrix is orthogonal. Therefore  $R$  is a rigid motion. According to the classification,  $R$  is either a rotation about an axis, or a reflection in a plane, or the composition of two. Since  $\det A = 1 > 0$ ,  $R$  is a rotation.

As  $R$  is a rotation about an axis, the matrix  $A$  is similar to

$$\begin{pmatrix} 1 & 0 & 0 \\ 0 & \cos \phi & -\sin \phi \\ 0 & \sin \phi & \cos \phi \end{pmatrix},$$

where  $\phi$  is the angle of rotation. Similar matrices have the same trace (since similar matrices have the same characteristic polynomial and the trace is one of its coefficients). The trace of  $A$  is 0. Hence  $1 + 2 \cos \phi = 0$ . Then  $\cos \phi = -1/2$  so that  $\phi = 2\pi/3$ .

The axis of the rotation  $R$  is the set of all points fixed by  $R$ . For any vector  $(x, y, z) \in \mathbb{R}^3$  we have

$$R(x, y, z) = R(x\mathbf{e}_1 + y\mathbf{e}_2 + z\mathbf{e}_3) = xR(\mathbf{e}_1) + yR(\mathbf{e}_2) + zR(\mathbf{e}_3) = x\mathbf{e}_3 + y\mathbf{e}_1 + z\mathbf{e}_2 = (y, z, x).$$

Therefore  $R(x, y, z) = (x, y, z)$  if and only if  $x = y = z$ . Thus the axis of the rotation is the line spanned by the vector  $(1, 1, 1)$ .