

Name \_\_\_\_\_ ID \_\_\_\_\_

MATH 311                  Final Exam                  Fall 2002  
Section 200                Solutions                      P. Yasskin

1-3	/30	6	/20
4	/20	7	/10
5	/20	8	/10

Multiple Choice: (10 points each)    Work Out: (points indicated)    Extra Credit: (10 points)

1. (10 points) If  $L : P_2 \rightarrow \mathbb{R}$  is a linear function satisfying

$$L(1 + x + x^2) = 2 \quad L(x + x^2) = -1 \quad \text{and} \quad L(x^2) = 3$$

find  $L(2 + 3x + 5x^2)$ .

- a. 16
- b. 9      correctchoice
- c. 4
- d. 0
- e. -4

$$2 + 3x + 5x^2 = a(1 + x + x^2) + b(x + x^2) + c(x^2)$$

By inspection or row operations,  $a = 2, b = 1, c = 2$ . So by linearity

$$\begin{aligned} L(2 + 3x + 5x^2) &= L(2(1 + x + x^2) + (x + x^2) + 2(x^2)) \\ &= 2L(1 + x + x^2) + L(x + x^2) + 2L(x^2) = 2(2) + (-1) + 2(3) = 9 \end{aligned}$$

2. (10 points) Find the plane tangent to the hyperbolic paraboloid  $x - yz = 0$  at the point  $P = (6, 3, 2)$ . Which of the following points does **not** lie on this plane?

- a.  $(-6, 0, 0)$
- b.  $(0, 3, 0)$
- c.  $(0, 0, 2)$
- d.  $(-1, 1, 1)$
- e.  $(1, -1, -1)$       correctchoice

The hyperbolic paraboloid is a level surface of the function  $g = x - yz$ .

Its gradient is  $\vec{\nabla}g = (1, -z, -y)$ .

So the normal to the surface at  $P$  is  $\vec{N} = \vec{\nabla}g|_{(6,3,2)} = (1, -2, -3)$ .

So the tangent plane is  $\vec{N} \cdot X = \vec{N} \cdot P$ , or  $x - 2y - 3z = 6 - 2 \cdot 3 - 3 \cdot 2 = -6$ .

Plugging in each point, we find  $(1, -1, -1)$  is not a solution.

3. (10 points) Duke Skywater is flying the Millenium Eagle through a polaron field. His galactic coordinates are  $(2300, 4200, 1600)$  measured in lightseconds and his velocity is  $\vec{v} = (.2, .3, .4)$  measured in lightseconds per second. He measures the strength of the polaron field is  $p = 274$  milliwookies and its gradient is  $\vec{\nabla}p = (3, 2, 2)$  milliwookies per lightsecond. Assuming a linear approximation for the polaron field and that his velocity is constant, how many seconds will Duke need to wait until the polaron field has grown to 286 milliwookies?

- a. 2
- b. 3
- c. 4
- d. 6 correctchoice
- e. 12

The derivative along Duke's path is

$$\frac{dp}{dt} = \vec{v} \cdot \vec{\nabla}p = (.2, .3, .4) \frac{\text{lightseconds}}{\text{second}} \cdot (3, 2, 2) \frac{\text{milliwookies}}{\text{lightsecond}} = .6 + .6 + .8 = 2 \frac{\text{milliwookies}}{\text{second}}$$

So the polaron field increases 2 milliwookies each second.

To increase 12 milliwookies, it will take 6 seconds.

4. (20 points) Consider the linear map  $f: \mathbb{R}^5 \rightarrow \mathbb{R}^3$  given by  $f(\vec{x}) = A\vec{x}$  where

$$A = \begin{pmatrix} 1 & 2 & -1 & 3 & 1 \\ 1 & 2 & 0 & 3 & -1 \\ -2 & -4 & 0 & -6 & 2 \end{pmatrix}.$$

When necessary, let  $\vec{x} \in \mathbb{R}^5$  be  $\vec{x} = \begin{pmatrix} r \\ s \\ t \\ u \\ v \end{pmatrix}$  and  $\vec{z} \in \mathbb{R}^3$  be  $\vec{z} = \begin{pmatrix} x \\ y \\ z \end{pmatrix}$ .

