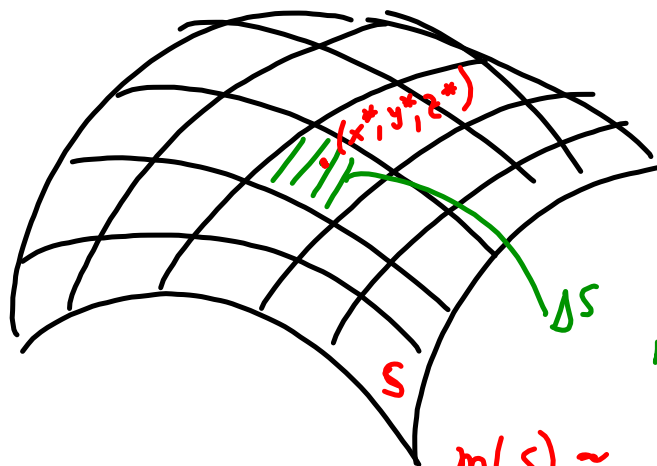


14.7: Surface Integrals

Problem: Find the mass of a thin sheet (say, of aluminum foil) which has a shape of a surface S and the density (mass per unit area) at the point (x, y, z) is $\rho(x, y, z)$.

Solution:



$$\rho = \text{const}$$

↓

$$m = \rho \cdot SA$$

$$= \rho \iint_S ds$$

$$m(\Delta s) = \rho(x^*, y^*, z^*) \Delta s$$

$$m(s) \approx \sum m(\Delta s) = \sum \rho \Delta s$$

$$m(s) = \iint_S \rho(x, y, z) ds$$

If S is given by $\mathbf{r}(u, v) = x(u, v)\mathbf{i} + y(u, v)\mathbf{j} + z(u, v)\mathbf{k}$, $(u, v) \in D$, then the surface integral of f over the surface S is:

$$\iint_S f(x, y, z) dS = \iint_D f(\mathbf{r}(u, v)) |\mathbf{N}(u, v)| dA = \iint_D f(\mathbf{r}(u, v)) |\vec{r}_u \times \vec{r}_v| du dv$$

$$dS = |\vec{N}(u, v)| du dv$$

$$dS = |\vec{r}_u \times \vec{r}_v| du dv$$

EXAMPLE 1. Find the mass of a thin funnel in the shape of a cone $z = \sqrt{x^2 + y^2}$ inside the cylinder $x^2 + y^2 \leq 2x$, if its density is a function $\rho(x, y, z) = x^2 + y^2 + z^2$.

$$m = \iint_S \rho(x, y, z) dS, \text{ where}$$

$$S = \{(x, y, z) \mid z = \sqrt{x^2 + y^2}, x^2 + y^2 \leq 2x\}$$

Parameterize S

Way I

$$\vec{r}(x, y) = \langle x, y, \sqrt{x^2 + y^2} \rangle$$

$$D = \{(x, y) \mid x^2 + y^2 \leq 2x\}$$

$$\vec{N}(x, y) = \langle z_x, z_y, -1 \rangle$$

$$= \left\langle \frac{x}{\sqrt{x^2 + y^2}}, \frac{y}{\sqrt{x^2 + y^2}}, -1 \right\rangle$$

$$|\vec{N}(x, y)| = \sqrt{\underbrace{\frac{x^2}{x^2 + y^2} + \frac{y^2}{x^2 + y^2}}_1 + (-1)^2}$$

$$|\vec{N}(x, y)| = \sqrt{2}$$

$$m = \iint_D \rho(x, y, \sqrt{x^2 + y^2}) |\vec{N}(x, y)| dA_{x, y}$$

$$= \iint_D 2(x^2 + y^2) \sqrt{2} dA$$

Use polar coordinates

$$D^* = \{(r, \theta) \mid 0 \leq r \leq 2\cos\theta, \frac{\pi}{2} \leq \theta \leq \frac{3\pi}{2}\}$$

$$m = 2\sqrt{2} \int_{-\pi/2}^{\pi/2} \int_0^{2\cos\theta} r^2 r dr d\theta$$

$$= 2\sqrt{2} \int_{-\pi/2}^{\pi/2} \left. \frac{r^4}{4} \right|_{r=0}^{2\cos\theta} d\theta = 2\sqrt{2} \int_{-\pi/2}^{\pi/2} 4\cos^4\theta d\theta = \dots$$

