Name\_\_\_\_\_

Math 311	Exam 3	Spring 2010
Section 502	Solutions	P. Yasskin

Consider the vector space  $P_3$  of polynomials with degree less than 3 with standard basis

$$e_1 = 1$$
  $e_2 = x$   $e_3 = x^2$ 

and the linear operator

$$L: P_3 \to P_3: L(p) = (x-2)\frac{dp}{dx}$$

**1.** (2 pts) What is  $\dim P_3$ ? What is the size of the matrix A of the linear map L?

 $\dim P_3 = 3$  A is a  $3 \times 3$  matrix.

**2**. (2 pts) Let  $p = a + bx + cx^2$ . Compute L(p).

$$L(p) = (x - 2)\frac{dp}{dx} = (x - 2)(b + 2cx)$$

**3**. (10 pts) Identify the kernel of *L*, a basis for the kernel, and the dimension of the kernel.

 $L(p) = (-2b) + (b - 4c)x + (2c)x^{2} = 0$   $\Rightarrow -2b = 0 \quad b - 4c = 0 \quad 2c = 0 \quad \Rightarrow \quad b = c = 0 \quad \Rightarrow \quad p = a$  $Ker(L) = \{p = a\} = \{\text{constant polynomials}\} = Span(1) \quad basis = \{1\} \quad \dim Ker(L) = 1$ 

**4**. (2 pts) What does the kernel of *L*, (found in part 2), say about one of the eigenvalues of *L*, and the eigenpolynomial(s) for that eigenvalue? No new computations!

 $L(1) = 0 \cdot 1$  So 0 is an eigenvalue and 1 is the eigenpolynomial.

5. (10 pts) Identify the image of *L*, a basis for the image, and the dimension of the image.

$$L(p) = (-2b) + (b - 4c)x + (2c)x^{2} = b(-2 + x) + c(-4x + 2x^{2})$$
  
$$Im(L) = \{L(p)\} = Span(-2 + x, -4x + 2x^{2}) \qquad basis = \{-2 + x, -4x + 2x^{2}\} \qquad \dim Im(L) = 2$$

6. (6 pts) Is the function L one-to-one? Why?

*L* is not 1 - 1 because  $Ker(L) \neq \{0\}$ 

- 7. (6 pts) Is the function L onto? Why?
  - L is not onto because dim Im(L) = 2 but dim  $Codom(L) = \dim P_3 = 3$

1,2	/ 4	10	/15
3,4	/12	11,12	/12
5	/10	13	/15
6,7	/12	14,15	/10
8,9	/16	Total	/106

8. (6 pts) Find the matrix of the linear map L relative to the e basis. Call it  $A_{e\leftarrow e}$ .

$$L(e_1) = L(1) = = (x-2)(0) = 0 = 0$$

$$L(e_2) = L(x) = = (x-2)(1) = -2 + x = -2e_1 + e_2$$

$$L(e_3) = L(x^2) = = (x-2)(2x) = -4x + 2x^2 = -4e_2 + 2e_3$$

$$A = \begin{pmatrix} 0 & -2 & 0 \\ 0 & 1 & -4 \\ 0 & 0 & 2 \end{pmatrix}$$

**9**. (10 pts) Find the eigenvalues of  $A_{e \leftarrow e}$ .

$$\det(A - \lambda \mathbf{1}) = \det\begin{pmatrix} -\lambda & -2 & 0\\ 0 & 1 - \lambda & -4\\ 0 & 0 & 2 - \lambda \end{pmatrix} = -\lambda(1 - \lambda)(2 - \lambda) = 0 \implies \lambda = 0, 1, 2$$

