

Name \_\_\_\_\_ ID \_\_\_\_\_

1	/15	5	/10
2	/30	6	/10
3	/5	7	/10
4	/10	8	/10

MATH 311                      Exam 1                      Spring 2001  
 Section 200                      Solutions                      P. Yasskin

1. (15 points) Consider the three points

$$P = (1, 2, 3) \quad Q = (1, 3, 4) \quad R = (2, 3, 3)$$

a. (5 pts) Find parametric equations of the plane containing  $P$ ,  $Q$  and  $R$ .

$$\vec{PQ} = Q - P = (0, 1, 1) \quad \vec{PR} = R - P = (1, 1, 0) \quad X = P + s\vec{PQ} + t\vec{PR}$$

$$\begin{pmatrix} x \\ y \\ z \end{pmatrix} = \begin{pmatrix} 1 \\ 2 \\ 3 \end{pmatrix} + s \begin{pmatrix} 0 \\ 1 \\ 1 \end{pmatrix} + t \begin{pmatrix} 1 \\ 1 \\ 0 \end{pmatrix} = \begin{pmatrix} 1+t \\ 2+s+t \\ 3+s \end{pmatrix}$$

b. (5 pts) Find a non-parametric equation of the plane containing  $P$ ,  $Q$  and  $R$ .

$$\vec{N} = \vec{PQ} \times \vec{PR} = \begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ 0 & 1 & 1 \\ 1 & 1 & 0 \end{vmatrix} = \vec{i}(-1) - \vec{j}(-1) + \vec{k}(-1) = (-1, 1, -1)$$

$$\vec{N} \cdot X = \vec{N} \cdot P \quad -x + y - z = -1 + 2 - 3 = -2$$

c. (5 pts) Find an equation of the line through  $P$  perpendicular to the plane containing  $P$ ,  $Q$  and  $R$ .

$$X = P + t\vec{N} \quad \begin{pmatrix} x \\ y \\ z \end{pmatrix} = \begin{pmatrix} 1 \\ 2 \\ 3 \end{pmatrix} + t \begin{pmatrix} -1 \\ 1 \\ -1 \end{pmatrix} = \begin{pmatrix} 1-t \\ 2+t \\ 3-t \end{pmatrix}$$

2. (30 points) Consider the equations

$$2x + 4y + 6z = 4$$

$$v + y = 2$$

$$w + z = b$$

$$2v + w + x + 4y + 4z = 3$$

a. (5 pts) Write out the augmented matrix for this system.

$$\left( \begin{array}{cccccc|c} 0 & 0 & 2 & 4 & 6 & 4 \\ 1 & 0 & 0 & 1 & 0 & 2 \\ 0 & 1 & 0 & 0 & 1 & b \\ 2 & 1 & 1 & 4 & 4 & 3 \end{array} \right)$$

b. (10 pts) For what value(s) of  $b$  do there exist solutions?

$$\frac{1}{2}R_1 \text{ and reorder rows : } \left( \begin{array}{cccccc|c} 1 & 0 & 0 & 1 & 0 & 2 \\ 0 & 1 & 0 & 0 & 1 & b \\ 0 & 0 & 1 & 2 & 3 & 2 \\ 2 & 1 & 1 & 4 & 4 & 3 \end{array} \right)$$

$$R_4 - 2R_1 - R_2 - R_3 \rightarrow R_4 : \left( \begin{array}{cccccc|c} 1 & 0 & 0 & 1 & 0 & 2 \\ 0 & 1 & 0 & 0 & 1 & b \\ 0 & 0 & 1 & 2 & 3 & 2 \\ 0 & 0 & 0 & 0 & 0 & -3 - b \end{array} \right)$$

So there are solutions only if  $b = -3$ .

c. (10 pts) For those value(s) of  $b$ , find all solutions.

