

NEW LOWER BOUNDS FOR THE RANK OF MATRIX MULTIPLICATION*

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Abstract. The rank of the matrix multiplication operator for $\mathbf{n} \times \mathbf{n}$ matrices is one of the most studied quantities in algebraic complexity theory. I prove that the rank is at least $3\mathbf{n}^2 - o(\mathbf{n}^2)$. More precisely, for any integer $p \leq \mathbf{n} - 1$ the rank is at least $(3 - \frac{1}{p+1})\mathbf{n}^2 - (1 + 2p\binom{2p}{p-1})\mathbf{n}$. The previous lower bound, due to Bläser, was $\frac{5}{2}\mathbf{n}^2 - 3\mathbf{n}$ (the case $p = 1$). The new bounds improve Bläser’s bound for all $\mathbf{n} > 84$. I also prove lower bounds for rectangular matrices that are significantly better than the previous bound.

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1. Introduction. Let $X = (x_j^i)$, $Y = (y_j^i)$ be $\mathbf{n} \times \mathbf{n}$ matrices with indeterminate entries. The *rank* of matrix multiplication, denoted $\mathbf{R}(M_{(\mathbf{n},\mathbf{n},\mathbf{n})})$, is the smallest number r of products $p_\rho = u_\rho(X)v_\rho(Y)$, $1 \leq \rho \leq r$, where u_ρ, v_ρ are linear forms, such that the entries of the matrix product XY are contained in the linear span of the p_ρ . This quantity is also called the bilinear complexity of $\mathbf{n} \times \mathbf{n}$ matrix multiplication. More generally, one may define the rank $\mathbf{R}(b)$ of any bilinear map b ; see section 2.

From the point of view of geometry, rank is badly behaved as it is not semicontinuous. Geometers usually prefer to work with the *border rank* of matrix multiplication, which fixes the semicontinuity problem by fiat: the border rank of a bilinear map b , denoted $\underline{\mathbf{R}}(b)$, is the smallest r such that b can be approximated to arbitrary precision by bilinear maps of rank r . By definition, one has $\mathbf{R}(b) \geq \underline{\mathbf{R}}(b)$. A more formal definition is given in section 2.

Let $M_{(\mathbf{n},\mathbf{m},\mathbf{l})}$ denote the multiplication of an $\mathbf{n} \times \mathbf{m}$ matrix by an $\mathbf{m} \times \mathbf{l}$ matrix. In [5] G. Ottaviani and I gave new lower bounds for the border rank of matrix multiplication; namely, for all $p \leq \mathbf{n} - 1$, $\underline{\mathbf{R}}(M_{(\mathbf{n},\mathbf{n},\mathbf{m})}) \geq \frac{2p+1}{p+1}\mathbf{nm}$. Taking $p = \mathbf{n} - 1$ gives the bound $\underline{\mathbf{R}}(M_{(\mathbf{n},\mathbf{n},\mathbf{m})}) \geq 2\mathbf{nm} - \mathbf{m}$. In this paper it will be advantageous to work with a smaller value of p . The results of [5] are used here to prove the following theorem.

THEOREM 1.1. *Let $p \leq \mathbf{n} - 1$ be a natural number. Then*

$$\mathbf{R}(M_{(\mathbf{n},\mathbf{n},\mathbf{m})}) \geq \frac{2p+1}{p+1}\mathbf{nm} + \mathbf{n}^2 - \left(1 + 2p\binom{2p}{p-1}\right)\mathbf{n}.$$

The previous bound, due to M. Bläser [2], was $\mathbf{R}(M_{(\mathbf{n},\mathbf{n},\mathbf{m})}) \geq 2\mathbf{nm} - \mathbf{m} + 2\mathbf{n} - 2$. For square matrices Theorem 1.1 specializes to the following theorem.

THEOREM 1.2. *Let $p \leq \mathbf{n} - 1$ be a natural number. Then*

$$\mathbf{R}(M_{(\mathbf{n},\mathbf{n},\mathbf{n})}) \geq \left(3 - \frac{1}{p+1}\right)\mathbf{n}^2 - \left(1 + 2p\binom{2p}{p-1}\right)\mathbf{n}.$$

In particular, $\mathbf{R}(M_{(\mathbf{n},\mathbf{n},\mathbf{n})}) \geq 3\mathbf{n}^2 - o(\mathbf{n}^2)$.

