# Highlights

Math 304 Linear Algebra

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From last time:

- The determinant tells whether a matrix is invertible.
- One way to compute a determinant: use row operations.
- Another way to compute a determinant: use cofactor expansion.

Today:

Vector spaces and subspaces: definitions and examples.

# Definition and first examples of vector spaces

A *vector space* is a set of mathematical objects equipped with two operations: addition and multiplication by scalars (for us, usually the real numbers) satisfying the usual commutative, associative, and distributive laws. There should be an additive identity element **0**, and each element should have an additive inverse, and the scalar 1 should be a multiplicative identity.

The formal axioms are listed in the textbook on page 119.

#### Basic examples.

- ▶ the Euclidean plane R<sup>2</sup>
- ► Euclidean 3-space R<sup>3</sup>
- ► Euclidean *n*-space *R<sup>n</sup>*
- the space of  $m \times n$  matrices  $R^{m \times n}$

## More examples: function spaces

- ► The set *P* of all polynomials is a vector space. In this space, "vectors" are objects like  $x^8 + \frac{5}{2}x^4 7x + \sqrt{3}$ .
- Fix a counting number n. The set P<sub>n</sub> of all polynomials with degree less than n is a vector space. This example is a subspace of the preceding space.
- ► Fix a closed interval [a, b]. The set C[a, b] of all continuous functions on the interval is a vector space. In this space, "vectors" are objects like 5e<sup>x</sup> + |x| cos(x).
- The set C<sup>2</sup>[a, b] of all functions with a continuous second derivative is a vector space. This example is a subspace of the preceding space.

### Examples that fail to be vector spaces

- ► The set of polynomials of degree 2 is not a vector space. Not closed under addition:  $(1 + x^2) + (x - x^2) = (1 + x)$ ; the degree does not stay equal to 2. Also, the set lacks an additive identity element, because the polynomial 0 does not have degree 2.
- ► The set of polynomials with integral coefficients is not a vector space. The set is not closed under scalar multiplication; for instance, multiplication by √2 does not preserve the set.
- ► The set of solutions of the differential equation y" + 5y' + 4y = sin(x) is not a vector space. Not closed under addition: the sum of two solutions satisfies the equation y" + 5y' + 4y = 2 sin(x).

In general, a sub**set** of a vector space is a sub**space** if and only if it is closed under both addition and scalar multiplication.

# Nullspace of a matrix

If *A* is an  $m \times n$  matrix, then the *nullspace* N(A) is the set of vectors **x** in  $\mathbb{R}^n$  such that  $A\mathbf{x} = \mathbf{0}$ .

The nullspace is always a subspace of  $R^n$ .

**Example** (#4b, p. 132).  $A = \begin{pmatrix} 1 & 2 & -3 & -1 \\ -2 & -4 & 6 & 3 \end{pmatrix}$ . Find N(A). To solve  $A\mathbf{x} = \mathbf{0}$ , row reduce the augmented matrix:

 $\begin{pmatrix} 1 & 2 & -3 & -1 & | & 0 \\ -2 & -4 & 6 & 3 & | & 0 \end{pmatrix} \xrightarrow{R_2 + 2R_1} \begin{pmatrix} 1 & 2 & -3 & -1 & | & 0 \\ 0 & 0 & 0 & 1 & | & 0 \end{pmatrix}$ 

So  $x_4 = 0$ ,  $x_2$  and  $x_3$  are free variables, and  $x_1 = -2x_2 + 3x_3$ . The null space consists of all linear combinations of the vectors

 $\begin{pmatrix} -2\\1\\0\\0 \end{pmatrix}$  and  $\begin{pmatrix} 3\\0\\1\\0 \end{pmatrix}$ , the so-called *span* of those vectors.

# Spanning sets Example: exercise 11, page 133 Which of the vectors $\begin{pmatrix} 2\\6\\6 \end{pmatrix}$ and $\begin{pmatrix} -9\\-2\\5 \end{pmatrix}$ is in the span of the vectors $\begin{pmatrix} -1\\2\\3 \end{pmatrix}$ and $\begin{pmatrix} 3\\4\\2 \end{pmatrix}$ ? Restatement: Is the system $x_1 \begin{pmatrix} -1\\2\\3 \end{pmatrix} + x_2 \begin{pmatrix} 3\\4\\2 \end{pmatrix} = \begin{pmatrix} 2\\6\\6 \end{pmatrix}$ consistent? Is the system $x_1 \begin{pmatrix} -1\\2\\3 \end{pmatrix} + x_2 \begin{pmatrix} 3\\4\\2 \end{pmatrix} = \begin{pmatrix} -9\\-2\\5 \end{pmatrix}$ consistent? Use row operations to find out.

# Exercise 11 continued

$$\begin{pmatrix} -1 & 3 & | & -9 \\ 2 & 4 & | & -2 \\ 3 & 2 & | & 5 \end{pmatrix} \xrightarrow{R_2 + 2R_1} \begin{pmatrix} -1 & 3 & | & -9 \\ 0 & 10 & | & -20 \\ 0 & 11 & | & -22 \end{pmatrix} \xrightarrow{R_2/10} \begin{pmatrix} -1 & 3 & | & -9 \\ 0 & 1 & | & -2 \\ 0 & 11 & | & -22 \end{pmatrix}$$
$$\xrightarrow{R_3 - 11R_2} \begin{pmatrix} -1 & 3 & | & -9 \\ 0 & 11 & | & -2 \\ 0 & 0 & | & 0 \end{pmatrix} \quad \text{ consistent.}$$