For  $b = -3$ , the equations reduce to

$$v + y = 2$$

$$w + z = -3$$

$$x + 2y + 3z = 2$$

So  $y$  and  $z$  are arbitrary and the solution is

$$\begin{pmatrix} v \\ w \\ x \\ y \\ z \end{pmatrix} = \begin{pmatrix} 2 - s \\ -3 - t \\ 2 - 2s - 3t \\ s \\ t \end{pmatrix} = \begin{pmatrix} 2 \\ -3 \\ 2 \\ 0 \\ 0 \end{pmatrix} + s \begin{pmatrix} -1 \\ 0 \\ -2 \\ 1 \\ 0 \end{pmatrix} + t \begin{pmatrix} 0 \\ -1 \\ -3 \\ 0 \\ 1 \end{pmatrix}$$

d. (5 pts) Circle the geometric description of the solution set:

point, line, 2-plane, 3-plane, 4-plane,  $\mathbf{R}^5$

3. (5 points) In  $\mathbf{R}^5$  with coordinates  $(v, w, x, y, z)$ , write out an equation of the 3-plane through the point  $P = (5, 4, 3, 2, 1)$  with tangent vectors

$$\vec{a} = (2, 1, 3, 0, 4) \quad \vec{b} = (1, -1, 2, -2, 3) \quad \vec{c} = (2, 1, 3, -1, 0)$$

$$\begin{pmatrix} v \\ w \\ x \\ y \\ z \end{pmatrix} = \begin{pmatrix} 5 \\ 4 \\ 3 \\ 2 \\ 1 \end{pmatrix} + r \begin{pmatrix} 2 \\ 1 \\ 3 \\ 0 \\ 4 \end{pmatrix} + s \begin{pmatrix} 1 \\ -1 \\ 2 \\ -2 \\ 3 \end{pmatrix} + t \begin{pmatrix} 2 \\ 1 \\ 3 \\ -1 \\ 0 \end{pmatrix}$$

4. (10 points) Duke Skywater is flying the Millennium Eagle along the curve

$$\vec{r}(t) = (2 \cos t, 3 \sin t, t)$$

At  $t = \frac{\pi}{2}$ , he releases a garbage pod which travels along his tangent line with constant velocity (equal to his velocity at the time of release). Where is the garbage pod at  $t = \pi$ ?

$$\begin{aligned} \vec{r}(t) &= (2 \cos t, 3 \sin t, t) & \vec{r}\left(\frac{\pi}{2}\right) &= \left(2 \cos \frac{\pi}{2}, 3 \sin \frac{\pi}{2}, \frac{\pi}{2}\right) = \left(0, 3, \frac{\pi}{2}\right) \\ \vec{v}(t) &= (-2 \sin t, 3 \cos t, 1) & \vec{v}\left(\frac{\pi}{2}\right) &= \left(-2 \sin \frac{\pi}{2}, 3 \cos \frac{\pi}{2}, 1\right) = (-2, 0, 1) \end{aligned}$$

The tangent line is

$$(x, y, z) = \vec{r}_{\text{tan}}(t) = \vec{r}\left(\frac{\pi}{2}\right) + \vec{v}\left(\frac{\pi}{2}\right)\left(t - \frac{\pi}{2}\right) = \left(0, 3, \frac{\pi}{2}\right) + \left(t - \frac{\pi}{2}\right)(-2, 0, 1)$$

At  $t = \pi$ , the garbage pod is at

$$(x, y, z) = \vec{r}_{\text{tan}}(\pi) = \left(0, 3, \frac{\pi}{2}\right) + \left(\frac{\pi}{2}\right)(-2, 0, 1) = (-\pi, 3, \pi)$$

5. (10 points) Duke Skywalker is flying the Millennium Eagle through the galactic polaron field. At  $t = 20$ , Duke's position is  $\vec{r} = (20, 10, 30)$  lightyears and his velocity is  $\vec{v} = (.1, .3, .2) \frac{\text{lightyears}}{\text{year}}$ . At that time, he measures the density of polarons to be  $\rho = 15 \times 10^6 \frac{\text{polarons}}{\text{lightyear}^3}$  and the gradient of this density to be  $\vec{\nabla}\rho = (2 \times 10^6, -1 \times 10^6, 3 \times 10^6) \frac{\text{polarons}}{\text{lightyear}^4}$ .

