

MATH 323.501
Exam 2 Solutions
November 12, 2013

1. For each statement below, write down whether it is **true** or **false**.
- (a) The rank of a matrix B plus the dimension of the null space of B is equal to the number of rows of B .
- (b) If $L : V \rightarrow W$ is a linear transformation, then the kernel of L is trivial if and only if L is surjective.
- (c) Suppose V_1 and V_2 are subspaces of \mathbb{R}^4 with $\dim(V_1) = 2$ and $\dim(V_2) = 3$. Then $\dim(V_1 \cap V_2)$ is either 1 or 2.
- (d) Suppose that $\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3, \mathbf{v}_4$ are linearly dependent vectors in \mathbb{R}^n . Then we have $\text{Span}(\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3, \mathbf{v}_4) = \text{Span}(\mathbf{v}_2, \mathbf{v}_3, \mathbf{v}_4)$.
- (e) If λ is an eigenvalue of a matrix A , then $A^2 - \lambda A$ is singular.

Solutions: (a) False: The rank plus the nullity is equal to the number of columns.

(b) False: The kernel is trivial if and only if L is injective.

(c) True: Since $V_1 \cap V_2 \subset V_1$, and $\dim(V_1) = 2$, we know that $\dim(V_1 \cap V_2)$ is either 0, 1, or 2. We need to rule out that the dimension is 0. Let $\{\mathbf{v}_1, \mathbf{v}_2\}$ be a basis of V_1 and let $\{\mathbf{w}_1, \mathbf{w}_2, \mathbf{w}_3\}$ be a basis of V_2 . There is a non-trivial linear dependency among these 5 vectors. Use this linear dependency to show that there is a non-zero vector in $V_1 \cap V_2$.

(d) False: We know that at least one of $\mathbf{v}_1, \dots, \mathbf{v}_4$ is redundant when taking the span, but we cannot say that it is definitely \mathbf{v}_1 .

(e) True: Since $A^2 - \lambda A = A(A - \lambda I)$, it follows that $\det(A^2 - \lambda A) = \det(A) \det(A - \lambda I)$. Since λ is an eigenvalue, we have $\det(A - \lambda I) = 0$, and so $\det(A^2 - \lambda A) = 0$.

2. Let $L : \mathbb{R}^2 \rightarrow \mathbb{R}^2$ be defined by

$$L \left(\begin{bmatrix} x_1 \\ x_2 \end{bmatrix} \right) = \begin{bmatrix} x_2 - x_1 \\ 2 - x_2 \end{bmatrix}.$$

Is L a linear transformation? Justify your answer.

Solution: It is not a linear transformation. The reason is that it fails to respect both addition and scalar multiplication. We only need to exhibit a counterexample to one of these, so we compute

$$L \left(3 \begin{bmatrix} 1 \\ 1 \end{bmatrix} \right) = L \left(\begin{bmatrix} 3 \\ 3 \end{bmatrix} \right) = \begin{bmatrix} 0 \\ -1 \end{bmatrix}$$

and

$$3L \left(\begin{bmatrix} 1 \\ 1 \end{bmatrix} \right) = 3 \begin{bmatrix} 0 \\ 1 \end{bmatrix} = \begin{bmatrix} 0 \\ 3 \end{bmatrix}.$$

Since these two values are not the same, we see that L does not respect scalar multiplication. Answers may vary of course, and it is also possible to provide a counterexample for addition.

3. Let A be the matrix

$$A = \begin{pmatrix} 1 & 1 & -2 & 0 \\ 3 & 5 & 4 & 2 \\ 0 & 1 & 5 & 1 \end{pmatrix},$$

and let V be the column space of A .

(a) Are the columns of A linearly independent or linearly dependent? Justify your answer.

(b) Find a basis for V . Show your work.

(c) What is the rank of A ? Explain.

Solution: (a) The columns are linearly dependent. The reason is that each column represents a vector in \mathbb{R}^3 . Thus we are considering 4 vectors in this 3-dimensional space, so they must be linearly dependent.

(b) We perform row operations on A and find that its reduced row echelon form is

$$\begin{pmatrix} 1 & 1 & -2 & 0 \\ 0 & 1 & 5 & 1 \\ 0 & 0 & 0 & 0 \end{pmatrix}.$$

The leading 1's appear in the first two columns, so the first two columns of A will make a basis for the column space of A . Thus $\left\{ \begin{pmatrix} 1 \\ 3 \\ 0 \end{pmatrix}, \begin{pmatrix} 1 \\ 5 \\ 1 \end{pmatrix} \right\}$ is a basis.