Way II Use cylindrical

$$\vec{R}(r, \theta) = \langle r\cos\theta, r\sin\theta, r \rangle$$

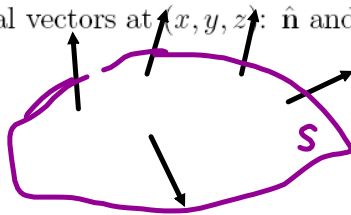
$$D = \{(r, \theta) \mid 0 \leq r \leq 2\cos\theta, \frac{\pi}{2} \leq \theta \leq \frac{3\pi}{2}\}$$

$$\vec{N}(r, \theta) = \vec{R}_r \times \vec{R}_\theta$$

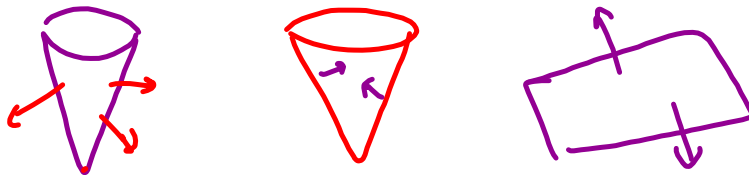
and so on...

- **Oriented surfaces.** We consider only two-sided surfaces.

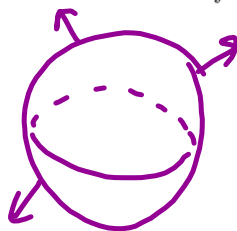
Let a surface S has a tangent plane at every point (except at any boundary points). There are two unit normal vectors at (x, y, z) : \hat{n} and $-\hat{n}$.



If it is possible to choose a unit normal vector \hat{n} at every point (x, y, z) of a surface S so that \hat{n} varies continuously over S , then S is called **oriented surface** and the given choice of \hat{n} provides S with an **orientation**. There are two possible orientations for any orientable surface:



Convention: For closed surfaces the positive orientation is outward.



- Surface integrals of vector fields.

DEFINITION 2. If \mathbf{F} is a continuous vector field defined on an oriented surface S with unit normal vector $\hat{\mathbf{n}}$, then the surface integral of \mathbf{F} over S is

$$\iint_S \vec{\mathbf{F}} \cdot \vec{dS} = \iint_S \underbrace{\mathbf{F} \cdot \hat{\mathbf{n}}}_{\text{unit}} dS, \quad , \quad d\vec{S} = \hat{\mathbf{n}} dS$$

This integral is also called the flux of \mathbf{F} across S .

Note that if S is given by $\mathbf{r}(u, v)$, $(u, v) \in D$, then

$$\text{unit} \leftarrow \hat{\mathbf{n}} = \frac{\mathbf{n}}{|\mathbf{n}|} = \frac{\vec{\mathbf{n}}(u, v)}{|\vec{\mathbf{n}}(u, v)|} = \frac{\vec{\mathbf{r}}_u \times \vec{\mathbf{r}}_v}{|\vec{\mathbf{r}}_u \times \vec{\mathbf{r}}_v|}$$

and

$$d\vec{S} = \hat{\mathbf{n}} dS = \frac{\vec{\mathbf{n}}(u, v)}{|\vec{\mathbf{n}}(u, v)|} \cdot \cancel{|\vec{\mathbf{n}}(u, v)|} du dv = \vec{\mathbf{n}}(u, v) du dv$$

Finally,

$$\iint_S \mathbf{F} \cdot d\mathbf{S} = \iint_D \vec{\mathbf{F}}(\vec{\mathbf{r}}(u, v)) \cdot \vec{\mathbf{n}}(u, v) du dv$$

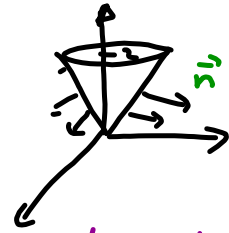
where $\vec{\mathbf{n}}(u, v) = \pm \vec{\mathbf{r}}_u \times \vec{\mathbf{r}}_v$

EXAMPLE 3. Find the flux of the vector field

$$\mathbf{F} = \langle x^2, y^2, z^2 \rangle$$

across the surface

$$S = \{z^2 = x^2 + y^2, 0 \leq z \leq 2\}.$$



Note Direction of \vec{n} is not indicated, so we have to choose \vec{n} pointed outward.