**10**. (15 pts) Find the eigenvectors for each eigenvalue. Call them  $\vec{v}_1$ ,  $\vec{v}_2$  and  $\vec{v}_3$ .

$$\begin{aligned} A\vec{v} &= \lambda\vec{v} \quad (A - \lambda \mathbf{1})\vec{v} = 0 \quad \begin{pmatrix} -\lambda & -2 & 0 & | & 0 \\ 0 & 1 - \lambda & -4 & | & 0 \\ 0 & 0 & 2 - \lambda & | & 0 \end{pmatrix} \\ \mathbf{a}. \ \lambda_1 &= 0: \quad \begin{pmatrix} 0 & -2 & 0 & | & 0 \\ 0 & 1 & -4 & | & 0 \\ 0 & 0 & 2 & | & 0 \end{pmatrix} \overset{R_2}{\underset{R_1 + 2R_2}{\stackrel{1}{2}R_3} \implies \begin{pmatrix} 0 & 1 & -4 & | & 0 \\ 0 & 0 & 1 & | & 0 \\ 0 & 0 & -8 & | & 0 \end{pmatrix} \overset{R_1 + 4R_2}{\underset{R_3 + 3R_2}{\stackrel{1}{2}R_3 + 8R_2} \implies \begin{pmatrix} 0 & 1 & 0 & | & 0 \\ 0 & 0 & 1 & | & 0 \\ 0 & 0 & -8 & | & 0 \end{pmatrix} \overset{R_1 + 4R_2}{\underset{R_3 + 3R_2}{\stackrel{1}{2}R_3 + 8R_2} \implies \begin{pmatrix} 0 & 1 & 0 & | & 0 \\ 0 & 0 & 1 & | & 0 \\ 0 & 0 & -8 & | & 0 \end{pmatrix} \overset{R_1 + 4R_2}{\underset{R_3 + 3R_2}{\stackrel{1}{2}R_3 + 8R_2} \implies \begin{pmatrix} 0 & 1 & 0 & | & 0 \\ 0 & 0 & 0 & | & 0 \end{pmatrix} \end{aligned}$$

$$\begin{aligned} \mathbf{b}. \ \lambda_2 &= 1: \qquad \begin{pmatrix} -1 & -2 & 0 & | & 0 \\ 0 & 0 & -4 & | & 0 \\ 0 & 0 & -4 & | & 0 \\ 0 & 0 & -4 & | & 0 \\ 0 & 0 & -4 & | & 0 \\ 0 & 0 & 0 & | & 0 \end{pmatrix} \overset{R_2 + 4R_3}{\underset{R_2 + 4R_3}{\stackrel{1}{2}R_3 \implies 1} \implies \begin{pmatrix} 1 & 2 & 0 & | & 0 \\ 0 & 0 & 1 & | & 0 \\ 0 & 0 & 0 & | & 0 \end{pmatrix} \end{aligned}$$

$$\begin{aligned} \mathbf{c}. \ \lambda_3 &= 2: \qquad \begin{pmatrix} -2 & -2 & 0 & | & 0 \\ 0 & -1 & -4 & | & 0 \\ 0 & 0 & 0 & | & 0 \end{pmatrix} \overset{-\frac{1}{2}R_1}{\underset{R_2 + 2R_3}{\stackrel{1}{2}R_3 \implies 2} \implies \begin{pmatrix} 1 & 1 & 0 & | & 0 \\ 0 & 0 & 1 & | & 0 \\ 0 & 0 & 0 & | & 0 \end{pmatrix}$$

$$\begin{aligned} \mathbf{c}. \ \lambda_3 &= 2: \qquad \begin{pmatrix} -2 & -2 & 0 & | & 0 \\ 0 & -1 & -4 & | & 0 \\ 0 & 0 & 0 & | & 0 \end{pmatrix} \overset{-\frac{1}{2}R_1}{\underset{R_2 + 2R_3 \implies 2}{\stackrel{1}{2}R_3 \implies 2} \implies \begin{pmatrix} 1 & 1 & 0 & | & 0 \\ 0 & 1 & 4 & | & 0 \\ 0 & 0 & 0 & | & 0 \end{pmatrix}$$

$$\begin{aligned} \mathbf{c}. \ \lambda_3 &= 2: \qquad \begin{pmatrix} -2 & -2 & 0 & | & 0 \\ 0 & -1 & -4 & | & 0 \\ 0 & 0 & 0 & | & 0 \end{pmatrix} \overset{-\frac{1}{2}R_1}{\underset{R_2 + 2R_3 \implies 2}{\stackrel{1}{2}R_3 \implies 2} \implies \begin{pmatrix} 1 & 1 & 0 & | & 0 \\ 0 & 1 & 4 & | & 0 \\ 0 & 0 & 0 & | & 0 \end{pmatrix}$$

$$\begin{aligned} \mathbf{c}. \ \lambda_3 &= 2: \qquad \begin{pmatrix} -2 & -2 & 0 & | & 0 \\ 0 & -1 & -4 & | & 0 \\ 0 & 0 & 0 & | & 0 \end{pmatrix} \overset{-\frac{1}{2}R_1}{\underset{R_2 + 2}{\stackrel{1}{2}R_3 \implies 2} \implies \begin{pmatrix} 1 & 1 & 0 & | & 0 \\ 0 & 1 & 4 & | & 0 \\ 0 & 0 & 0 & | & 0 \end{pmatrix}$$

$$\begin{aligned} \mathbf{c}. \ \lambda_3 &= 2: \qquad \begin{pmatrix} x & y \\ y &= x & x & x \\ y &= x & x & y \\ z &= r & x & x & y \\ z &= r & x & x & y \\ z &= r & x & x & y \\ z &= r & x & x & y \\ z &= r & x & x & y \\ z &= r & x & x & y \\ z &= r & x & x & y \\ z &= r & x & x & y \\ z &= r & x & x & y \\ z &= r & x & x & y \\ z &= r & x & x & y \\ z &= r & x & x & y \\ z &= r & x & x & y \\ z &= r & x & x & y$$

**11.** (6 pts) Find the eigenpolynomials for each eigenvalue. Call them  $q_1$ ,  $q_2$  and  $q_3$ . Verify they are eigenpolynomials by checking that  $L(q_k) = \lambda_k q_k$  using the definition of *L*.