(c) The rank of A is 2. We know that the rank of a matrix is the same as the dimension of its column space (or the dimension of its row space, or the number of non-zero rows when it is put in row echelon form).

4. Let $\mathcal{A} = \left\{ \begin{pmatrix} 1 \\ 1 \end{pmatrix}, \begin{pmatrix} 1 \\ -1 \end{pmatrix} \right\} \subseteq \mathbb{R}^2$. We can take it as given that \mathcal{A} is a basis for \mathbb{R}^2 . Suppose that \mathcal{B} is another basis of \mathbb{R}^2 with change of basis matrix

$$P = \begin{pmatrix} 2 & 5 \\ 1 & 3 \end{pmatrix}.$$

That is, for every $\mathbf{v} \in \mathbb{R}^2$, we have $[\mathbf{v}]_{\mathcal{A}} = P[\mathbf{v}]_{\mathcal{B}}$.

(a) Find a matrix Q such that for every $\mathbf{v} \in \mathbb{R}^2$, $[\mathbf{v}]_{\mathcal{B}} = Q[\mathbf{v}]_{\mathcal{A}}$.

(b) Suppose that $L : \mathbb{R}^2 \rightarrow \mathbb{R}^2$ is a linear transformation and that with respect to the basis \mathcal{A} we have $[L]_{\mathcal{A}}^{\mathcal{A}} = \begin{pmatrix} 1 & -2 \\ -3 & 4 \end{pmatrix}$. Find $[L]_{\mathcal{B}}^{\mathcal{B}}$.

(c) What are the vectors in \mathcal{B} with respect to the standard coordinates on \mathbb{R}^2 ?

Solution: (a) If we take the equation $[\mathbf{v}]_{\mathcal{A}} = P[\mathbf{v}]_{\mathcal{B}}$ given and multiply through on the left by P^{-1} , we see that $P^{-1}[\mathbf{v}]_{\mathcal{A}} = [\mathbf{v}]_{\mathcal{B}}$. Thus $Q = P^{-1}$, which we calculate as

$$Q = \begin{pmatrix} 3 & -5 \\ -1 & 2 \end{pmatrix}.$$

(b) The matrix P is the change of basis matrix from basis \mathcal{B} into basis \mathcal{A} . Thus $P = [I]_{\mathcal{B}}^{\mathcal{A}}$. Likewise, $Q = [I]_{\mathcal{A}}^{\mathcal{B}}$. Thus

$$[L]_{\mathcal{B}}^{\mathcal{B}} = [I]_{\mathcal{A}}^{\mathcal{B}} [L]_{\mathcal{A}}^{\mathcal{A}} [I]_{\mathcal{B}}^{\mathcal{A}} = Q [L]_{\mathcal{A}}^{\mathcal{A}} P.$$

We calculate and find

$$[L]_{\mathcal{B}}^{\mathcal{B}} = \begin{pmatrix} 3 & -5 \\ -1 & 2 \end{pmatrix} \begin{pmatrix} 1 & -2 \\ -3 & 4 \end{pmatrix} \begin{pmatrix} 2 & 5 \\ 1 & 3 \end{pmatrix} = \boxed{\begin{pmatrix} 10 & 12 \\ -4 & -5 \end{pmatrix}}.$$

(c) If we let $V = [I]_{\mathcal{A}}^{\mathcal{S}}$ be the transition matrix from \mathcal{A} to the standard basis and let $U = [I]_{\mathcal{B}}^{\mathcal{S}}$ be the transition matrix from \mathcal{B} to the standard basis, then

$$P = [I]_{\mathcal{B}}^{\mathcal{A}} = [I]_{\mathcal{S}}^{\mathcal{A}} [I]_{\mathcal{B}}^{\mathcal{S}} = V^{-1}U.$$

Multiplying through by V on the left we see that,

$$U = VP,$$

and the columns of U will be the vectors in \mathcal{B} with respect to the standard basis. Now $V = \begin{pmatrix} 1 & 1 \\ 1 & -1 \end{pmatrix}$, since those are the coordinates of the basis vectors in \mathcal{A} with respect to the standard coordinates. Therefore,

$$U = \begin{pmatrix} 1 & 1 \\ 1 & -1 \end{pmatrix} \begin{pmatrix} 2 & 5 \\ 1 & 3 \end{pmatrix} = \begin{pmatrix} 3 & 8 \\ 1 & 2 \end{pmatrix},$$

and so with respect to the standard basis $\boxed{\mathcal{B} = \left\{ \begin{pmatrix} 3 \\ 1 \end{pmatrix}, \begin{pmatrix} 8 \\ 2 \end{pmatrix} \right\}}$.

