Name	1-8	/40	10	/20		
Math 311 Section 503	Final Exam Version A	Spring 2015 P. Yasskin	9	/16	11	/28
Multiple Choice: 5 points each. No Part Credit					Total	/104

Work Out: Points indicated. Show all work.

1. Hydrocloric acid (*HCl*) and sodium hydroxide (*NaOH*) react to produce sodium chloride (*NaCl*) and water ( $H_2O$ ) according to the chemical equation:

$$aHCl + bNaOH \rightarrow cNaCl + dH_2O$$

Which of the following is the augmented matrix which is used to solve this chemical equation? (Put the elements in the order *H*, *Cl*, *Na*, *O*.)

- **2**. Suppose A is nilpotent, i.e.  $A^2 = 0$ . Which of the following is true?
  - **a**. A + 1 is invertible and  $(A + 1)^{-1} = A 1$  **b**. A + 1 is invertible and  $(A + 1)^{-1} = 1 - A$  **c**. A + 1 is invertible and  $(A + 1)^{-1} = 1 - 2A$  **d**. A + 1 is invertible and  $(A + 1)^{-1} = 1 + A$ **e**. A + 1 is not invertible

**3**. Consider the vector space M(2,2) of  $2 \times 2$  matrices with the basis

$$E_{1} = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} \qquad E_{2} = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} \qquad E_{3} = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \qquad E_{4} = \begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix}$$

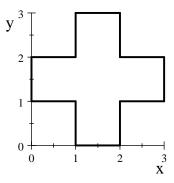
Which of the following are the components of the matrix  $A = \begin{pmatrix} 9 & 5 \\ 1 & 1 \end{pmatrix}$  relative to the *E* basis?

**a.** 
$$(A)_E = \begin{pmatrix} 2 & 1 & 4 & 3 \end{pmatrix}^{\mathsf{T}}$$
  
**b.**  $(A)_E = \begin{pmatrix} 1 & 2 & 3 & 4 \end{pmatrix}^{\mathsf{T}}$   
**c.**  $(A)_E = \begin{pmatrix} 4 & 5 & 2 & 3 \end{pmatrix}^{\mathsf{T}}$   
**d.**  $(A)_E = \begin{pmatrix} 5 & 4 & 3 & 2 \end{pmatrix}^{\mathsf{T}}$   
**e.**  $(A)_E = \begin{pmatrix} 5 & -4 & 3 & -2 \end{pmatrix}^{\mathsf{T}}$ 

**4**. Consider the vector space  $C_2([0,1])$  of real valued function on the interval [0,1] whose second derivatives exist and are continuous with the inner product  $\langle f,g \rangle = \int_{-1}^{1} f(x)g(x) dx$ . Consider the subspace  $V = Span(x,x^2)$  spanned by the basis  $v_1 = x$ ,  $v_2 = x^2$ . Which of the following is an orthonormal basis for V?

**a.** 
$$u_1 = x$$
  $u_2 = x^2$   
**b.**  $u_1 = x$   $u_2 = x^2 - \frac{3}{4}x$   
**c.**  $u_1 = \sqrt{\frac{3}{2}}x$   $u_2 = \sqrt{\frac{5}{2}}x^2$   
**d.**  $u_1 = \sqrt{\frac{5}{2}}x$   $u_2 = \sqrt{\frac{7}{2}}x^2$   
**e.**  $u_1 = \sqrt{2}x$   $u_2 = 4\sqrt{5}x^2 - 3\sqrt{5}x$ 

- **5**. Consider the second derivative linear operator  $L: P_6 \rightarrow P_6: L(p) = \frac{d^2p}{dx^2}$  on the space of polynomials of degree less than 6. Find the kernel, Ker(L). HINT: Let  $p = a + bx + cx^2 + dx^3 + ex^4 + fx^5$ .
  - **a**. Ker(L) = Span(1)
  - **b**. Ker(L) = Span(1, x)
  - **c**.  $Ker(L) = Span(1, x, x^2)$
  - **d**.  $Ker(L) = Span(x^2, x^3, x^4, x^5)$
  - **e**.  $Ker(L) = Span(x, x^2, x^3, x^4, x^5)$
- 6. Consider the second derivative linear operator  $L: P_6 \rightarrow P_6: L(p) = \frac{d^2p}{dx^2}$  on the space of polynomials of degree less than 6. Find the image, Im(L). HINT: Let  $p = a + bx + cx^2 + dx^3 + ex^4 + fx^5$ .
  - **a**.  $\operatorname{Im}(L) = Span(1)$
  - **b**.  $\operatorname{Im}(L) = \operatorname{Span}(1, x)$
  - **c**. Im(*L*) = Span(1,  $x, x^2, x^3$ )
  - **d**. Im(*L*) = Span( $x^2, x^3, x^4, x^5$ )
  - **e**. Im(L) = Span( $x, x^2, x^3, x^4, x^5$ )
- 7. Compute the line integral  $\oint \vec{F} \cdot d\vec{s}$  clockwise around the complete boundary of the plus sign, shown at the right, for the vector field  $\vec{F} = (4x^3 + 2y, 4y^3 3x)$ .
  - **a**. 25
  - **b**. 5
  - **c**. 0
  - **d**. -5
  - **e**. -25