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The “in particular” sentence follows by setting, e.g., $p = \lfloor \sqrt{\log(\mathbf{n})} \rfloor$.

This improves Bläser’s bound [1] of $\frac{5}{2}\mathbf{n}^2 - 3\mathbf{n}$ (the case $p = 1$) for all $\mathbf{n} > 84$. Working under my direction, Massarenti and Raviolo [8, 7] improved the error term in Theorem 1.2. In a preprint of this article I made a mistake in computing the error term. Unfortunately this mistake was not noticed before Massarenti and Raviolo’s paper [8], which repeated the error, was published, although their contribution is completely correct, and their correct bound will appear in [7].

Remark 1.3. If T is a tensor of border rank r , where the approximating curve of rank r tensors limits in such a way that q derivatives of the curve are used, then the rank of T is at most $(2q - 1)r$; see [3, Prop. 15.26]. In [6] the authors give explicit, but very large, upper bounds on the order of approximation h needed to write a tensor of border rank r as lying in the h -jet of a curve of tensors of rank r .

The language of tensors will be used throughout. In section 2 the language of tensors is introduced, and previous work of Bläser and others is rephrased in a language suitable for generalizations. In section 3 I describe the equations of [5] and give a very easy proof of a slightly weaker result than Theorem 1.1. In section 4 I express the equations in coordinates and prove Theorem 1.1. I work over the complex numbers throughout.

2. Ranks and border ranks of tensors. Let A, B, C be vector spaces of dimensions $\mathbf{a}, \mathbf{b}, \mathbf{c}$ and with dual spaces A^*, B^*, C^* . That is, A^* is the space of linear maps $A \rightarrow \mathbb{C}$. Write $A^* \otimes B$ for the space of linear maps $A \rightarrow B$ and $A^* \otimes B^* \otimes C$ for the space of bilinear maps $A \times B \rightarrow C$. To avoid extra $*$ ’s, I work with bilinear maps $A^* \times B^* \rightarrow C$, i.e., elements of $A \otimes B \otimes C$. Let $T : A^* \times B^* \rightarrow C$ be a bilinear map. One may also consider T as a linear map $T : A^* \rightarrow B \otimes C$ (and similarly with the roles of A, B, C exchanged) or as a trilinear map $A^* \times B^* \times C^* \rightarrow \mathbb{C}$.

The *rank* of a bilinear map $T : A^* \times B^* \rightarrow C$, denoted $\mathbf{R}(T)$, is the smallest r such that there exist $a_1, \dots, a_r \in A, b_1, \dots, b_r \in B, c_1, \dots, c_r \in C$ such that $T(\alpha, \beta) = \sum_{i=1}^r a_i(\alpha)b_i(\beta)c_i$ for all $\alpha \in A^*$ and $\beta \in B^*$. The *border rank* of T , denoted $\underline{\mathbf{R}}(T)$, is the smallest r such that T may be written as a limit of a sequence of rank r tensors. Since the set of tensors of border rank at most r is closed, one can use polynomials to obtain lower bounds on border rank. That is, let P be a polynomial on $A \otimes B \otimes C$ such that P vanishes on all tensors of border rank at most r : if $T \in A \otimes B \otimes C$ is such that $P(T) \neq 0$, then $\underline{\mathbf{R}}(T) > r$.

The following proposition is a rephrasing of part of the proof in [1].

PROPOSITION 2.1. *Let P be a polynomial of degree d on $A \otimes B \otimes C$ such that $P(T) \neq 0$ implies $\underline{\mathbf{R}}(T) > r$. Let $T \in A \otimes B \otimes C$ be a tensor such that $P(T) \neq 0$ and $T : A^* \rightarrow B \otimes C$ is injective. Then $\mathbf{R}(T) \geq r + \mathbf{a} - d$.*

As stated, the proposition is useless, as the degrees of polynomials vanishing on all tensors of border rank at most r are greater than r . (A general tensor of border rank r also has rank r .) However, the conclusion still holds if one can find, for a given tensor T , a polynomial, or collection of polynomials on smaller spaces, such that the nonvanishing of P on T is equivalent to the nonvanishing of the new polynomials. Then one substitutes the smaller degree into the statement to obtain the nontrivial lower bound.