5. Suppose V is a vector space and that $\{\mathbf{u}, \mathbf{v}, \mathbf{w}\}$ is a basis for V . Prove that $\{\mathbf{u} + 2\mathbf{v} + 3\mathbf{w}, 4\mathbf{v} + 5\mathbf{w}, 6\mathbf{w}\}$ is also a basis for V .

Solution: Since $\{\mathbf{u}, \mathbf{v}, \mathbf{w}\}$ contains 3 elements and is a basis for V , the dimension of V is 3. Since $\dim(V) = 3$, any other set of 3 linearly independent vectors in V will also be a basis. Thus it suffices to show that $\mathbf{u} + 2\mathbf{v} + 3\mathbf{w}$, $4\mathbf{v} + 5\mathbf{w}$, and $6\mathbf{w}$ are linearly independent.

Suppose that we have constants $a, b, c \in \mathbb{R}$ such that

$$a(\mathbf{u} + 2\mathbf{v} + 3\mathbf{w}) + b(4\mathbf{v} + 5\mathbf{w}) + c(6\mathbf{w}) = \mathbf{0}.$$

Then by manipulating the left-hand side and gathering terms we have

$$a\mathbf{u} + (2a + 4b)\mathbf{v} + (3a + 5b + 6c)\mathbf{w} = \mathbf{0}.$$

Since $\mathbf{u}, \mathbf{v}, \mathbf{w}$ are linearly independent, this implies that

$$a = 0, \quad 2a + 4b = 0, \quad 3a + 5b + 6c = 0.$$

As $a = 0$, the second equation implies that $b = 0$ also. Then using the third equation, $a = b = 0$ implies that $c = 0$. Therefore, $\mathbf{u} + 2\mathbf{v} + 3\mathbf{w}$, $4\mathbf{v} + 5\mathbf{w}$, and $6\mathbf{w}$ are linearly independent.

6. Consider the matrix

$$A = \begin{pmatrix} 1 & 0 & -2 \\ 2 & 0 & -4 \\ -1 & 0 & 2 \end{pmatrix}.$$

(a) Find the eigenvalues of A .

(b) For each eigenvalue λ of A , find vectors that span the eigenspace corresponding to λ .

Solution: (a) We calculate

$$\det \begin{pmatrix} 1 - \lambda & 0 & -2 \\ 2 & -\lambda & -4 \\ -1 & 0 & 2 - \lambda \end{pmatrix} = (1 - \lambda)((-\lambda)(2 - \lambda) - 2(-\lambda)) = -\lambda^2(\lambda - 3).$$

Therefore the eigenvalues are $\lambda = 0, 3$.

(b) $\lambda = 0$: To calculate the eigenspace E_0 for $\lambda = 0$, we compute the null space of A itself. The reduced row echelon form of A is

$$\begin{pmatrix} 1 & 0 & -2 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix},$$

and so the defining equation of the nullspace is $x_1 = 2x_3$. From this we see that

$$E_0 = \text{Span} \left\{ \begin{pmatrix} 2 \\ 0 \\ 1 \end{pmatrix}, \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix} \right\}.$$

$\lambda = 3$: To calculate the eigenspace E_3 for $\lambda = 3$, we compute the null space of

$$A - 3I = \begin{pmatrix} -2 & 0 & -2 \\ 2 & -3 & -4 \\ -1 & 0 & -1 \end{pmatrix},$$

whose reduced row echelon form is

$$\begin{pmatrix} 1 & 0 & 1 \\ 0 & 1 & 2 \\ 0 & 0 & 0 \end{pmatrix}.$$

Thus the defining equations of E_3 are $x_1 = -x_3$ and $x_2 = -2x_3$, so $E_3 = \text{Span} \left\{ \begin{pmatrix} -1 \\ -2 \\ 1 \end{pmatrix} \right\}$.