Section 16.7 Surface Integrals

Recall: If a smooth parametric surface S is given by the equation $\mathbf{r}(u,v)$ and S is covered just once as (u,v) ranges throughout the parametric domain D, then the **surface area** of S is

$$A(S) = \iint_{D} |\mathbf{r}_{u} \times \mathbf{r}_{v}| dA$$

Definition: Now suppose we want to integrate a function f(x,y,z) over a surface S defined by the equation $\mathbf{r}(u,v)$ and S is covered just once as (u,v) ranges throughout the parametric domain D, then the **surface** integral of f over S is

$$\iint_{S} \underline{f(x,y,z)} \, dS = \iint_{D} f(\mathbf{r}(u,v)) \underline{|\mathbf{r}_{u} \times \mathbf{r}_{v}|} \, dA$$

Example 1: Evaluate $\iint_S (x+y+z) dS$ where S is defined by $\mathbf{r}(u,v) = \langle u+v, u-v, 1+u+2v \rangle$, $0 \le u \le 1$ and $0 \le v \le 2$

$$\iint_{S} f(x,y,z) ds = \iint_{\Omega} f(r(u,v)) | r_{u,x} r_{v}| dA$$

$$\int_{0}^{1} \int_{0}^{2} \left(3u + u - v + 1 + u + 2v \right) \int_{1}^{1} dv du$$

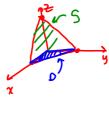
$$\int_{0}^{1} \int_{0}^{2} \left(3u + 2v + 1 \right) \int_{1}^{1} dv du$$

Example 1b: Set up but do not evaluate $\iint_S y dS$ where \underline{S} is the part of the plane $\underline{2x + u + z = 4}$ that lies in the first octant.

and
$$O = domain of \Gamma(u, v)$$
.

$$\frac{z=4-y-2x}{\int \int y ds} \int \int \frac{1}{x} x ds = \begin{vmatrix} i & j & k \\ i & 0 & -2 \\ 0 & 1 & -1 \end{vmatrix}$$

$$Z=4-y-2x$$
D in the plane, set $Z=0$



Example 2: Evaluate $\iint_S (x+2y+z) dS$ where \underline{S} is the part of the plane $\underline{y+z=4}$ that is inside the cylinder $\underline{x}^2+y^2=1$.

cylinder
$$x^{2}+y^{2}=1$$
.

$$\iint_{S} f(x, y, z) ds = \iint_{S} f(r(y, y)) | r_{y} \times r_{y}| dA$$

$$\int_{X=X} | y=y | r_{y}| | r_$$

Example 3: Evaluate
$$\iint_{S} u^{2} dS$$
 where S is the part of the cone $y = \sqrt{x^{2} + 2^{2}}$, with $0 \le y \le 2$

$$\iint_{S} f(\lambda, y, 2) dS = \iint_{S} f(\Gamma(u, y^{-1})) \left[\int_{U} u^{2} v^{-1} \right] dA$$

$$I(\lambda, 2) = \left(\frac{\lambda}{\lambda} \right) \left[\frac{\lambda}{\lambda} \right] \left[\frac{\lambda}{\lambda} \right$$

Example 4: Set up but do not evaluate
$$\iint_{S} (y^{2}+z^{2}) dS \text{ where } S \text{ is part of the paraboloid } x = 4-y^{2}-z^{2}$$
that lies in front of the plane $x = 0$.

$$(y, z) = \langle 4-y^{2}-z^{2}, y, z \rangle$$

$$(y, z) = \langle 4-y^{2}-z^{$$

Recall from spherical coordinates, we can parameterize a sphere as $x = \rho \sin \phi \cos \theta$, $y = \rho \sin \phi \sin \theta$ and $z = \rho \cos \phi$. Thus $r(\theta, \phi) = \langle \rho \sin \phi \cos \theta, \rho \sin \phi \sin \theta, \rho \cos \phi \rangle$. Then

$$\mathbf{r}_{\phi} \times \mathbf{r}_{\theta} = \left\langle \rho^2 \sin^2 \phi \cos \theta, \rho^2 \sin^2 \phi \sin \theta, \rho^2 \sin \phi \cos \phi \right\rangle$$

and

$$|\mathbf{r}_{\theta} \times \mathbf{r}_{\phi}| = \rho^2 \sin(\phi)$$

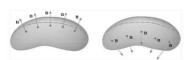
Example 5: Evaluate
$$\iint_S z dS$$
, where S is the part of the sphere $x^2 + y^2 + z^2 = 16$ that lies between the planes $z = 2$ and $z = 2\sqrt{3}$

here, $\nabla = 4$
 $D = 0 = 2\pi$
 $D = 0 =$

Surface Integrals through Vector Fields

Here, we study surfaces in vector fields. Since surfaces are two sided, we must have an orientation of the surface. The normal vectors to the surface provide the orientation, but since there are two normal vectors to a surface, we need a convention. The usual orientation we choose is the upward orientation. If the problem does not state the orientation, assume positive (upward). If the problem states upward orientation, we want the normal to have a positive ${\bf k}$ component. If the problem states downward orientation, we want the normal to have a negative ${\bf k}$ component. For closed surfaces, the convention is to have the normal vectors that point outward from the surface, called positive orientation.