 $\begin{array}{l} q_1 = e\vec{v}_1 = 1 \quad q_2 = e\vec{v}_2 = -2 + x \quad q_3 = e\vec{v}_3 = 4 - 4x + x^2 \\ L(q_1) = L(1) = (x - 2)(0) = 0 = 0q_1 \\ L(q_2) = L(-2 + x) = (x - 2)(1) = -2 + x = 1q_2 \\ L(q_3) = L(4 - 4x + x^2) = (x - 2)(-4 + 2x) = 8 - 8x + 2x^2 = 2(4 - 4x + x^2) = 2q_3 \end{array}$ 

**12.** (6 pts) The eigenpolynomials  $q = (q_1, q_2, q_3)$  form a second basis for  $P_3$ . Find the matrix of the linear map *L* relative to the *q* basis. Call it *D*.

$$L(q_1) = 0q_1$$

$$L(q_2) = 1q_2$$

$$L(q_3) = 2q_3$$

$$D = \begin{pmatrix} 0 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 2 \end{pmatrix}$$

**13**. (15 pts) Find the change of basis matrices  $\underset{e \leftarrow a}{C}$  and  $\underset{a \leftarrow e}{C}$ .

$$q_{1} = 1 = e_{1} \qquad q_{2} = -2 + x = -2e_{1} + e_{2} \qquad q_{3} = 4 - 4x + x^{2} = 4e_{1} - 4e_{2} + e_{3}$$

$$C_{e \leftarrow q} = \begin{pmatrix} 1 & -2 & 4 \\ 0 & 1 & -4 \\ 0 & 0 & 1 \end{pmatrix}$$
Equivalently, the eigenvectors go in the columns.
$$\begin{pmatrix} 1 & -2 & 4 & | & 1 & 0 & 0 \\ 0 & 1 & -4 & | & 0 & 1 & 0 \\ 0 & 0 & 1 & | & 0 & 0 & 1 \end{pmatrix} \Rightarrow \begin{pmatrix} 1 & 0 & 0 & | & 1 & 2 & 4 \\ 0 & 1 & 0 & | & 0 & 1 & 4 \\ 0 & 0 & 1 & | & 0 & 0 & 1 \end{pmatrix} \xrightarrow{C}_{q \leftarrow e} = \begin{pmatrix} 1 & 2 & 4 \\ 0 & 1 & 4 \\ 0 & 0 & 1 & 0 \end{pmatrix}$$

**14**. (5 pts) Verify your matrices satisfy  $C_{e\leftarrow q} \quad D_{q\leftarrow q} \quad C_{e\leftarrow e} = A_{e\leftarrow e}$ .

$$\begin{array}{ccc} C & D & C \\ e \leftarrow q & q \leftarrow e \end{array} = \left( \begin{array}{ccc} 1 & -2 & 4 \\ 0 & 1 & -4 \\ 0 & 0 & 1 \end{array} \right) \left( \begin{array}{ccc} 0 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 2 \end{array} \right) \left( \begin{array}{ccc} 1 & 2 & 4 \\ 0 & 1 & 4 \\ 0 & 0 & 1 \end{array} \right) = \left( \begin{array}{ccc} 1 & -2 & 4 \\ 0 & 1 & -4 \\ 0 & 0 & 1 \end{array} \right) \left( \begin{array}{ccc} 0 & 0 & 0 \\ 0 & 1 & 4 \\ 0 & 0 & 2 \end{array} \right) \\ = \left( \begin{array}{ccc} 0 & -2 & 0 \\ 0 & 1 & -4 \\ 0 & 0 & 2 \end{array} \right) = \begin{array}{c} A \\ e \leftarrow e \end{array}$$

 $15. (5 \text{ pts}) \text{ Compute } \begin{pmatrix} A \\ e \leftarrow e \end{pmatrix}^5. \qquad \begin{pmatrix} A \\ e \leftarrow e \end{pmatrix}^5 = \begin{pmatrix} C \\ e \leftarrow q \end{pmatrix} \begin{pmatrix} D \\ q \leftarrow e \end{pmatrix}^5 = \begin{pmatrix} C \\ e \leftarrow q \end{pmatrix}^5 = \begin{pmatrix}$