In our situation, first I will show $P(M_{(\mathbf{n}, \mathbf{n}, \mathbf{m})}) \neq 0$ if and only if $\tilde{P}(\tilde{M}) \neq 0$, where \tilde{M} is a tensor in a smaller space of tensors and \tilde{P} is a polynomial of lower degree than P ; see (2). More precisely, note that in the course of the proof, $B \otimes C$ does not play a role, and we will see that the relevant polynomial, when applied to matrix multiplication $M \in A \otimes B \otimes C = A \otimes \mathbb{C}^{\mathbf{n}^2} \otimes \mathbb{C}^{\mathbf{n}^2}$, will not vanish if and only if a

polynomial \tilde{P} applied to $\tilde{M} \in A \otimes \mathbb{C}^{\mathbf{n}} \otimes \mathbb{C}^{\mathbf{n}}$ with $\deg(\tilde{P}) = \deg(P)/\mathbf{n}$ does not vanish, so the proof below works in this case. Then, in section 4, I show that $\tilde{P}(\tilde{M}) \neq 0$ is implied by the nonvanishing of two polynomials of even smaller degrees.

This is why both Bläser’s result and the result of this paper improve the bound of border rank by $\mathbf{a} = \mathbf{n}^2$ minus an error term, where Bläser improves Strassen’s bound and I improve the bound of [5]. (Bläser shows Strassen’s equations for border rank, when applied to the matrix multiplication tensor, are equivalent to the nonvanishing of three polynomials of degree \mathbf{n} , hence the error term of $3\mathbf{n}$. See [4, section 11.5] for an exposition.)

To prove the proposition, we need a standard lemma, also used in [2], which appears in this form in [4, Lemma 11.5.0.2].

LEMMA 2.2. *Let $\mathbb{C}^{\mathbf{a}}$ be given a basis. Given a polynomial P of degree d on $\mathbb{C}^{\mathbf{a}}$, there exists a set of at most d basis vectors such that P restricted to their span is not identically zero.*

The lemma follows by simply choosing a monomial that appears in P , as it can involve at most d basis vectors.

Proof of Proposition 2.1. Let $\mathbf{R}(T) = r$, and assume we have written T as a sum of r rank one tensors. Since $T : A^* \rightarrow B \otimes C$ is injective, we may write $T = T' + T''$ with $\mathbf{R}(T') = \mathbf{a}$, $\mathbf{R}(T'') = r - \mathbf{a}$, and $T' : A^* \rightarrow B \otimes C$ injective. Now consider the \mathbf{a} elements of $A \otimes B \otimes C$ appearing in T' . Since they are linearly independent, by Lemma 2.2 we may choose a subset of d of them such that P , evaluated on the sum of terms in T whose A terms are in the span of these d elements, is not identically zero. Let T_1 denote the sum of the terms in T' not involving the (at most) d basis vectors needed for nonvanishing, so $\mathbf{R}(T_1) \geq \mathbf{a} - d$. Let $T_2 = T - T_1 + T''$. Now $\mathbf{R}(T_2) \geq r$ because $P(T_2) \neq 0$. Finally, $\mathbf{R}(T) = \mathbf{R}(T_1) + \mathbf{R}(T_2)$. \square

Let $G(k, V) \subset \mathbb{P}\Lambda^k V$ denote the Grassmannian of k -planes through the origin in V in its Plücker embedding. That is, if a k -plane is spanned by v_1, \dots, v_k , we write it as $[v_1 \wedge \dots \wedge v_k]$. One says a function on $G(k, V)$ is a polynomial of degree d if, as a function in the Plücker coordinates, it is a degree d polynomial. The Plücker coordinates (x_α^μ) , $k + 1 \leq \mu \leq \dim V = \mathbf{v}$, $1 \leq \alpha \leq k$, are obtained by choosing a basis $e_1, \dots, e_{\mathbf{v}}$ of V , centering the coordinates at $[e_1 \wedge \dots \wedge e_k]$, and writing a nearby k -plane as $[(e_1 + \sum x_1^\mu e_\mu) \wedge \dots \wedge (e_k + \sum x_k^\mu e_\mu)]$. If the polynomial is also homogeneous in the x_α^μ , this is equivalent to it being the restriction of a homogeneous degree d polynomial on $\Lambda^k V$. (The ambiguity of the scale does not matter as we are concerned only with its vanishing.)