$$\text{Flux} = \iint_S \vec{F} \cdot d\vec{S}$$

Parameterize S : Way 1

$$\vec{r}(x,y) = \langle x, y, \sqrt{x^2 + y^2} \rangle.$$

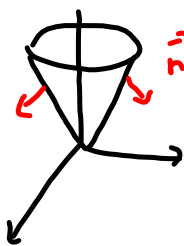
$$D = \{(x,y) \mid 0 \leq x^2 + y^2 \leq 4\}$$

and so on
See also Example 1

We use here parameterization using cylindrical coordinates;

$$\mathbf{R}(\theta, r) = \langle \underbrace{r \cos \theta}_x, \underbrace{r \sin \theta}_y, \underbrace{r}_z \rangle, \quad D = \{(r, \theta) \mid 0 \leq r \leq 2, 0 \leq \theta \leq 2\pi\}$$

$$\vec{n}(\theta, r) = \pm \mathbf{R}_\theta \times \mathbf{R}_r = \pm \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ -r \sin \theta & r \cos \theta & 0 \\ \cos \theta & \sin \theta & 1 \end{vmatrix} = \pm \langle r \cos \theta, r \sin \theta, -r \rangle$$



\vec{n} is pointed down \Rightarrow its last component must be negative

$$\vec{n}(\theta, r) = \langle r \cos \theta, r \sin \theta, -r \rangle$$

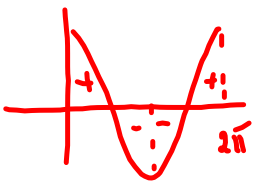
$$\text{Flux} = \iint_D \vec{F}(\vec{R}(\theta, r)) \cdot \vec{n}(r, \theta) dA_{r, \theta}$$

$$= \iint_D \langle r^2 \cos^2 \theta, r^2 \sin^2 \theta, r^2 \rangle \cdot \langle r \cos \theta, r \sin \theta, -r \rangle dA_{r, \theta}$$

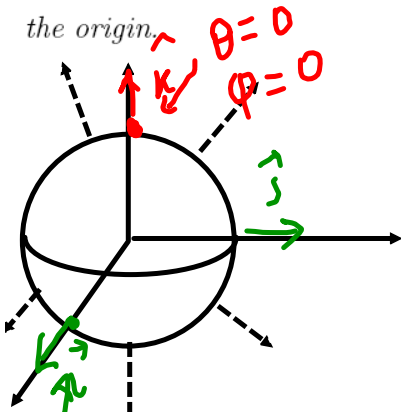
$$= \int_0^{2\pi} \int_0^2 (r^3 \cos^3 \theta + r^3 \sin^3 \theta - r^3) dr d\theta$$

$$\int_0^{2\pi} (\cos^3 \theta + \sin^3 \theta - 1) d\theta \int_0^2 r^3 dr = -2\pi \left. \frac{r^4}{4} \right|_0^2 = -\frac{\pi}{2} \cdot 16 = \boxed{-8\pi}$$

because $\int_0^{2\pi} \cos^3 \theta d\theta = \int_0^{2\pi} \sin^3 \theta d\theta = 0$



EXAMPLE 4. Evaluate $I = \oiint_S \mathbf{F} \cdot d\mathbf{S}$ where $\mathbf{F} = \langle z, y, x \rangle$ and S is the unit sphere centered at the origin.



S is closed $\Rightarrow \vec{n}$ is pointed outward.

$$S = \{(x, y, z) \mid x^2 + y^2 + z^2 = 1\}$$

Use spherical coordinates to parameterize S : $\rho = 1$

$$\vec{r}(\theta, \varphi) = \langle \sin \varphi \cos \theta, \sin \varphi \sin \theta, \cos \varphi \rangle \quad ; S$$

$$D = \{(\theta, \varphi) \mid 0 \leq \theta \leq 2\pi, 0 \leq \varphi \leq \pi\}$$

$$\vec{n}(\theta, \varphi) = \pm \vec{r}_\theta \times \vec{r}_\varphi = \pm \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ -\sin \varphi \sin \theta & \sin \varphi \cos \theta & 0 \\ \cos \varphi \cos \theta & \cos \varphi \sin \theta & -\sin \varphi \end{vmatrix}$$

$$\pm \langle -\sin^2 \varphi \cos \theta, -\sin^2 \varphi \sin \theta, -\sin \varphi \cos \varphi \rangle =$$