8. Consider the vector space M(2,2) of  $2 \times 2$  matrices. Let  $A = \begin{pmatrix} 1 & 0 \\ 0 & 2 \end{pmatrix}$ . Consider the linear

function,  $L: M(2,2) \rightarrow M(2,2): L(X) = AX - XA$ . Which of the following is not an eigenvalue and corresponding eigenmatrix (eigenvector) of *L*?

HINT: Let 
$$X = \begin{pmatrix} x & y \\ z & w \end{pmatrix}$$
.  
a.  $\lambda = -1$   $X = \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix}$   
b.  $\lambda = 0$   $X = \begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix}$   
c.  $\lambda = 0$   $X = \begin{pmatrix} 0 & 0 \\ 0 & 1 \end{pmatrix}$   
d.  $\lambda = 1$   $X = \begin{pmatrix} 0 & 0 \\ 0 & 1 \end{pmatrix}$   
e.  $\lambda = 2$   $X = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}$ 

**9**. (16 points) Which of the following is an inner product on  $\mathbb{R}^2$ ? If not, why not? Put ×'s in the correct boxes. No part credit. Let  $\vec{x} = (x_1, x_2), \quad \vec{y} = (y_1, y_2).$ 

				Why not?			
		Inner Product?		Not	Not	Not	Positive but Not
	$\langle \vec{x}, \vec{y} \rangle =$	Yes	No	Symmetric	Linear	Positive	Positive Definite
a.	$x_1y_1 + 2x_2y_2$						
b.	$x_1^2 y_1^2 + 2x_2^2 y_2^2$						
<b>C</b> .	$x_1y_1 + 2x_1y_2 + 2x_2y_2$						
d.	$x_1y_1 - x_1y_2 - x_2y_1 + x_2y_2$						
е.	$x_1y_1 + x_1y_2 + x_2y_1 + x_2y_2$						
f.	$x_1y_1 + x_1y_2 + x_2y_1 + 2x_2y_2$						
<b>g</b> .	$x_1y_1 - x_1y_2 - x_2y_1 + 2x_2y_2$						
h.	$x_1y_1 - x_2y_2$						

**10**. (20 points) Let M(2,3) be the vector space of  $2 \times 3$  matrices. Consider the subspace  $V = Span(A_1, A_2, A_3, A_4)$  where

$$A_{1} = \begin{pmatrix} 1 & 1 & 0 \\ 2 & 3 & -2 \end{pmatrix}, A_{2} = \begin{pmatrix} 2 & 2 & 0 \\ 4 & 6 & -4 \end{pmatrix}, A_{3} = \begin{pmatrix} -1 & 0 & 2 \\ -3 & 0 & 0 \end{pmatrix}, A_{4} = \begin{pmatrix} 1 & 3 & 4 \\ 0 & 9 & -6 \end{pmatrix}$$

Find a basis for V. What is the  $\dim V$ ?

- 11. (28 points) Compute  $\iint_{H} \vec{F} \cdot d\vec{S}$  over the hemisphere  $z = \sqrt{25 x^2 y^2}$  oriented upward, for the vector field  $\vec{F} = (x^3 + 4y^2 + 4z^2, 4x^2 + y^3 + 4z^2, 4x^2 + 4y^2 + z^3)$ . HINT: Use Gauss' Theorem by following these steps:
  - **a**. Write out Gauss' Theorem for the Volume, *V*, which is the solid hemisphere  $0 \le z \le \sqrt{25 x^2 y^2}$ . Split up the boundary,  $\partial V$ , into two pieces, the hemisphere, *H*, and the disk, *D*, at the bottom. State orientations. Solve for the integral you want.

**b**. Compute the volume integral using spherical coordinates.

(continued)

**c**. Compute the other surface integral over *D* by parametrizing the disk, computing the tangent vectors and normal vector, checking the orientation, evaluating the vector field on the disk and doing the integral.

d. Solve for the original integral.