LEMMA 2.3. *Let A be given a basis. Given a homogeneous polynomial of degree d on the Grassmannian $G(k, A)$, there exists at least dk basis vectors such that, denoting their (at most) dk -dimensional span by A' , P restricted to $G(k, A')$ is not identically zero.*

Proof. Consider the map $f : A^{\times k} \rightarrow G(k, A)$ given by $(a_1, \dots, a_k) \mapsto [a_1 \wedge \dots \wedge a_k]$. Then f is surjective. Take the polynomial P and pull it back by f . (The pullback $f^*(P)$ is defined by $f^*(P)(a_1, \dots, a_k) := P(f(a_1, \dots, a_k))$.) The pullback is of degree d in each copy of A . (That is, fixing $k - 1$ parameters, it becomes a degree d polynomial in the k th.) Now simply apply Lemma 2.2 k times to see that the pulled back polynomial is not identically zero restricted to A' , and thus P restricted to $G(k, A')$ is not identically zero. \square

Remark 2.4. The bound in Lemma 2.3 is sharp, as we give A a basis $a_1, \dots, a_{\mathbf{a}}$ and consider the polynomial on $\Lambda^k A$ with coordinates $x^I = x^{i_1}, \dots, x^{i_k}$ corresponding to the vector $\sum_I x^I a_{i_1} \wedge \dots \wedge a_{i_k} : P = x^{1, \dots, k} x^{k+1, \dots, 2k} \dots x^{(d-1)k+1, \dots, dk}$. Then

P restricted to $G(k, \langle a_1, \dots, a_{dk} \rangle)$ is nonvanishing, but there is no smaller subspace spanned by basis vectors on which it is nonvanishing.

3. Matrix multiplication and its rank. Let $M_{\langle \mathbf{m}, \mathbf{n}, \mathbf{l} \rangle} : \text{Mat}_{\mathbf{m} \times \mathbf{n}} \times \text{Mat}_{\mathbf{n} \times \mathbf{l}} \rightarrow \text{Mat}_{\mathbf{m} \times \mathbf{l}}$ denote the matrix multiplication operator. Write $M = \mathbb{C}^{\mathbf{m}}$, $N = \mathbb{C}^{\mathbf{n}}$, and $L = \mathbb{C}^{\mathbf{l}}$. Then

$$M_{\langle \mathbf{m}, \mathbf{n}, \mathbf{l} \rangle} : (N \otimes L^*) \times (L \otimes M^*) \rightarrow N \otimes M^*$$

has the interpretation as $M_{\langle \mathbf{m}, \mathbf{n}, \mathbf{l} \rangle} = \text{Id}_N \otimes \text{Id}_M \otimes \text{Id}_L \in (N^* \otimes L) \otimes (L^* \otimes M) \otimes (N \otimes M^*)$, where $\text{Id}_N \in N^* \otimes N$ is the identity map. If one thinks of $M_{\langle \mathbf{m}, \mathbf{n}, \mathbf{l} \rangle}$ as a trilinear map $(N \otimes L^*) \times (L \otimes M^*) \times (N \otimes M^*) \rightarrow \mathbb{C}$, in bases it is $(X, Y, Z) \mapsto \text{trace}(XYZ)$. If one thinks of $M_{\langle \mathbf{m}, \mathbf{n}, \mathbf{l} \rangle}$ as a linear map $N \otimes L^* \rightarrow (L^* \otimes M) \otimes (N \otimes M^*)$, it is just the identity map tensored with Id_M . In particular, if $\alpha \in N \otimes L^*$ is of rank q , its image, considered as a linear map $L \otimes M^* \rightarrow N \otimes M^*$, is of rank qm .

Returning to general tensors $T \in A \otimes B \otimes C$, from now on assume that $\mathbf{b} = \mathbf{c}$. When $T = M_{\langle \mathbf{m}, \mathbf{n}, \mathbf{l} \rangle}$, one has $A = N^* \otimes L$, $B = L^* \otimes M$, $C = N \otimes M^*$, so $\mathbf{b} = \mathbf{c}$ is equivalent to $\mathbf{l} = \mathbf{n}$.