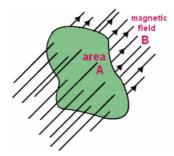
The two orientations of an orientable surface



Positive orientation



Definition: Suppose $\mathbf{F} = \langle P, Q, R \rangle$ is a vector field that contains surface S. The amount of flow that passes through the surface S is called the **Flux** of **F** across the surface S. In other words, the flux of **F** describes the flow at any point across the surface. If \mathbf{n} is a unit normal vector to the surface at any point on S, notice that \mathbf{n} 'passes through' the surface S.



Definition: Let $F = \langle P, Q, R \rangle$ be a vector field whose domain includes a surface S where S is defined parametrically by $\mathbf{r}(u, v)$. Then the **Flux** of **F** over S is

$$\iiint_{S} \mathbf{F} \cdot d\mathbf{S} = \iint_{S} \mathbf{F} \cdot \mathbf{n} \, dS = \iiint_{D} \mathbf{F}(\mathbf{r}(u, v)) \cdot (\mathbf{r}_{u} \times \mathbf{r}_{v}) \, dA$$

Example 6: Evaluate
$$\iint_{S} \mathbf{F} \cdot d\mathbf{S}$$
 where $\mathbf{F} = \langle y, 2z, x \rangle$ and S is defined by $\mathbf{r}(u, v) = \langle 3u + v, u - 2v, 3 - u + v \rangle$ and $0 \le u \le 1, 0 \le v \le 1$. Assume positive (upward) orientation.

$$\iint_{S} \mathbf{F} \cdot d\mathbf{S} = \iint_{S} \mathbf{F} \left(\mathbf{r}(u, v) \right) \cdot \left(\mathbf{r}_{u} \times \mathbf{r}_{v} \right) dA$$

$$\lim_{S \to \infty} \mathbf{r}_{v} = \begin{bmatrix} \mathbf{i} & \mathbf{j} & \mathbf{j} & \mathbf{j} \\ \mathbf{j} & \mathbf{j} & \mathbf{j} & \mathbf{j} & \mathbf{j} \\ \mathbf{j} & \mathbf{j} & \mathbf{j} & \mathbf{j} & \mathbf{j} \\ \mathbf{j} & \mathbf{j} & \mathbf{j} & \mathbf{j} & \mathbf{j} & \mathbf{j} \\ \mathbf{j} & \mathbf{j} & \mathbf{j} & \mathbf{j} & \mathbf{j} & \mathbf{j} \\ \mathbf{j} & \mathbf{j} & \mathbf{j} & \mathbf{j} & \mathbf{j} & \mathbf{j} \\ \mathbf{j} & \mathbf{j} & \mathbf{j} & \mathbf{j} & \mathbf{j} & \mathbf{j} \\ \mathbf{j} & \mathbf{j} & \mathbf{j} & \mathbf{j} & \mathbf{j} & \mathbf{j} \\ \mathbf{j} & \mathbf{j} & \mathbf{j} & \mathbf{j} & \mathbf{j} & \mathbf{j} & \mathbf{j} \\ \mathbf{j} & \mathbf{j} & \mathbf{j} & \mathbf{j} & \mathbf{j} & \mathbf{j} & \mathbf{j} \\ \mathbf{j} & \mathbf{j} & \mathbf{j} & \mathbf{j} & \mathbf{j} & \mathbf{j} & \mathbf{j} \\ \mathbf{j} & \mathbf{j} & \mathbf{j} & \mathbf{j} & \mathbf{j} & \mathbf{j} & \mathbf{j} \\ \mathbf{j} & \mathbf{j} \\ \mathbf{j} & \mathbf{j} \\ \mathbf{j} & \mathbf{j} \\ \mathbf{j} & \mathbf{j} \\ \mathbf{j} & \mathbf{j} \\ \mathbf{j} & \mathbf{j} \\ \mathbf{j} & \mathbf{j} \\ \mathbf{j} & \mathbf{j} \\ \mathbf{j} & \mathbf{j} \\ \mathbf{j} & \mathbf{j} \\ \mathbf{j} & \mathbf{j} &$$

Example 7: Find the flux of
$$F = \langle x, y, z \rangle$$
 where S is part of the surface $z = 1 - x^2 - y^2$ above the xy -plane. Assume positive (upward) orientation.

Flux $F = \iint_S F \cdot dS$

Parameter $I \neq z \in S$:

$$((x, y) = \langle x, y, 1 - x^2 - y^2 \rangle)$$

$$(x \neq y) = \langle x, y, 1 - x^2 - y^2 \rangle$$

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Section 16.7 (continued)

secol: Let S be a surface parameterized by (14,
$$\tau$$
), where 0 is the domain of (4, τ). Then

If (x, y, z) $dS = \iint_S F(x(u, \tau)) \Big|_{C_0 \in C_1} dA$

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If (x, y, z) dA

If (x, y, z) (x, z) $(x$