Highlights

Math 304 Linear Algebra

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From last time:

Gram-Schmidt orthonormalization process and QR factorization

Today:

eigenvalues and eigenvectors

Example

The matrix $A = \begin{pmatrix} 2 & 1 \\ 0 & 3 \end{pmatrix}$ defines a linear transformation of R^2 that is easy to understand. The transformation stretches the vector $\mathbf{u}_1 = \begin{pmatrix} 1 \\ 0 \end{pmatrix}$ by a factor of 2 and stretches the vector $\mathbf{u}_2 = \begin{pmatrix} 1 \\ 1 \end{pmatrix}$ by a factor of 3.

³⁾ The vectors \mathbf{u}_1 and \mathbf{u}_2 are called *eigenvectors*, and the scale factors 2 and 3 are the corresponding *eigenvalues*.

The transformation is particularly simple to describe in the basis $[\mathbf{u}_1, \mathbf{u}_2]$: namely, the matrix $U^{-1}AU$ is the diagonal matrix $\begin{pmatrix} 2 & 0 \\ 0 & 3 \end{pmatrix}$.

Computing eigenvectors

Example. The matrix $A = \begin{pmatrix} 12 & 4 & -5 \\ -8 & 0 & 5 \\ 10 & 4 & -3 \end{pmatrix}$ has 3 as one of its eigenvalues. Find a corresponding eigenvector

eigenvalues. Find a corresponding eigenvector.

Solution. We seek a vector **v** such that $A\mathbf{v} = 3\mathbf{v}$. Equivalently, **v** should be in the nullspace of the matrix A - 3I (I =identity). Find the nullspace by row reduction:

$$\begin{pmatrix} 9 & 4 & -5 & | & 0 \\ -8 & -3 & 5 & | & 0 \\ 10 & 4 & -6 & | & 0 \end{pmatrix} \xrightarrow{R_1 \to R_1 + R_2} \begin{pmatrix} 1 & 1 & 0 & | & 0 \\ -8 & -3 & 5 & | & 0 \\ 10 & 4 & -6 & | & 0 \end{pmatrix}$$

$$\xrightarrow{R_2 \to R_2 + 8R_1}_{R_3 \to R_3 - 10R_1} \begin{pmatrix} 1 & 1 & 0 & | & 0 \\ 0 & 5 & 5 & | & 0 \\ 0 & -6 & -6 & | & 0 \end{pmatrix} \xrightarrow{\text{three}}_{\text{steps}} \begin{pmatrix} 1 & 0 & -1 & | & 0 \\ 0 & 1 & 1 & | & 0 \\ 0 & 0 & 0 & | & 0 \end{pmatrix}.$$

Thus $\mathbf{v} = (1, -1, 1)^T$ is an eigenvector with eigenvalue 3.

Computing eigenvalues

Example. The matrix $A = \begin{pmatrix} 12 & 4 & -5 \\ -8 & 0 & 5 \\ 10 & 4 & -3 \end{pmatrix}$ has other

eigenvalues besides the number 3. Find them.

Solution. The condition for a number λ to be an eigenvalue of *A* is that the matrix $A - \lambda I$ have a non-trivial nullspace. Equivalently, det $(A - \lambda I) = 0$, the *characteristic equation*:

$$0 = \begin{vmatrix} 12 - \lambda & 4 & -5 \\ -8 & 0 - \lambda & 5 \\ 10 & 4 & -3 - \lambda \end{vmatrix} \begin{vmatrix} R_{1} \rightarrow \\ = \\ R_{1} + R_{2} \end{vmatrix} \begin{vmatrix} 4 - \lambda & 4 - \lambda & 0 \\ -8 & -\lambda & 5 \\ 10 & 4 & -3 - \lambda \end{vmatrix}$$
$$\begin{vmatrix} C_{2} \rightarrow \\ = \\ C_{2} - C_{1} \end{vmatrix} \begin{vmatrix} 4 - \lambda & 0 & 0 \\ -8 & 8 - \lambda & 5 \\ 10 & -6 & -3 - \lambda \end{vmatrix} = (4 - \lambda) \begin{vmatrix} 8 - \lambda & 5 \\ -6 & -3 - \lambda \end{vmatrix}$$
$$= (4 - \lambda)(\lambda^{2} - 5\lambda + 6) = (4 - \lambda)(\lambda - 3)(\lambda - 2).$$

Therefore the eigenvalues of *A* are 4, 3, and 2.

Eigenvalues and similarity

If *A* and *B* are similar matrices ($B = S^{-1}AS$), then *A* and *B* have the same eigen*values* (but not the same eigen*vectors*). Here's why. If $A\mathbf{v} = \lambda \mathbf{v}$, then $B\mathbf{w} = \lambda \mathbf{w}$ with $\mathbf{w} = S^{-1}\mathbf{v}$. In fact, $B\mathbf{w} = (S^{-1}AS)(S^{-1}\mathbf{v}) = S^{-1}A\mathbf{v} = S^{-1}\lambda\mathbf{v} = \lambda\mathbf{w}$. **Example.** Since the matrix $A = \begin{pmatrix} 12 & 4 & -5 \\ -8 & 0 & 5 \\ 10 & 4 & -3 \end{pmatrix}$ has eigenvalues 4, 3, and 2, the matrix *A* is similar to a diagonal matrix $\begin{pmatrix} 4 & 0 & 0 \\ 0 & 3 & 0 \\ 0 & 0 & 2 \end{pmatrix}$. Similar matrices have equal determinants, so det(*A*) = 24 (the product of the eigenvalues). Similar matrices have equal traces too, and indeed 12 + 0 - 3 = 4 + 3 + 2.