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MATH 311	Exam 1	Fall 2000
Section 502		P. Yasskin

1	/10	6	/10
2	/10	7	/15
5	/10	8	/15
So	cantron		/30

**1.** (10 points) Find the inverse of 
$$A = \begin{pmatrix} -1 & 0 & 3 \\ 0 & 1 & 4 \\ 1 & 1 & 0 \end{pmatrix}$$
.

Use it to solve  $XA = \begin{pmatrix} 0 & 0 & 2 \\ 2 & 1 & 0 \\ 0 & 2 & 0 \end{pmatrix}$ .

2. (10 points) Consider the polynomials

$$p_1(x) = 1 - x^2$$
  
 $p_2(x) = 2 - x - x^2$   
 $p_3(x) = 1 - x$ 

and the vector space

## W =**Span** $(p_1, p_2, p_3).$

Find a subset of  $\{p_1, p_2, p_3\}$  which is a basis for *W*. Prove it spans *W* and is linearly independent.

**3**. Consider the vector space  $P_3$ , the set of polynomials of degree 3 or less?

• (5 points) Scantron #1 Which of the following is NOT a subspace of  $P_3$ ?

**a.**  $A = \{ p \in P_3 | p(0) = 0 \}$  **b.**  $B = \{ p \in P_3 | p(1) = 0 \}$  **c.**  $C = \{ p \in P_3 | p(0) = p(1) \}$  **d.**  $D = \{ p \in P_3 | p(0) + p(1) = 0 \}$ **e.**  $E = \{ p \in P_3 | p(0) = 1 \}$ 

4. Consider the vector space  $\mathbf{R}^+$  of all positive real numbers with the operations of Vector Addition:  $x \oplus y = xy$  (real number addition) Scalar Multiplication:  $\alpha \circ x = x^{\alpha}$  (real number exponentiation)

• (5 points) Scantron #2 Translate the vector identity

 $0 \circ x = \vec{0}$ 

into ordinary arithmetic.

**a.**  $1^{x} = 1$  **b.**  $x^{0} = 1$  **c.**  $0^{x} = 0$  **d.**  $x^{1} = x$ **e.**  $0^{x} = 1$  5. Consider the linear map  $L : \mathbb{R}^3 \to \mathbb{R}^4$  given by  $L(\vec{x}) = A\vec{x}$  where  $A = \begin{pmatrix} 1 & -1 & 0 \\ 0 & 1 & 2 \\ 2 & 0 & 4 \\ 3 & -1 & 4 \end{pmatrix}$ .

• (10 points) Solve 
$$L(\vec{x}) = \begin{pmatrix} 2 \\ -1 \\ 2 \\ 4 \end{pmatrix}$$
.

- (5 points) Scantron #3 Describe the solution set:
  - a. No Solutions
  - **b**. Unique Solution (Point in  $\mathbf{R}^3$ )
  - c.  $\infty$ -Many Solutions (Line in  $\mathbb{R}^3$ )
  - **d**.  $\infty$ -Many Solutions (Plane in  $\mathbb{R}^3$ )
  - e.  $\infty$ -Many Solutions (All of  $\mathbb{R}^3$ )
- (5 points) Scantron #4 Is L a one-to-one function?
  - a. Yes
  - **b**. No

6. Again consider the linear map  $L : \mathbb{R}^3 \to \mathbb{R}^4$  given by  $L(\vec{x}) = A\vec{x}$  where  $A = \begin{pmatrix} 1 & -1 & 0 \\ 0 & 1 & 2 \\ 2 & 0 & 4 \\ 3 & -1 & 4 \end{pmatrix}$ .

• (10 points) Solve 
$$L(\vec{x}) = \begin{pmatrix} 1 \\ 1 \\ 1 \\ 1 \end{pmatrix}$$
.

- (5 points) Scantron #5 Describe the solution set:
  - a. No Solutions
  - **b**. Unique Solution (Point in **R**<sup>3</sup>)
  - c.  $\infty$ -Many Solutions (Line in  $\mathbb{R}^3$ )
  - d.  $\infty$ -Many Solutions (Plane in  $\mathbb{R}^3$ )
  - e.  $\infty$ -Many Solutions (All of  $\mathbb{R}^3$ )
- (5 points) Scantron #6 Is L an onto function?
  - a. Yes
  - **b**. No

- 7. Again consider the linear map  $L : \mathbb{R}^3 \to \mathbb{R}^4$  given by  $L(\vec{x}) = A\vec{x}$  where  $A = \begin{pmatrix} 1 & -1 & 0 \\ 0 & 1 & 2 \\ 2 & 0 & 4 \\ 3 & -1 & 4 \end{pmatrix}$ .
  - (5 points) Find Ker(L), the kernel (or null space) of L.

- (5 points) Give a basis for Ker(L). (No proof)
- (5 points) What is the dimension of Ker(L)? (No proof)

- 8. Again consider the linear map  $L : \mathbb{R}^3 \to \mathbb{R}^4$  given by  $L(\vec{x}) = A\vec{x}$  where  $A = \begin{pmatrix} 1 & -1 & 0 \\ 0 & 1 & 2 \\ 2 & 0 & 4 \\ 3 & -1 & 4 \end{pmatrix}$ .
  - (5 points) Find Im(L), the image (or range) of L.

• (5 points) Give a basis for Im(L). (No proof)

• (5 points) What is the dimension of Im(L)? (No proof)