

# Linear precision for parametric patches

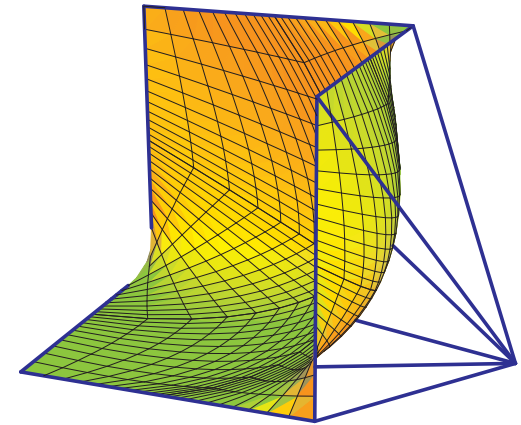
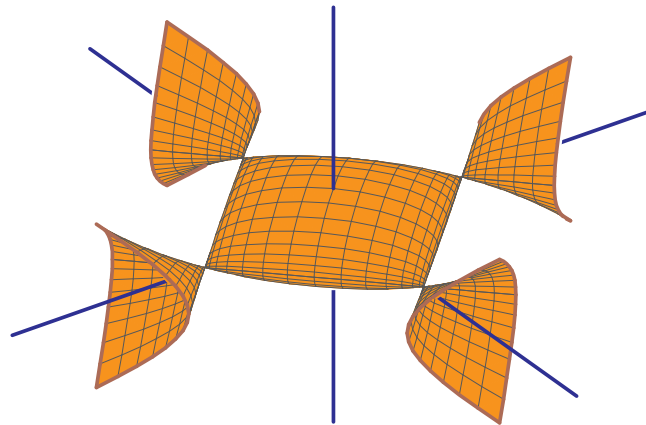
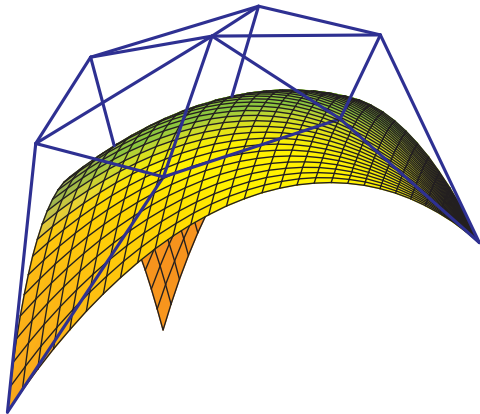
Mathematical methods for curves and surfaces

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# Overview

(With L. Garcia, K. Ranestad, and H.-C. Graf von Bothmer)

Linear precision is the ability of a patch to replicate affine functions.

It has interesting properties and connections to other areas of mathematics.

- Any patch has a unique reparametrization (possibly non-rational) with linear precision. This reparametrization is the maximum likelihood estimator from algebraic statistics.
- This reparametrization for toric patches is computed by iterative proportional fitting, an algorithm from statistics.
- Linear precision has an interesting mathematical formulation for toric patches, which leads to a classification, using algebraic geometry, of toric surface patches having linear precision.

# (Control-point) patch schemes

Let  $\mathcal{A} \subset \mathbb{R}^d$  (e.g.  $d = 2$ ) be a finite index set with convex hull  $\Delta$ .

$\beta := \{\beta_{\mathbf{a}}: \Delta \rightarrow \mathbb{R}_{\geq 0} \mid \mathbf{a} \in \mathcal{A}\}$ , *basis functions* with  $1 = \sum_{\mathbf{a}} \beta_{\mathbf{a}}(x)$ .

Given *control points*  $\{\mathbf{b}_{\mathbf{a}} \mid \mathbf{a} \in \mathcal{A}\} \subset \mathbb{R}^\ell$  (e.g.  $\ell = 3$ ), get a map

$$\varphi : \Delta \rightarrow \mathbb{R}^\ell \quad x \longmapsto \sum \beta_{\mathbf{a}}(x) \mathbf{b}_{\mathbf{a}}$$

The image of  $\varphi$  is a patch with shape  $\Delta$ . Call  $(\beta, \mathcal{A})$  is a *patch*.

*Affine invariance* and the *convex hull property* are built into this definition.

Linear precision is the ability to replicate linear functions.

We will adopt a precise, but restrictive definition.

