

## 4 Second-order linear equations with constant coefficients

4.1 A homogeneous, second-order, linear equation with constant coefficients has the (normal) form

$$y'' + py' + qy = 0 \quad (4.1)$$

If there is a constant factor in front of the term  $y''$ , divide by this factor to bring the equation into normal form.

Solution of homogeneous, 2nd-order, linear ODE with constant coefficients
<p>In order to solve equations of type (4.1), first solve the auxiliary equation</p> $r^2 + pr + q = 0.$ <p>Depending on the discriminant <math>D = p^2 - 4q</math>, there are three possibilities:</p> <ol style="list-style-type: none"><li>1. <math>D &gt; 0</math>: The auxiliary equation has two real solutions <math>r_1</math> and <math>r_2</math>. From these we obtain the two linearly independent solutions</li></ol> $y_1 = e^{r_1 x} \qquad y_2 = e^{r_2 x}.$ <ol style="list-style-type: none"><li>2. <math>D &lt; 0</math>: The auxiliary equation has two conjugate complex solutions <math>r \pm i\alpha</math>. From these we obtain the two linearly independent solutions</li></ol> $y_1 = e^{rx} \sin \alpha x \qquad y_2 = e^{rx} \cos \alpha x.$ <ol style="list-style-type: none"><li>3. <math>D = 0</math>: The auxiliary equation only has a single real solution <math>r</math>. From this we obtain the two linearly independent solutions</li></ol> $y_1 = e^{rx} \qquad y_2 = xe^{rx}.$ <p>The fundamental solution of (4.1) is</p> $y(x) = c_1 y_1(x) + c_2 y_2(x).$

4.2 An inhomogeneous, second-order, linear equation with constant coefficients has the form

$$y'' + py' + qy = f \tag{4.2}$$

Solution of inhomogeneous, 2nd order, linear ODE with constant coefficients
<ol style="list-style-type: none"> <li>1. Compute the fundamental solution of the homogeneous equation (4.1).</li> <li>2. Compute one <i>particular</i> solution <math>y_p</math> of the inhomogeneous equation (4.2).</li> <li>3. The fundamental solution of the inhomogeneous equation is</li> </ol> $y(x) = c_1y_1(x) + c_2y_2(x) + y_p(x).$

4.3 If the right hand sided of the equation is simple, a particular solution to an inhomogeneous, 2nd-order, linear equation can be guessed using the following method:

Undetermined coefficient								
<ol style="list-style-type: none"> <li>1. Compute the linearly independent solutions <math>y_1</math> and <math>y_2</math> according to 4.1.</li> <li>2. Depending on the right hand side of the ODE, choose a guess from the following table:</li> </ol> <table border="1" style="margin-left: auto; margin-right: auto;"> <thead> <tr> <th>right hand side</th> <th>guess</th> </tr> </thead> <tbody> <tr> <td><math>e^{\alpha t}</math></td> <td><math>ae^{\alpha t}</math></td> </tr> <tr> <td><math>\alpha \sin \nu t + \beta \cos \nu t</math></td> <td><math>a \sin \nu t + b \cos \nu t</math></td> </tr> <tr> <td><math>\alpha_n t^n + \alpha_{n-1} t^{n-1} + \dots + \alpha_1 t + \alpha_0</math></td> <td><math>a_n t^n + a_{n-1} t^{n-1} + \dots + a_1 t + a_0</math></td> </tr> </tbody> </table> <p>Make sure that you use the full trigonometric or polynomial expansion, even if you only have a single sine, cosine or monomial.</p> <ol style="list-style-type: none"> <li>3. Check, if your guess is a solution to the homogeneous equation. If so, multiply with <math>t</math>. Repeat, until your guess is not a solution to the homogeneous equation.</li> <li>4. Insert your guess into the inhomogeneous equation and solve for the coefficients.</li> </ol>	right hand side	guess	$e^{\alpha t}$	$ae^{\alpha t}$	$\alpha \sin \nu t + \beta \cos \nu t$	$a \sin \nu t + b \cos \nu t$	$\alpha_n t^n + \alpha_{n-1} t^{n-1} + \dots + \alpha_1 t + \alpha_0$	$a_n t^n + a_{n-1} t^{n-1} + \dots + a_1 t + a_0$
right hand side	guess							
$e^{\alpha t}$	$ae^{\alpha t}$							
$\alpha \sin \nu t + \beta \cos \nu t$	$a \sin \nu t + b \cos \nu t$							
$\alpha_n t^n + \alpha_{n-1} t^{n-1} + \dots + \alpha_1 t + \alpha_0$	$a_n t^n + a_{n-1} t^{n-1} + \dots + a_1 t + a_0$							

4.4 A particular solution to an inhomogeneous, 2nd-order, linear equation can be computed using the following method:

Variation of parameters
<ol style="list-style-type: none"> <li>1. Compute the linearly independent solutions <math>y_1</math> and <math>y_2</math> according to 4.1.</li> <li>2. Obtain functions <math>u_1</math> and <math>u_2</math> by solving the system <math display="block">\begin{aligned} u_1' y_1 + u_2' y_2 &amp;= 0 \\ u_1' y_1' + u_2' y_2' &amp;= f \end{aligned} \tag{4.3}</math> and integrating <math>u_1'</math> and <math>u_2'</math> (intgration constants are of no importance).</li> <li>3. A particular solution is now obtained as</li> </ol> $y_p(x) = u_1(x)y_1(x) + u_2(x)y_2(x).$

4.5 Note that the first equation in (4.3) has no dependence on the right hand side. Even more, in the case of complex solutions to the characteristic equations, it always gives  $u_1' = -\tan(\beta x) u_2'$ .