Name	NetID_	
MATH 308	Final Exam	Spring 2009
Section 511		P. Yasskin

1	/20	4	/10
2	/20	5	/20
3	/10	6	/20
Total			/100

- 1. (20 points) Consider the second order non-homogeneous differential equation  $y'' + 5y' + 4y = 6e^{-x} + 8x^2 + 3$ .
  - **a**. Find two solutions of the homogeneous differential equation y'' + 5y' + 4y = 0. Verify they are linearly independent. Give the general homogeneous solution.

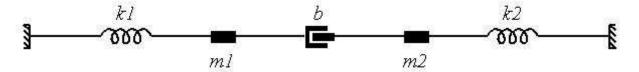
**b**. Use undetermined coefficients to find a particular non-homogeneous solution.

**c**. Find the non-homogeneous solution satisfying the initial conditions: y(0) = 6 y'(0) = 3.

- **2**. (20 points) Consider the second order homogeneous differential equation  $x^2y'' + (-2x 2x^2)y' + (2 + 2x + x^2)y = 0$ .
  - **a.** Verify  $y_1 = xe^x$  is a solution. (Show your algebra!)

**b**. Use reduction of order (similar to variation of parameters) to find a second solution. (Be careful with your algebra. Nearly everything should cancel.)

3. (10 points) Consider the mass-spring-piston system shown in the figure.

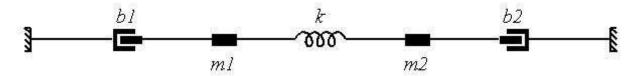


The masses are  $m_1 = 6 \text{ kg}$  and  $m_2 = 8 \text{ kg}$ .

The spring constants are  $k_1 = 3$  N/m and  $k_2 = 5$  N/m.

The piston pulls in with a force proportional to the velocity with which it is expanding or pushes out with a force proportional to the velocity with which it is contracting with a proportionality constant which is the drag coefficient of b=4 N-sec/m. Initially, mass  $m_1$  is moved 2 m to the right and given a velocity of 5 m/sec to the left, while mass  $m_2$  is moved 4 m to the left and given a velocity of 3 m/sec to the right. Let x(t) be the displacement of  $m_1$  from it's rest position measured positive to the right. Let y(t) be the displacement of  $m_2$  from it's rest position measured positive to the right. Set up **second** order **differential equations** and **initial conditions** for x and y. **Do not solve** the equations.

**4**. (10 points) Consider the mass-spring-piston system shown in the figure.



The masses are  $m_1 = 1$  kg and  $m_2 = 1$  kg. The spring constants is k = 7 N/m. The drag coefficient for the pistons are  $b_1 = 5 \text{ N-sec/m}$  and  $b_2 = 6 \text{ N-sec/m}$ . Each piston pulls in with a force proportional to the velocity with which it is expanding or pushes out with a force proportional to the velocity with which it is contracting. Initially, mass  $m_1$  is moved 1 m to the right and given a velocity of 2 m/sec to the right, while mass  $m_2$  is moved 3 m to the left and given a velocity of 4 m/sec to the left. Let x(t) be the displacement of  $m_1$  from it's rest position measured positive to the right. Let y(t) be the displacement of  $m_2$  from it's rest position measured positive to the right. The second order differential equations and initial conditions for x and y are

$$m_1 x'' = -b_1 x' + k(y - x)$$
 or  $x'' = -5x' + 7(y - x)$   $x(0) = -5x' + 7(y - x)$ 

$$m_2 y'' = -b_2 y' - k(y - x)$$
 or  $y'' = -6y' - 7(y - x)$   $y(0) = -3$   $y'(0)$ 

Let 
$$p = x'$$
 and  $q = y'$ .

Let p=x' and q=y'. Set up **first** order **differential equations**  $\vec{x}'=A\vec{x}$  for  $\vec{x}=$ and **initial conditions** for  $\vec{x}(0)$ .

Do not solve the equations.

**5**. (20 points) Consider the first order differential equations  $\vec{x}' = A\vec{x}$ 

where 
$$\vec{x} = \begin{pmatrix} x \\ p \\ y \\ q \end{pmatrix}$$
 and  $A = \begin{pmatrix} 0 & 1 & 0 & 0 \\ -1 & -3 & 1 & 0 \\ 0 & 0 & 0 & 1 \\ 1 & 0 & -1 & -3 \end{pmatrix}$ .

Find the **eigenvalues** and **eigenvectors** of A.

Then find the **general solution** of the differential equation. (Vector form is OK.) HINT: Two of the eigenvalues and eigenvectors are:

$$r = -2 \vec{u}_{-2} = \begin{pmatrix} 1 \\ -2 \\ -1 \\ 2 \end{pmatrix} r = -3 \vec{u}_{-3} = \begin{pmatrix} -1 \\ 3 \\ -1 \\ 3 \end{pmatrix}$$

6. (20 points) Consider the first order **non-homogeneous** system of differential equations

$$\vec{x}' = A\vec{x} + \vec{f}$$
 where  $\vec{x} = \begin{pmatrix} x \\ p \\ y \\ q \end{pmatrix}$  and  $A = \begin{pmatrix} 0 & 1 & 0 & 0 \\ -1 & 0 & 1 & 3 \\ 0 & 0 & 0 & 1 \\ 1 & 3 & -1 & 0 \end{pmatrix}$  and  $\vec{f} = \begin{pmatrix} 3 \\ -t \\ 0 \\ t \end{pmatrix}$ .

The general solution of the corresponding homogeneous differential equation is

$$\vec{x} = c_0 \vec{u}_0 + c_1 e^{-t} \vec{u}_{-1} + c_2 e^{-2t} \vec{u}_{-2} + c_3 e^{3t} \vec{u}_3$$
 where

$$\vec{u}_0 = \begin{pmatrix} 1 \\ 0 \\ 1 \\ 0 \end{pmatrix} \qquad u_{-1} = \begin{pmatrix} 1 \\ -1 \\ -1 \\ 1 \end{pmatrix} \qquad \vec{u}_{-2} = \begin{pmatrix} 1 \\ -2 \\ -1 \\ 2 \end{pmatrix} \qquad \vec{u}_3 = \begin{pmatrix} 1 \\ 3 \\ 1 \\ 3 \end{pmatrix}$$

Use undetermined coefficients to determine a particular solution.

HINTS: Look for a solution of the form  $\vec{x}_p = \vec{a} + t\vec{b}$ .

First solve for  $\vec{b}$  and keep the arbitrary constant. Then solve for  $\vec{a}$ . If you have time check your answer in the differential equation.