# Linear Precision

Let  $\mathcal{A}$  be the control points, ( $\mathbf{b}_a = \mathbf{a}$ ), to get the *tautological map*,

$$\tau : x \longmapsto \sum \beta_a(x) \mathbf{a} \quad \tau : \Delta \rightarrow \Delta.$$

**Definition.**  $(\beta, \mathcal{A})$  has *linear precision* if and only if  $\tau$  is the identity map.

**Theorem (G-S).** *If  $\tau$  is a homeomorphism, the patch  $\{\beta_a \mid \mathbf{a} \in \mathcal{A}\}$  has a unique reparametrization with linear precision,  $\{\beta_a \circ \tau^{-1} \mid \mathbf{a} \in \mathcal{A}\}$ .*

How to compute  $\tau^{-1}$ ? The map  $\tau$  factors

$$\begin{array}{ccccc} \varphi: & \Delta & \xrightarrow{\beta} & \mathbb{RP}^{\mathcal{A}} & \xrightarrow{\mu} & \Delta \\ & x & \longmapsto & [1, \beta_a(x) \mid \mathbf{a} \in \mathcal{A}] & [0, \dots, 1, \dots, 0] & \longmapsto & \mathbf{a} \end{array}$$

Note that  $\beta \circ \tau^{-1} = \mu^{-1}: \Delta \rightarrow X_\beta$ , where  $X_\beta := \text{image } \beta(\Delta) \subset \mathbb{RP}^{\mathcal{A}}$ .

We shall see that  $\mu^{-1}$  is the key.

# Toric patches (After Krasauskas)

A polytope  $\Delta$  with integer vertices is given by facet inequalities

$$\Delta = \{x \in \mathbb{R}^d \mid h_i(x) \geq 0 \ i = 1, \dots, n\},$$

where  $h_i$  is linear with integer coefficients.

For each  $\mathbf{a} \in \mathcal{A} := \Delta \cap \mathbb{Z}^d$ , there is a *toric Bézier function*

$$\beta_{\mathbf{a}}(x) := h_1(x)^{h_1(\mathbf{a})} \dots h_n(x)^{h_n(\mathbf{a})}.$$

Let  $w = \{w_{\mathbf{a}} \mid \mathbf{a} \in \mathcal{A}\} \subset \mathbb{R}_{>}$  be positive weights. The *toric patch*  $(w, \mathcal{A})$  is the patch with blending functions  $\{w_{\mathbf{a}}\beta_{\mathbf{a}} \mid \mathbf{a} \in \mathcal{A}\}$ . Write  $X_{w, \mathcal{A}}$  for its image in  $\mathbb{RP}^{\mathcal{A}}$ , which is the positive part of a toric variety.

The map  $\mu: X_{w, \mathcal{A}} \rightarrow \Delta$  is the *algebraic moment map*.

# Example: Bézier triangles

Bézier triangles are toric surface patches.

Set  $\mathcal{A} := \{(i, j) \in \mathbb{N}^2 \mid i \geq 0, j \geq 0, n - i - j \geq 0\}$ , then

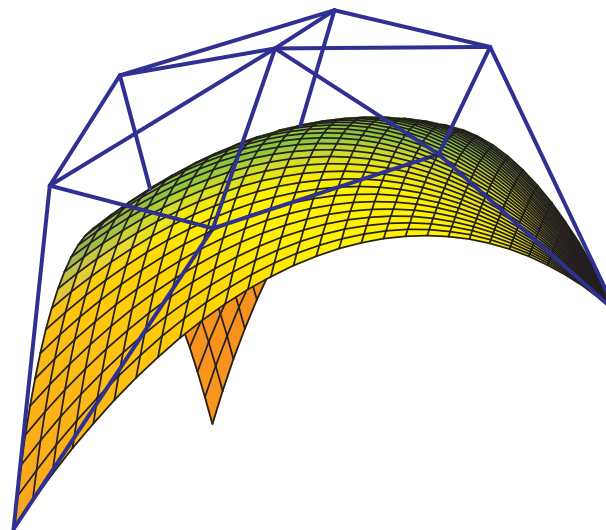
$$w_{(i,j)} \beta_{(i,j)} := \frac{n!}{i!j!(n-i-j)!} x^i y^j (n-x-y)^{n-i-j}.$$

These are essentially the Bernstein polynomials, which have linear precision.

The corresponding toric variety is the Veronese surface of degree  $n$ .

Choosing control points, get Bézier triangle of degree  $n$ .

This picture is a cubic Bézier triangle.



# Digression: algebraic statistics

In algebraic statistics, the probability simplex is identified with the positive part,  $\mathbb{RP}_{>}^n$ , of  $\mathbb{RP}^n$ , and its subvarieties  $X_{w,\mathcal{A}}$  are called *toric statistical models*.