- a. What does he measure as the time rate of change the polaron density,  $\frac{d\rho}{dt}$ ?

$$\frac{d\rho}{dt} = \vec{\nabla}\rho \cdot \vec{v} = (2 \times 10^6, -1 \times 10^6, 3 \times 10^6) \cdot (.1, .3, .2) = (.2 - .3 + .6) \times 10^6 = .5 \times 10^6 = 5 \times 10^5$$

- b. Using a linear approximation, what would he expect the polaron density to be at the point  $\vec{x} = (21, 12, 29)$ ?

$$\begin{aligned} \rho_{\text{tan}}(\vec{x}) &= \rho(\vec{r}) + \vec{\nabla}\rho \cdot (\vec{x} - \vec{r}) \\ \rho_{\text{tan}}(21, 12, 29) &= 15 \times 10^6 + (2 \times 10^6, -1 \times 10^6, 3 \times 10^6) \cdot (1, 2, -1) \\ &= 15 \times 10^6 + (2 - 2 - 3) \times 10^6 = 12 \times 10^6 \end{aligned}$$

6. (10 points) Duke Skywalker is flying the Millennium Eagle through the galactic hyperon field. At  $t = 20$ , Duke's position is  $\vec{r} = (20, 10, 30)$  lightyears and his velocity is  $\vec{v} = (.1, .3, .2) \frac{\text{lightyears}}{\text{year}}$ . At that time, he measures the hyperon field and its Jacobian to be

$$\vec{H} = \begin{pmatrix} 200 \\ 150 \\ 300 \end{pmatrix} \text{Hans} \quad D\vec{H} = \begin{pmatrix} 30 & -10 & 20 \\ -40 & 10 & 5 \\ -10 & 0 & 10 \end{pmatrix} \frac{\text{Hans}}{\text{lightyear}}$$

- a. What does he measure as the time rate of change the hyperon field,  $\frac{d\vec{H}}{dt}$ ?

$$\frac{d\vec{H}}{dt} = D\vec{H} \vec{v} = \begin{pmatrix} 30 & -10 & 20 \\ -40 & 10 & 5 \\ -10 & 0 & 10 \end{pmatrix} \begin{pmatrix} .1 \\ .3 \\ .2 \end{pmatrix} = \begin{pmatrix} 3 - 3 + 4 \\ -4 + 3 + 1 \\ -1 + 0 + 2 \end{pmatrix} = \begin{pmatrix} 4 \\ 0 \\ 1 \end{pmatrix}$$

- b. Using a linear approximation, what would he expect the hyperon field to be at  $t = 22$ ?

$$\begin{aligned} \vec{H}_{\text{tan}}(t) &= \vec{H}(a) + \frac{d\vec{H}}{dt}(t - a) \\ \vec{H}_{\text{tan}}(22) &= \begin{pmatrix} 200 \\ 150 \\ 300 \end{pmatrix} + \begin{pmatrix} 4 \\ 0 \\ 1 \end{pmatrix} (22 - 20) = \begin{pmatrix} 208 \\ 150 \\ 302 \end{pmatrix} \end{aligned}$$