- a. (2) Identify the domain and give its dimension.

$$\text{Dom}(f) = \mathbb{R}^5 \quad \dim \text{Dom}(f) = 5$$

- b. (2) Identify the codomain and give its dimension.

$$\text{Codom}(f) = \mathbb{R}^3 \quad \dim \text{Codom}(f) = 3$$

- c. (2) Verify that  $f$  is linear.

$$f(\vec{x} + \vec{y}) = A(\vec{x} + \vec{y}) = A\vec{x} + A\vec{y} = f(\vec{x}) + f(\vec{y}) \quad \text{additive}$$

$$f(a\vec{x}) = A(a\vec{x}) = a(A\vec{x}) = af(\vec{x}) \quad \text{scalar multiplicative}$$

- d. (4) Find the kernel of  $f$ . Write it as a *Span* and give a basis and its dimension.

$$\text{Ker}(f) = \{\vec{x} \mid f(\vec{x}) = \vec{0}\} \quad \text{Solve}$$

$$\begin{pmatrix} 1 & 2 & -1 & 3 & 1 \\ 1 & 2 & 0 & 3 & -1 \\ -2 & -4 & 0 & -6 & 2 \end{pmatrix} \begin{pmatrix} r \\ s \\ t \\ u \\ v \end{pmatrix} = \begin{pmatrix} r + 2s - t + 3u + v \\ r + 2s + 3u - v \\ -2r - 4s - 6u + 2v \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix}$$

$$\left( \begin{array}{ccccc|c} 1 & 2 & -1 & 3 & 1 & 0 \\ 1 & 2 & 0 & 3 & -1 & 0 \\ -2 & -4 & 0 & -6 & 2 & 0 \end{array} \right) \begin{array}{l} R_2 - R_1 \\ R_3 + 2R_1 \end{array} \Rightarrow \left( \begin{array}{ccccc|c} 1 & 2 & -1 & 3 & 1 & 0 \\ 0 & 0 & 1 & 0 & -2 & 0 \\ 0 & 0 & -2 & 0 & 4 & 0 \end{array} \right) \begin{array}{l} R_1 + R_2 \\ R_3 + 2R_2 \end{array}$$

$$\Rightarrow \left( \begin{array}{ccccc|c} 1 & 2 & 0 & 3 & -1 & 0 \\ 0 & 0 & 1 & 0 & -2 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 \end{array} \right) \Rightarrow \begin{pmatrix} r \\ s \\ t \\ u \\ v \end{pmatrix} = \begin{pmatrix} -2s - 3u + v \\ s \\ 2v \\ u \\ v \end{pmatrix}$$

$$\begin{aligned} \text{Ker}(f) &= \left\{ \begin{pmatrix} -2s - 3u + v \\ s \\ 2v \\ u \\ v \end{pmatrix} \right\} = \left\{ s \begin{pmatrix} -2 \\ 1 \\ 0 \\ 0 \\ 0 \end{pmatrix} + u \begin{pmatrix} -3 \\ 0 \\ 0 \\ 1 \\ 0 \end{pmatrix} + v \begin{pmatrix} 1 \\ 0 \\ 2 \\ 0 \\ 1 \end{pmatrix} \right\} \\ &= \text{Span} \left\{ \begin{pmatrix} -2 \\ 1 \\ 0 \\ 0 \\ 0 \end{pmatrix}, \begin{pmatrix} -3 \\ 0 \\ 0 \\ 1 \\ 0 \end{pmatrix}, \begin{pmatrix} 1 \\ 0 \\ 2 \\ 0 \\ 1 \end{pmatrix} \right\} \quad \text{Basis is: } \begin{pmatrix} -2 \\ 1 \\ 0 \\ 0 \\ 0 \end{pmatrix}, \begin{pmatrix} -3 \\ 0 \\ 0 \\ 1 \\ 0 \end{pmatrix}, \begin{pmatrix} 1 \\ 0 \\ 2 \\ 0 \\ 1 \end{pmatrix} \end{aligned}$$

$$\dim \text{Ker}(f) = 3$$

e. (4) Find the image of  $f$ . Write it as a  $\text{Span}$  and give a basis and its dimension.