$$= \pm \sin \varphi \langle -\sin \varphi \cos \theta, -\sin \varphi \sin \theta, -\cos \varphi \rangle$$

$$\vec{F}(\vec{r}(\theta, \varphi)) \cdot \vec{n}(\theta, \varphi)$$

$$= \langle \cos \varphi, \sin \varphi \sin \theta, \sin \varphi \cos \theta \rangle$$

$$\cdot \langle \sin \varphi \cos \theta, \sin \varphi \sin \theta, \cos \varphi \rangle \sin \varphi$$

$$= \sin^2 \varphi (\cos \varphi \cos \theta + \sin \varphi \sin^2 \theta + \cos \theta \cos \varphi)$$

$$= \sin^2 \varphi (2 \cos \varphi \cos \theta + \sin \varphi \sin^2 \theta)$$

$$\oiint_S \vec{F} \cdot d\vec{S} = \iint_D (2 \cos \varphi \cos \theta \sin^2 \varphi + \sin^3 \varphi \sin^2 \theta) dA_{\theta, \varphi}$$

$$= 2 \int_0^{2\pi} \int_0^\pi \cos \theta \sin^2 \varphi \cos \varphi d\varphi d\theta + \int_0^{2\pi} \int_0^\pi \sin^2 \theta \sin^3 \varphi d\varphi d\theta$$

$$= \left(\int_0^{2\pi} \frac{1}{2} - \frac{1}{2} \cos 2\theta d\theta \right) \left(\int_0^\pi \sin \varphi d\varphi - \int_0^\pi \cos^2 \varphi \sin \varphi d\varphi \right)$$

$$\left(\pi - 0 \right) \left(-\cos \varphi \Big|_0^\pi + \frac{\cos^3 \varphi}{3} \Big|_0^\pi \right) = \pi \left(2 + \left(-\frac{1-1}{3} \right) \right)$$

$$= \boxed{\frac{4\pi}{3}}$$

$$\int_C \vec{F} \cdot d\vec{r} = \int_a^b \vec{F}(\vec{r}(t)) \cdot \underbrace{\vec{r}'(t)}_{\text{tangent to } C} dt$$

$$\vec{F} = \rho \vec{V}$$

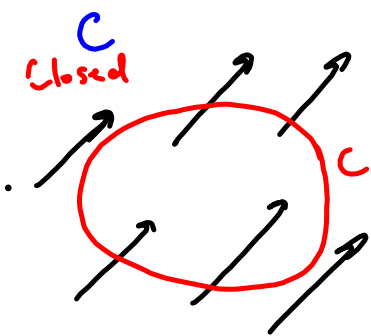
ρ ← density of fluid
 \vec{V} ← velocity

$$\left[\frac{\text{kg}}{\text{m}^3} \right] \cdot \left[\frac{\text{m}}{\text{s}} \right] = \left[\frac{\text{kg}}{\text{m}^2 \cdot \text{s}} \right]$$

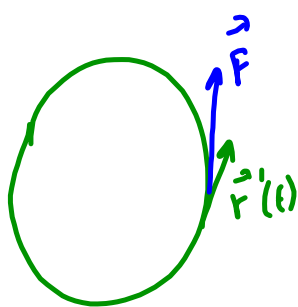
amount of fluid per unit area per unit time.

$\int_C \vec{F} \cdot d\vec{r}$ measures how much vector field C is aligned with the curve C .

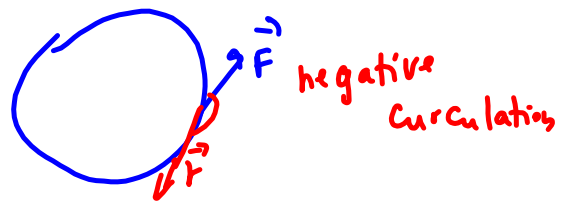
$\oint_C \vec{F} \cdot d\vec{r}$ measures how much vector field tends to circulate around the C .



$$\oint_C \vec{F} \cdot d\vec{r} \quad \text{Macroscopic circulation of } \vec{F}$$



$\vec{F} \cdot \vec{r}' > 0$
positive circulation



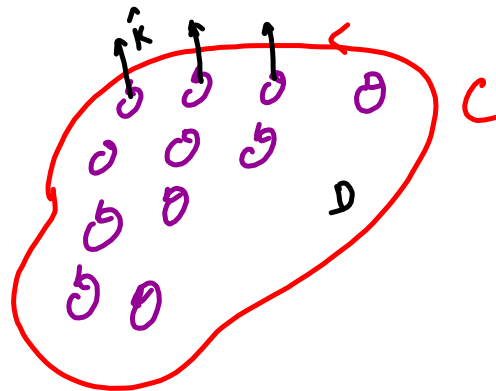
negative circulation

$$\oint_C \vec{F} \cdot d\vec{r} = \iint_D \underbrace{\text{curl } \vec{F} \cdot \hat{k}}_{\text{microscopic circulation of } \vec{F}} dA$$

macroscopic circulation

Green's Theorem.