The equations of [5] are as follows: given $T \in A \otimes B \otimes C$, with $\mathbf{b} = \mathbf{c}$, take $A' \subset A$ of dimension $2p + 1 \leq \mathbf{a}$. Define a linear map

$$(1) \quad T_{A'}^{\wedge p} : \Lambda^p A' \otimes B^* \rightarrow \Lambda^{p+1} A' \otimes C$$

by first considering $T|_{A' \otimes B \otimes C} : B^* \rightarrow A' \otimes C$ tensored with the identity map on $\Lambda^p A'$, which is a map $\Lambda^p A \otimes B^* \rightarrow \Lambda^p A \otimes A \otimes C$, and then projecting the image to $\Lambda^{p+1} A' \otimes C$. Then if the determinant of this linear map is nonzero, the border rank of T is at least $\frac{2p+1}{p+1} \mathbf{b}$. If there exists an A' such that the determinant is nonzero, we may think of the determinant as a nontrivial homogeneous polynomial of degree $\binom{2p+1}{p} \mathbf{b}$ on $G(2p+1, A)$.

Now consider the case $T = M_{\langle \mathbf{n}, \mathbf{n}, \mathbf{m} \rangle}$, and recall that $B = L^* \otimes M$, $C = N \otimes M^*$. The map $(M_{\langle \mathbf{n}, \mathbf{n}, \mathbf{m} \rangle})_{A'}^{\wedge p} : \Lambda^p A' \otimes L \otimes M^* \rightarrow \Lambda^{p+1} A' \otimes N \otimes M^*$ is actually a reduced map

$$(2) \quad \tilde{M}_{A'}^{\wedge p} : \Lambda^p A' \otimes L \rightarrow \Lambda^{p+1} A' \otimes N$$

tensored with the identity map $M^* \rightarrow M^*$, and thus its determinant is nonvanishing if and only if the determinant of $\tilde{M}_{A'}^{\wedge p}$ is nonvanishing. *But this is a polynomial of degree $\binom{2p+1}{p} \mathbf{n} \ll \binom{2p+1}{p} \mathbf{n}^2$ on $G(2p+1, \mathbf{n}^2)$.* Proposition 2.1, with $d = \binom{2p+1}{p} \mathbf{n}$, $\mathbf{a} = \mathbf{n}^2$, and $r = \frac{2p+1}{p+1} \mathbf{m} \mathbf{n}$, combined with Lemma 2.3, gives the bound

$$\mathbf{R}(M_{\langle \mathbf{n}, \mathbf{n}, \mathbf{m} \rangle}) \geq \frac{2p+1}{p+1} \mathbf{m} \mathbf{n} + \mathbf{n}^2 - (2p+1) \binom{2p+1}{p} \mathbf{n}.$$

Note that this already gives the $3\mathbf{n}^2 - o(\mathbf{n}^2)$ asymptotic lower bound. The remainder of the paper is dedicated to improving the error term.

4. The equations of [5] in coordinates. Let $\mathbf{a} = 3$ (so $p = 1$) and $\mathbf{b} = \mathbf{c}$; the map (1) expressed in bases is a $3\mathbf{b} \times 3\mathbf{b}$ matrix. If a_0, a_1, a_2 is a basis of A and one chooses bases of B, C , then elements of $B \otimes C$ may be written as matrices, and $T = a_0 \otimes X_0 + a_1 \otimes X_1 + a_2 \otimes X_2$, where the X_j are size \mathbf{b} square matrices. Order the

basis of A by a_0, a_1, a_2 and of $\Lambda^2 A$ by $a_1 \wedge a_2, a_0 \wedge a_1, a_0 \wedge a_2$. We compute

$$\begin{aligned} T_A^{\wedge 1}(a_0 \otimes \beta) &= \beta(X_0) \otimes a_0 \wedge a_0 + \beta(X_1) \otimes a_1 \wedge a_0 + \beta(X_2) \otimes a_2 \wedge a_0 \\ &= -\beta(X_1) \otimes a_0 \wedge a_1 - \beta(X_2) \otimes a_0 \wedge a_2, \\ T_A^{\wedge 1}(a_1 \otimes \beta) &= \beta(X_0) \otimes a_0 \wedge a_1 - \beta(X_2) \otimes a_1 \wedge a_2, \\ T_A^{\wedge 1}(a_2 \otimes \beta) &= \beta(X_0) \otimes a_0 \wedge a_2 + \beta(X_1) \otimes a_1 \wedge a_2, \end{aligned}$$

so the corresponding matrix for $T_A^{\wedge 1}$ is the block matrix

$$\text{Mat}(T_A^{\wedge 1}) = \begin{pmatrix} 0 & -X_2 & X_1 \\ -X_1 & X_0 & 0 \\ -X_2 & 0 & X_0 \end{pmatrix}.$$