$$\text{Im}(f) = \{f(\vec{x})\} = \left\{ \begin{pmatrix} r + 2s - t + 3u + v \\ r + 2s + 3u - v \\ -2r - 4s - 6u + 2v \end{pmatrix} \right\}$$

$$= \left\{ r \begin{pmatrix} 1 \\ 1 \\ -2 \end{pmatrix} + s \begin{pmatrix} 2 \\ 2 \\ -4 \end{pmatrix} + t \begin{pmatrix} -1 \\ 0 \\ 0 \end{pmatrix} + u \begin{pmatrix} 3 \\ 3 \\ -6 \end{pmatrix} + v \begin{pmatrix} 1 \\ -1 \\ 2 \end{pmatrix} \right\}$$

$$= \text{Span} \left\{ \begin{pmatrix} 1 \\ 1 \\ -2 \end{pmatrix}, \begin{pmatrix} 2 \\ 2 \\ -4 \end{pmatrix}, \begin{pmatrix} -1 \\ 0 \\ 0 \end{pmatrix}, \begin{pmatrix} 3 \\ 3 \\ -6 \end{pmatrix}, \begin{pmatrix} 1 \\ -1 \\ 2 \end{pmatrix} \right\} = \text{Span} \left\{ \begin{pmatrix} 1 \\ 1 \\ -2 \end{pmatrix}, \begin{pmatrix} -1 \\ 0 \\ 0 \end{pmatrix} \right\}$$

$$\text{Basis is: } \begin{pmatrix} 1 \\ 1 \\ -2 \end{pmatrix}, \begin{pmatrix} -1 \\ 0 \\ 0 \end{pmatrix} \quad \dim \text{Im}(f) = 2$$

f. (2) Verify your answers are consistent with the Nullity-Rank Theorem.

$$\dim \text{Ker}(f) + \dim \text{Im}(f) = 3 + 2 = 5 = \dim \text{Dom}(f)$$

g. (2) Is  $f$  one-to-one? Why?

$f$  is NOT one-to-one because  $\text{Ker}(f) \neq \{\vec{0}\}$

h. (2) Is  $f$  onto? Why?

$f$  is NOT onto because  $\text{Im}(f) \neq \text{Codom}(f) = \mathbb{R}^3$

5. (20 points) Consider the vector space  $P_2$  of polynomials of degree  $\leq 2$ .

Consider the bases

$$\begin{aligned} e_1 &= 1 & e_2 &= x & e_3 &= x^2 \\ f_1 &= 1+x & f_2 &= x & f_3 &= -x+x^2 \end{aligned}$$

Consider the function  $L : P_2 \rightarrow P_2$  given by

$$L(p) = 2p(0) + p(1)x$$

a. (4) Find the matrix of  $L$  relative to the  $e$ -basis (on both the domain and the codomain). Call it  $A$ .

$$\begin{aligned} L(e_1) &= L(1) = 2 + x = 2e_1 + e_2 \\ L(e_2) &= L(x) = x = e_2 \\ L(e_3) &= L(x^2) = x = e_2 \end{aligned} \quad A_{e \leftarrow e} = \begin{pmatrix} 2 & 0 & 0 \\ 1 & 1 & 1 \\ 0 & 0 & 0 \end{pmatrix}$$

b. (8) Find the change of basis matrices between the  $e$  and  $f$  bases. (Call them  $C$  and  $C$ .)

Be sure to identify which is which!

$$\begin{aligned} f_1 &= 1+x = e_1 + e_2 \\ f_2 &= x = e_2 \\ f_3 &= -x+x^2 = -e_2 + e_3 \end{aligned} \quad C_{e \leftarrow f} = \begin{pmatrix} 1 & 0 & 0 \\ 1 & 1 & -1 \\ 0 & 0 & 1 \end{pmatrix}$$

$$\left( \begin{array}{ccc|ccc} 1 & 0 & 0 & 1 & 0 & 0 \\ 1 & 1 & -1 & 0 & 1 & 0 \\ 0 & 0 & 1 & 0 & 0 & 1 \end{array} \right) \xrightarrow{R2 - R1 + R3} \left( \begin{array}{ccc|ccc} 1 & 0 & 0 & 1 & 0 & 0 \\ 0 & 1 & 0 & -1 & 1 & 1 \\ 0 & 0 & 1 & 0 & 0 & 1 \end{array} \right) \quad C_{f \leftarrow e} = \begin{pmatrix} 1 & 0 & 0 \\ -1 & 1 & 1 \\ 0 & 0 & 1 \end{pmatrix}$$

c. (4) Find the matrix of  $L$  relative to the  $f$ -basis. Call it  $B$ .

$$B_{f \leftarrow f} = C_{f \leftarrow e} A_{e \leftarrow e} C_{e \leftarrow f} = \begin{pmatrix} 1 & 0 & 0 \\ -1 & 1 & 1 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} 2 & 0 & 0 \\ 1 & 1 & 1 \\ 0 & 0 & 0 \end{pmatrix} \begin{pmatrix} 1 & 0 & 0 \\ 1 & 1 & -1 \\ 0 & 0 & 1 \end{pmatrix} = \begin{pmatrix} 2 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{pmatrix}$$

d. (4) Find  $B$  by a second method.