$\hat{k} \perp D$

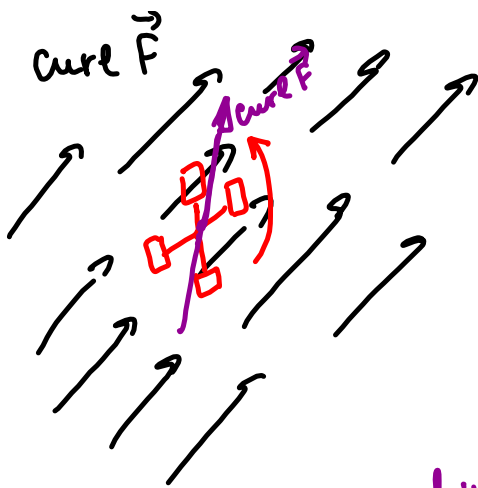


Stokes' Theorem:

$$\oint_C \vec{F} \cdot d\vec{r} = \iint_S \text{curl } \vec{F} \cdot \hat{n} dS$$

$C = \partial S$

Flux of $\text{curl } \vec{F}$



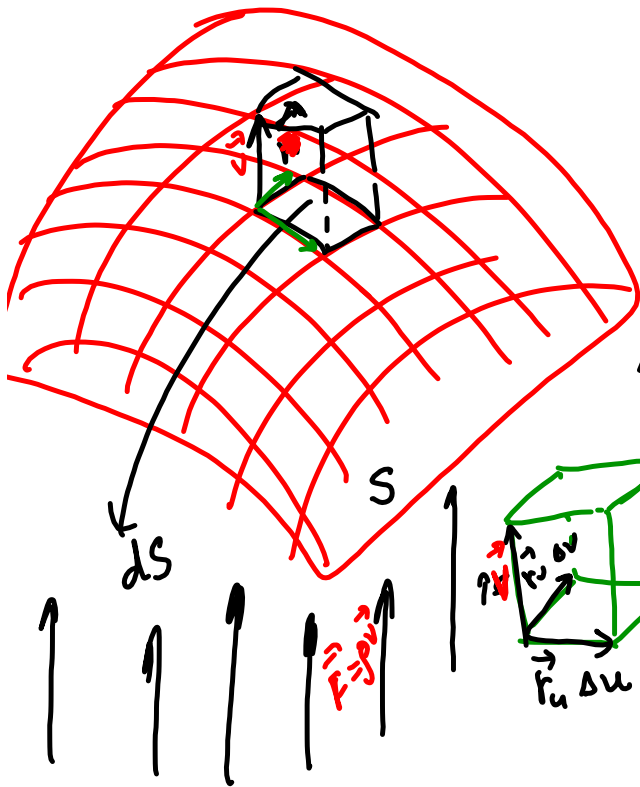
$\text{curl } \vec{F}$ shows how fluid may rotate.

$\text{curl } \vec{F}$ measures the tendency of the vector field to curl around the given point in the direction given by the right hand rule.

$$|\text{curl } \vec{F}| = \text{angular velocity.}$$

Flux of \vec{F}
across S

$$\iint_S \vec{F} \cdot \hat{n} \, d\vec{S} = \iiint_D \vec{F}(\vec{r}(u,v)) \cdot \hat{n}(u,v) \, du \, dv$$



$\vec{F} = \rho \vec{V}$ (= mass of fluid
per unit area
and per unit time.)

$$\Delta m = \rho \cdot dV = \rho (\vec{r}_u \times \vec{r}_v) \cdot \vec{V} \, du \, dv$$

$$= \rho \vec{V} \cdot \hat{n} \, du \, dv$$

$$\text{Total mass} = \iint_S dm$$

$$= \iint_S \vec{F} \cdot \hat{n} \, ds$$