Now assume X_0 is invertible, and change bases such that it is the identity matrix. Recall the formula for block matrices,

$$(3) \quad \det \begin{pmatrix} X & Y \\ Z & W \end{pmatrix} = \det(W) \det(X - YW^{-1}Z),$$

assuming W is invertible. Then, using the $(\mathbf{b}, 2\mathbf{b}) \times (\mathbf{b}, 2\mathbf{b})$ blocking (so $X = 0$ in (3)),

$$\det \text{Mat}(T_A^{\wedge 1}) = \det(X_1 X_2 - X_2 X_1) = \det([X_1, X_2]).$$

When $\dim A > 3$, if there exists a three dimensional subspace A' of A , such that $\det \text{Mat}(T_{A'}^{\wedge 1}) \neq 0$, then $\mathbf{R}(T) \geq \frac{3}{2}\mathbf{b}$ as this is (1) in the case $p = 1$. These are Strassen's equations [9].

I now phrase the equations of [5] in coordinates. Let $\dim A = 2p + 1$. Write $T = a_0 \otimes X_0 + \cdots + a_{2p} \otimes X_{2p}$. The expression of (1) in bases is as follows: write $a_I := a_{i_1} \wedge \cdots \wedge a_{i_p}$ for $\Lambda^p A$, require that the first $\binom{2p}{p-1}$ basis vectors have $i_1 = 0$ and that the second $\binom{2p}{p}$ do not, and call these multi-indices $0J$ and K . Order the bases of $\Lambda^{p+1} A$ such that the first $\binom{2p}{p+1}$ multi-indices do not have 0 and the second $\binom{2p}{p}$ do, and furthermore that the second set of indices is ordered the same way as K , except that we write $0K$ since a zero index is included. Then the resulting matrix is of the form

$$(4) \quad \begin{pmatrix} 0 & Q \\ \tilde{Q} & R \end{pmatrix},$$

where this matrix is blocked $(\binom{2p}{p+1}\mathbf{b}, \binom{2p}{p}\mathbf{b}) \times (\binom{2p}{p+1}\mathbf{b}, \binom{2p}{p}\mathbf{b})$,

$$R = \begin{pmatrix} X_0 & & \\ & \ddots & \\ & & X_0 \end{pmatrix},$$

and Q, \tilde{Q} have entries in blocks consisting of X_1, \dots, X_{2p} and zero. Thus if X_0 is the identity matrix, so is R , and the determinant equals the determinant of $Q\tilde{Q}$. If X_0 is the identity matrix, when $p = 1$ we have $Q\tilde{Q} = [X_1, X_2]$, and when $p = 2$

$$(5) \quad Q\tilde{Q} = \begin{pmatrix} 0 & [X_1, X_2] & [X_1, X_3] & [X_1, X_4] \\ [X_2, X_1] & 0 & [X_2, X_3] & [X_2, X_4] \\ [X_3, X_1] & [X_3, X_2] & 0 & [X_3, X_4] \\ [X_4, X_1] & [X_4, X_2] & [X_4, X_3] & 0 \end{pmatrix}.$$

In general, when X_0 is the identity matrix, $Q\tilde{Q}$ is a block $\binom{2p}{p-1}\mathbf{b} \times \binom{2p}{p-1}\mathbf{b}$ matrix whose block entries are either zero or commutators $[X_i, X_j]$.

To prove Theorem 1.1 we work with $\tilde{M}_A^{\wedge p}$ of (2), so $\mathbf{b} = \mathbf{n}$. First apply Lemma 2.2 to choose \mathbf{n} basis vectors such that restricted to them $\det(X_0)$ is nonvanishing, and then we consider our polynomial $\det(Q\tilde{Q})$ as defined on $G(2p, (2p+1)\mathbf{n}^2 - 1)$ and apply Lemma 2.3, using $2p\binom{2p}{p-1}\mathbf{n}$ basis vectors to ensure it is nonvanishing. Our error term is thus $\mathbf{n} + 2p\binom{2p}{p-1}\mathbf{n}$, and the theorem follows.

Remark 4.1. In [8, 7], the authors show that the matrix $Q\tilde{Q}$ can be made to have a nonzero determinant by a subtle combination of factoring and splitting it into a sum of two matrices that carries a lower cost than just taking its determinant.

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