OR  $\vec{r}_{\text{tan}}(22) = \vec{r}_{\text{tan}}(20) + \vec{v}(20)(22 - 20) = (20, 10, 30) + 2(.1, .3, .2) = (20.2, 10.6, 30.4)$

$$\begin{aligned} \vec{H}_{\text{tan}}(\vec{r}_{\text{tan}}(t)) &= \vec{H}(\vec{r}(a)) + D\vec{H}(\vec{r}(t) - \vec{r}(a)) \\ \vec{H}_{\text{tan}}(\vec{r}_{\text{tan}}(22)) &= \begin{pmatrix} 200 \\ 150 \\ 300 \end{pmatrix} + \begin{pmatrix} 30 & -10 & 20 \\ -40 & 10 & 5 \\ -10 & 0 & 10 \end{pmatrix} \begin{pmatrix} .2 \\ .6 \\ .4 \end{pmatrix} = \begin{pmatrix} 208 \\ 150 \\ 302 \end{pmatrix} \end{aligned}$$

7. (10 points) Consider the vector space  $\mathbf{R}^+$  of all positive real numbers with the operations of

Vector Addition:  $x \oplus y = xy$  (real number addition)

Scalar Multiplication:  $a \odot x = x^a$  (real number exponentiation)

Translate each of the following statements into ordinary arithmetic.

a. For all  $x$  we have  $0 \odot x = \vec{0}$ .

For all  $x$  we have  $x^0 = 1$ .

b. For all  $a$  we have  $a \odot \vec{0} = \vec{0}$ .

For all  $a$  we have  $1^a = 1$ .

c. If  $a \odot x = \vec{0}$  then either  $a = 0$  or  $x = \vec{0}$ .

If  $x^a = 1$  then either  $a = 0$  or  $x = 1$ .

8. (10 points) Consider the linear function  $L : \mathbf{R}^3 \rightarrow \mathbf{R}^2$  given by

$$L(\vec{u}) = \begin{pmatrix} \int_0^1 (u_1 + u_2x + u_3x^2) dx \\ \frac{d}{dx}(u_1 + u_2x + u_3x^2) \Big|_{x=1} \end{pmatrix}$$

Find the matrix  $A$  of the linear function, so that you can rewrite it as

$$L(\vec{u}) = A\vec{u}$$

$$L \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix} = \begin{pmatrix} \int_0^1 (1) dx \\ \frac{d}{dx}(1) \Big|_{x=1} \end{pmatrix} = \begin{pmatrix} 1 \\ 0 \end{pmatrix}$$

$$L \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix} = \begin{pmatrix} \int_0^1 (x) dx \\ \frac{d}{dx}(x) \Big|_{x=1} \end{pmatrix} = \begin{pmatrix} \frac{1}{2} \\ 1 \end{pmatrix} \quad A = \begin{pmatrix} 1 & \frac{1}{2} & \frac{1}{3} \\ 0 & 1 & 2 \end{pmatrix}$$

$$L \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix} = \begin{pmatrix} \int_0^1 (x^2) dx \\ \frac{d}{dx}(x^2) \Big|_{x=1} \end{pmatrix} = \begin{pmatrix} \frac{1}{3} \\ 2 \end{pmatrix}$$

OR

$$\begin{aligned} L(\vec{u}) &= \begin{pmatrix} \int_0^1 (u_1 + u_2x + u_3x^2) dx \\ \frac{d}{dx}(u_1 + u_2x + u_3x^2) \Big|_{x=1} \end{pmatrix} = \begin{pmatrix} \left[ u_1x + u_2 \frac{x^2}{2} + u_3 \frac{x^3}{3} \right]_0^1 \\ (u_2 + 2u_3x) \Big|_{x=1} \end{pmatrix} \\ &= \begin{pmatrix} u_1 + u_2 \frac{1}{2} + u_3 \frac{1}{3} \\ u_2 + 2u_3 \end{pmatrix} = \begin{pmatrix} 1 & \frac{1}{2} & \frac{1}{3} \\ 0 & 1 & 2 \end{pmatrix} \begin{pmatrix} u_1 \\ u_2 \\ u_3 \end{pmatrix} \quad A = \begin{pmatrix} 1 & \frac{1}{2} & \frac{1}{3} \\ 0 & 1 & 2 \end{pmatrix} \end{aligned}$$