11: Complex roots of the characteristic equation (section 3.3.)

- 1. Case 2: two complex conjugate roots $r_1 = \overline{r_2}$ (in this case $D = b^2 4ac < 0$)
- 2. Recall that the **characteristic equation** of a linear homogeneous equation with constant real coefficients

$$ay'' + by' + cy = 0 \tag{1}$$

is

$$ar^2 + br + c = 0. (2)$$

$$D=b^2-4ac<0 \Rightarrow r_{1,2}=\frac{-b\pm\sqrt{D}}{2a}=-\frac{b}{2a}\pm i\frac{\sqrt{|D|}}{2a}=:\lambda+i\mu$$

Then two particular solutions which form a fundamental set are

$$y_1 = e^{(\lambda + i\mu)t}, \qquad y_2 = e^{(\lambda - i\mu)t}.$$

3. Note that formally there is no difference between this case and Case 1 (two distinct real roots). However in practice we prefer to work with real functions instaed of complex exponentials. By Superposition Principle the following linear combinations are solutions as well

$$\frac{1}{2}(y_1 + y_2) = e^{\lambda t} \cos(\mu t), \quad \frac{1}{2i}(y_1 - y_2) = e^{\lambda t} \sin(\mu t)$$

Note that these solutions are real functions.

- 4. FACT: $\frac{\mathrm{d}}{\mathrm{d}t}(e^{rt}) = re^{rt}$ for any complex r.
- 5. Show that $\{e^{\lambda t}\cos(\mu t), e^{\lambda t}\sin(\mu t)\}$ is a fundamental set of solutions, i.e. that general solution of (1) has a form

$$y(t) = C_1 e^{\lambda t} \cos(\mu t) + C_2 e^{\lambda t} \sin(\mu t)$$
(3)

6. Solve the following two differential equations which are important in applied mathematics:

$$y'' + \omega^2 y = 0$$
 and $y'' - \omega^2 y = 0$,

where ω is a real positive constant.

7. Alternative form of solution (3):

$$y(t) = e^{\lambda t} R \cos(\mu t - \delta), \tag{4}$$

where

$$R = \sqrt{C_1^2 + C_2^2}, \quad \cos \delta = \frac{C_1}{\sqrt{C_1^2 + C_2^2}} = \frac{C_1}{R}, \quad \sin \delta = \frac{C_2}{\sqrt{C_1^2 + C_2^2}} = \frac{C_2}{R}.$$

Note that $\tan \delta = C_2/C_1$.

- 8. Application: Mechanical unforced vibration: a mass hanging from a spring (more details in Section 3.7).
 - $\lambda = 0$ corresponds to **undamped** free vibration (simple harmonic motion)
 - $\lambda < 0$ corresponds to **damped** free vibration
 - R is called the **amplitude** of the motion
 - δ is called the **phase**, or phase angle, and measures the displacement of the wave from its normal position corresponding to $\delta = 0$.
 - $T = \frac{2\pi}{\mu}$ is the **period** of the motion.
- 9. Consider

$$y'' + 2y' + 3y = 0. (5)$$

- (a) Find general solution.
- (b) Find solution of (5) subject to the initial conditions

$$y(0) = 2, \quad y'(0) = 1.$$

(c) Sketch the graph of the solution of IVP from (b) and describe its behavior as t increases.