For example, the subvariety corresponding to the Bézier triangle is the *trinomial distribution*.

The algebraic moment map  $\mu: \mathbb{RP}_{>}^n \rightarrow \Delta$  is called the *expectation map*, and, for  $p \in \mathbb{RP}_{>}^n$ , the point  $\mu^{-1}(\mu(p)) \in X_{w,\mathcal{A}}$  is the *maximum likelihood estimator*, the distribution in the model which ‘best’ explains  $p$ .

*Iterative proportional fitting (IPF)* is a fast numerical algorithm to compute  $\mu^{-1}$ . IPF may be useful in modeling.

In statistics, linear precision corresponds to maximum likelihood degree 1. In that case, IPF converges in one iteration. Many statistical models have MLD 1.

# Linear precision for toric patches

Given the data  $(w, \mathcal{A})$  of a toric patch, define a polynomial

$$F_{w, \mathcal{A}} := \sum_{\mathbf{a} \in \mathcal{A}} w_{\mathbf{a}} x^{\mathbf{a}},$$

where  $x^{\mathbf{a}}$  is the multivariate monomial.

**Theorem (G-S).** *A toric patch  $(w, \mathcal{A})$  has linear precision if and only if*

$$\mathbb{C}^d \ni x \longmapsto \left( x_1 \frac{\partial F_{w, \mathcal{A}}}{\partial x_1}, x_2 \frac{\partial F_{w, \mathcal{A}}}{\partial x_2}, \dots, x_d \frac{\partial F_{w, \mathcal{A}}}{\partial x_d} \right) \quad (*)$$

*defines a birational isomorphism  $\mathbb{C}^d \dashrightarrow \mathbb{C}^d$ .*

We say that  $F$  *defines a toric polar Cremona transformation*, when its toric derivatives  $(*)$  define a birational map.

# Linear precision for toric surface patches

**Theorem (GvB-R-S).** *A polynomial  $F \in \mathbb{C}[x, y]$  defines a toric polar Cremona transformation if and only if it is equivalent to one of the following forms*

- $(x + y + 1)^n$  ( $\iff$  *Bézier triangle*).
- $(x + 1)^m(y + 1)^n$  ( $\iff$  *tensor-product patch*).
- $(x + 1)^m((x + 1)^d + y)^n$  ( $\iff$  *trapezoidal patch*).
- $x^2 + y^2 + z^2 - 2(xy + xz + yz)$ . (*no analog in modeling*).

In particular, this classifies toric surface patches that enjoy linear precision.

# Future work?

- When is it possible to tune a patch (move the points  $\mathcal{A}$ ) to achieve linear precision?
- Linear precision for 3- and higher-dimensional patches.
- Algebraic statistics furnishes many higher dimensional toric patches with linear precision.
- Can iterative proportional fitting be useful to compute patches?

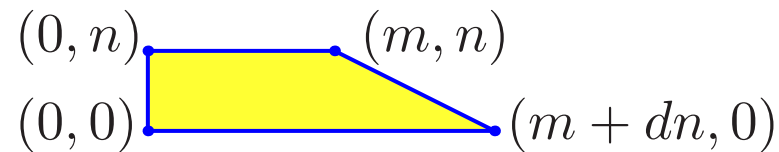
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# Trapezoidal patch

Let  $n, d \geq 1$  and  $m \geq 0$  be integers, and set

$$\mathcal{A} := \{(i, j) : 0 \leq j \leq n \text{ and } 0 \leq i \leq m + dn - dj\},$$

which are the integer points inside the trapezoid below.



Choose weights  $w_{i,j} := \binom{n}{j} \binom{m+dn-dj}{i}$ . Then the toric Bézier functions are

$$\beta_{i,j}(s, t) := \binom{n}{j} \binom{m+dn-dj}{i} s^i (m + dn - s - dt)^{m+dn-dj-i} t^j (n - t)^{n-j}.$$

# Bibliography

- Rimvydas Krasauskas, *Toric surface patches*, Adv. Comput. Math. **17** (2002), no. 1-2, 89–133.
- Luis Garcia-Puente and Frank Sottile, *Linear precision for parametric patches*, 2007, ArXiv:0706.2116.
- Hans-Christian Graf van Bothmer, Kristian Ranestad, and Frank Sottile, *Linear precision for toric surface patches*, 2008. ArXiv:0806.3230.