

Solving ODEs using MatLab

A command used to solve ODE's in MatLab (a "solver") is `ode45`
Enter

```
>> help ode45
```

to see information about this command. Note that all commands and variables in MatLab help are written in capitals.

The first argument of `ode45` is a function. It is convenient to program it in a separate file.

Consider, for instance the equation

$$y' = \frac{\cos t}{2y - 2}.$$

Program the function in the right-hand side of the equation in the file `example1.m` using MatLab editor.

```
function yprime=example1(t, y)
yprime=cos(t)/(2*y-2);
```

Then type

```
>> [t, y]=ode45(@example1, [0, 4*pi], 3);
>> plot(t, y)
```

We will find a table of values of the function y at values of t from 0 to 4π . The initial value of y at $t = 0$ will be 3, which is entered as the last entry of `ode45`.

The command `plot(t, y)` will plot the graph of the function y on the interval $[0, 4\pi]$.

Consider now the linear system

$$\vec{x}' = \begin{pmatrix} -0.1, 0.075; 0.1, -0.2 \end{pmatrix} \vec{x}$$

with the initial values $\vec{x}(1) = \begin{pmatrix} 10/2 \end{pmatrix}$. At first program the right-hand side of the equation as a function in the file `example3.m`

```
function xprime=example2(t, x)
xprime=[-0.1, 0.075; 0.1, -0.2]*x;
```

Then type in MatLab:

```
>> [t, y]=ode45(@example2, [1, 100], [10; 2]);
>> plot(y(:,1), y(:,2))
```

Let us try some other initial values and plot the results on the same frame.

```

>> hold
Current plot held
>> [t, y]=ode45(@example2, [1, 100], [10; -2]);
>> plot(y(:,1), y(:,2))
>> [t, y]=ode45(@example2, [1, 100], [0; 10]);
>> plot(y(:,1), y(:,2))
>> [t, y]=ode45(@example2, [1, 100], [5; 6]);
>> plot(y(:,1), y(:,2))
>> [t, y]=ode45(@example2, [1, 100], [-10; 0]);
>> plot(y(:,1), y(:,2))
>> [t, y]=ode45(@example2, [1, 100], [-10; -10]);
>> plot(y(:,1), y(:,2))

```

Consider now the system

$$\vec{x}' = \begin{pmatrix} -0.5 & 1 \\ -1 & -0.5 \end{pmatrix} \vec{x}$$

```

>> hold off
>> [t, y]=ode45(@example3, [1, 100], [1; 0]);
>> plot(y(:,1), y(:,2))
>> hold Current plot held
>> [t, y]=ode45(@example3, [1, 100], [-2; 0]);
>> plot(y(:,1), y(:,2))

```

If we want to solve a second order ODE, we have to pass to the equivalent first order system. For example, if we want to solve the equation

$$4t^2y'' + 8ty' + 65y = 0,$$

we pass to the system

$$\begin{cases} y_1' = y_2 \\ y_2' = -2y_2/t - 65y_1/(4t^2) \end{cases}$$

where $y_1 = y$ and $y_2 = y'$. So, we define a function `example4`

```

function xprime=example4(t, x)
xprime=[0; 0];
xprime(1)=x(2);
xprime(2)=-2*x(2)/t-65*x(1)/(4*t^2);

>> hold off
>> [t, y]=ode45(@example4, [1, 3*pi], [2; 3]);
>> plot(t, y(:,1))
>> [t, y]=ode45(@example4, [1, 6*pi], [2; 3]);
>> plot(t, y(:,1))
>> [t, y]=ode45(@example4, [1, 20*pi], [2; 3]);
>> plot(t, y(:,1))

```

Below are some other examples. Download the m-files and see what functions they describe.

```
>> [t, y]=ode45(@example5, [0, 3], [2; 3]);
>> plot(t, y(:,1))
>> [t, y]=ode45(@example6, [0, 2], [1; -4]);
>> plot(t, y(:,1))
>> hold
Current plot held
>> [t, y]=ode45(@example6, [0, 2], [1; -2]);
>> plot(t, y(:,1))
>> [t, y]=ode45(@example6, [0, 2], [1; 0]);
>> plot(t, y(:,1))
>> [t, y]=ode45(@example6, [0, 2], [1; 2]);
>> plot(t, y(:,1))
>> hold off
>> [t, y]=ode45(@example7, [-1, 2], [1; 1]);
>> plot(t, y(:,1))
>> [t, y]=ode45(@example7, [-1, 10], [1; 1]);
>> plot(t, y(:,1))
>> [t, y]=ode45(@example7, [-1, 13], [1; 1]);
>> plot(t, y(:,1))
>> [t, y]=ode45(@example7, [-3, 13], [1; 1]);
>> plot(t, y(:,1))
```