

### Notes on Chapter 3

1. The eigenvalues  $\lambda_i$  of an N by N matrix A are the (possibly complex) roots of the characteristic polynomial  $\det(\lambda I - A)$ . This  $N^{\text{th}}$  degree polynomial can be factored as

$$(\lambda - \lambda_1)^{m_1}(\lambda - \lambda_2)^{m_2} \dots (\lambda - \lambda_k)^{m_k}$$

2.  $m_i$  is called the algebraic multiplicity of the eigenvalue  $\lambda_i$ . The sum of the algebraic multiplicities is always N.
3. For each eigenvalue  $\lambda_i$  the set of solutions to  $(\lambda_i I - A)z = 0$  (the set of eigenvectors corresponding to  $\lambda_i$ ) is a subspace of  $R^N$ , called the eigenspace for that eigenvalue. The dimension of the eigenspace corresponding to  $\lambda_i$  is called the geometric multiplicity,  $n_i$ , of this eigenvalue.
4. Now let's choose a basis for the eigenspace of  $\lambda_1$ , and place these  $n_1$  vectors in the first  $n_1$  columns of a matrix S ( $n_i$  is the geometric multiplicity of  $\lambda_i$ ). Choose the remaining columns of this N by N matrix so that they form a basis for  $R^N$  (recall the extension to a basis theorem). Then  $AS = SE$ , where E has the form:

$$\begin{bmatrix} \lambda_1 & 0 & \dots & 0 & x & \dots & x \\ 0 & \lambda_1 & \dots & 0 & x & \dots & x \\ \dots & \dots & \dots & \dots & \dots & \dots & \dots \\ 0 & 0 & \dots & \lambda_1 & x & \dots & x \\ 0 & 0 & \dots & 0 & x & \dots & x \\ 0 & 0 & \dots & 0 & x & \dots & x \\ \dots & \dots & \dots & \dots & \dots & \dots & \dots \\ 0 & 0 & \dots & 0 & x & \dots & x \end{bmatrix}$$

5. Since S has an inverse,  $A = SES^{-1}$  (A is "similar" to E), so  $\det(\lambda I - A) = \det(\lambda SS^{-1} - SES^{-1}) = \det(S(\lambda I - E)S^{-1}) = \det(S)\det(\lambda I - E)\det(S^{-1}) = \det(SS^{-1})\det(\lambda I - E) = \det(\lambda I - E)$  so A and E have exactly the same characteristic polynomial, and the characteristic polynomial for E contains the factor  $(\lambda - \lambda_1)^{n_1}$ . Thus the algebraic multiplicity  $m_1$  is at least as large as the geometric multiplicity  $n_1$ . The same is clearly true for all eigenvalues, so in general we see that  $1 \leq n_i \leq m_i$ . If  $n_i < m_i$ , the eigenvalue  $\lambda_i$  is said to be "defective" (it's missing some of its eigenvalues).

6. Any set of eigenvectors  $z_i$  corresponding to distinct eigenvalues  $\lambda_i$  are independent. To show this, assume  $\sum_{i=1}^k \alpha_i z_i = 0$ . Then by multiplying both sides of this equation by  $A^j$  we get:  
 $\sum_{i=1}^k \alpha_i A^j z_i = \sum_{i=1}^k \alpha_i \lambda_i^j z_i = 0$   
 If we take  $j=0, \dots, k-1$ , we get  $k$  equations for the  $k$  unknowns  $\alpha_i z_i, i = 1, \dots, k$ :

$$\begin{bmatrix} 1 & 1 & 1 & \dots & 1 \\ \lambda_1 & \lambda_2 & \lambda_3 & \dots & \lambda_k \\ \lambda_1^2 & \lambda_2^2 & \lambda_3^2 & \dots & \lambda_k^2 \\ \lambda_1^3 & \lambda_2^3 & \lambda_3^3 & \dots & \lambda_k^3 \\ \dots & \dots & \dots & \dots & \dots \\ \lambda_1^{k-1} & \lambda_2^{k-1} & \lambda_3^{k-1} & \dots & \lambda_k^{k-1} \end{bmatrix} \begin{bmatrix} \alpha_1 z_1 \\ \alpha_2 z_2 \\ \alpha_3 z_3 \\ \dots \\ \alpha_k z_k \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \\ \dots \\ 0 \end{bmatrix}$$

The matrix is the Vandermonde matrix, and we showed in a homework problem that if all the  $\lambda_i$  are distinct, the determinant of this matrix is nonzero, thus  $\alpha_i z_i = 0$  for each  $i$ , and since  $z_i \neq 0, \alpha_i = 0$ .

7. Since the sum of the algebraic multiplicities is  $N$ , the sum of the geometric multiplicities is less than or equal to  $N$ . If it is equal to  $N$ , then  $A$  has a complete set of  $N$  linearly independent eigenvectors, because there are  $n_i$  independent eigenvectors for each  $\lambda_i$ , and we saw in (6) that eigenvectors for different eigenvalues are independent. So load up all  $N$  linearly independent eigenvectors in the columns of a new matrix  $S$ . Then  $AS = SD$ , where  $D$  is a diagonal matrix with the eigenvalues of  $A$  along the diagonal, and  $A = SDS^{-1}$  and we say that  $A$  is diagonalizable (similar to a diagonal matrix).
8. If all eigenvalues are distinct, then  $1 \leq n_i \leq m_i = 1$  and so  $n_i = m_i$  for each  $i$ , and  $A$  has a complete set of eigenvectors and is therefore diagonalizable. If  $A$  has eigenvalues of algebraic multiplicity greater than 1, it will be diagonalizable only if no eigenvalues are defective.