

6. (6 pts) Is the function L one-to-one? Why?

7. (6 pts) Is the function L onto? Why?

8. (6 pts) Find the matrix of the linear map L relative to the e basis. Call it A .

$$A = \begin{pmatrix} & & \\ & & \\ & & \end{pmatrix}$$

9. (10 pts) Find the eigenvalues of A .

$$\lambda_1 = \square \quad \lambda_2 = \square \quad \lambda_3 = \square$$

10. (15 pts) Find the eigenvectors for each eigenvalue. Call them \vec{v}_1 , \vec{v}_2 and \vec{v}_3 .

a. $\lambda_1 = \square$:

$$\vec{v}_1 = \begin{pmatrix} \\ \end{pmatrix}$$

b. $\lambda_2 = \square$:

$$\vec{v}_2 = \begin{pmatrix} \\ \end{pmatrix}$$

c. $\lambda_3 = \square$:

$$\vec{v}_3 = \begin{pmatrix} \\ \\ \end{pmatrix}$$

11. (6 pts) Find the eigenpolynomials for each eigenvalue. Call them q_1 , q_2 and q_3 .
Verify they are eigenpolynomials by checking that $L(q_k) = \lambda_k q_k$ using the definition of L .

$q_1 = \square$ $L(q_1) =$

$q_2 = \square$ $L(q_2) =$

$q_3 = \square$ $L(q_3) =$

12. (6 pts) The eigenpolynomials $q = (q_1, q_2, q_3)$ form a second basis for P_3 . Find the matrix of the linear map L relative to the q basis. Call it D .

$$D = \begin{pmatrix} & & \\ & & \\ & & \end{pmatrix}_{q \leftarrow q}$$

13. (15 pts) Find the change of basis matrices C and C .

$$C = \begin{pmatrix} & & \\ & & \\ & & \end{pmatrix}_{e \leftarrow q}$$

$$C = \begin{pmatrix} & & \\ & & \\ & & \end{pmatrix}_{q \leftarrow e}$$

14. (5 pts) Verify your matrices satisfy $\begin{matrix} C & D & C \\ e \leftarrow q & q \leftarrow q & q \leftarrow e \end{matrix} = \begin{matrix} A \\ e \leftarrow e \end{matrix}$.

15. (5 pts) Compute $\begin{pmatrix} A \\ e \leftarrow e \end{pmatrix}^5$.