Highlights

Math 304 Linear Algebra

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June 13, 2006

From last time:

- row space and column space
- the rank-nullity property

Today:

examples of linear transformations

What is a linear transformation?

Matrix multiplication preserves linear combinations, namely,

 $A(\mathbf{x} + \mathbf{y}) = A(\mathbf{x}) + A(\mathbf{y})$, and $A(c\mathbf{x}) = cA(\mathbf{x})$ for every scalar *c*.

Any mapping/function/transformation/operator from one vector space to another is called *linear* if it satisfies the same two properties.

Examples of linear transformations

- Geometric examples in R² or R³: dilation, rotation, reflection, projection
- Examples in spaces of functions: differentiation, integration, point evaluation
- Examples in the space of matrices: taking the transpose, taking the *trace* (the sum of the numbers on the main diagonal)

Non-examples of linear transformations

- Geometric: translation
- Function spaces: squaring a function
- Matrices: taking the inverse

Subspaces associated to a linear transformation

Suppose $L: V \to W$ is a linear transformation from one vector space V to another vector space W.

• The *kernel* of *L* is the set of vectors \mathbf{v} in *V* such that $L(\mathbf{v}) = \mathbf{0}$.

Example: If $L: P_5 \to R$ is defined by L(p) = p(0), then the kernel of *L* is the set of polynomials with constant term 0. The kernel is essentially the same concept as the nullspace of a matrix.

The kernel is always a subspace of V.

L is *one-to-one* (or *injective*) if $ker(L) = \{\mathbf{0}\}$.

The range L(V) is the set of all vectors w in W such that w = L(v) for some v in V.

Example: If $L: P_5 \rightarrow P_5$ is differentiation, then the range of *L* is P_4 .

The range is always a subspace of W. The range is analogous to the column space of a matrix.

L is onto (or surjective) if L(V) = W.