Recall  $L(p) = 2p(0) + p(1)x$

$$\begin{aligned} L(f_1) &= L(1+x) = 2 + 2x = 2f_1 \\ L(f_2) &= L(x) = x = f_2 \\ L(f_3) &= L(-x+x^2) = 0 = 0 \end{aligned} \quad B_{f \leftarrow f} = \begin{pmatrix} 2 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{pmatrix}$$

6. (20 points) **Stokes' Theorem** states that if  $S$  is a nice surface in  $\mathbf{R}^3$  and  $\partial S$  is its boundary curve traversed counterclockwise as seen from the tip of the normal to  $S$  and  $\vec{F}$  is a nice vector field on  $S$  then

$$\iint_S \vec{\nabla} \times \vec{F} \cdot d\vec{S} = \oint_{\partial S} \vec{F} \cdot d\vec{s}$$

Verify Stokes' Theorem if

$$F = (y, -x, x^2 + y^2)$$

and  $S$  is the paraboloid  $z = x^2 + y^2$  for  $z \leq 4$  with **normal pointing up and in**.

Remember to check the orientations.

The paraboloid may be parametrized by:

$$\vec{R}(r, \theta) = (r \cos \theta, r \sin \theta, r^2)$$

- a. (10) Compute  $\iint_S \vec{\nabla} \times \vec{F} \cdot d\vec{S}$  using the following steps:

$$\vec{\nabla} \times \vec{F} = \begin{vmatrix} i & j & k \\ \partial_x & \partial_y & \partial_z \\ y & -x & x^2 + y^2 \end{vmatrix} = i(2y - 0) - j(2x - 0) + k(-1 - 1) = (2y, -2x, -2)$$

$$(\vec{\nabla} \times \vec{F})(\vec{R}(r, \theta)) = (2r \sin \theta, -2r \cos \theta, -2)$$

$$\vec{R}_r = (\cos \theta, \sin \theta, 2r)$$

$$\vec{R}_\theta = (-r \sin \theta, r \cos \theta, 0)$$

$$\vec{N} = i(-2r^2 \cos \theta) - j(2r^2 \sin \theta) + k(r \cos^2 \theta + r \sin^2 \theta) = (-2r^2 \cos \theta, -2r^2 \sin \theta, r)$$

This is oriented correctly as up and in.

$$\begin{aligned} \iint_S \vec{\nabla} \times \vec{F} \cdot d\vec{S} &= \iint_S \vec{\nabla} \times \vec{F} \cdot \vec{N} dr d\theta = \int \int (-4r^3 \sin \theta \cos \theta + 4r^3 \sin \theta \cos \theta - 2r) dr d\theta \\ &= \int_0^{2\pi} \int_0^2 (-2r) dr d\theta = 2\pi [-r^2]_0^2 = -8\pi \end{aligned}$$

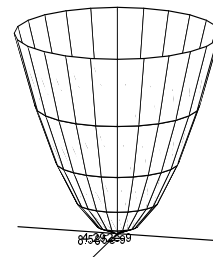
- b. (10) Recall  $F = (y, -x, x^2 + y^2)$  and  $S$  is the paraboloid  $z = x^2 + y^2$  for  $z \leq 4$  with **normal pointing up and in**. Compute  $\oint_{\partial S} \vec{F} \cdot d\vec{s}$  using the following steps:

$$\vec{r}(\theta) = (2 \cos \theta, 2 \sin \theta, 4)$$

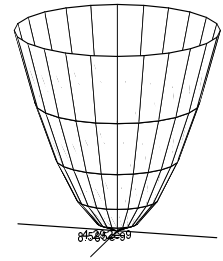
$$\vec{v}(\theta) = (-2 \sin \theta, 2 \cos \theta, 0) \quad \text{which is correctly counterclockwise.}$$

$$\vec{F}(\vec{r}(\theta)) = (2 \sin \theta, -2 \cos \theta, 4)$$

$$\oint_{\partial S} \vec{F} \cdot d\vec{s} = \int_0^{2\pi} \vec{F} \cdot \vec{v} d\theta = \int_0^{2\pi} (-4 \sin^2 \theta - 4 \cos^2 \theta) d\theta = \int_0^{2\pi} (-4) d\theta = -8\pi$$



7. (10 points) The paraboloid at the right is the graph of the equation  $z = x^2 + y^2$ .



It may be parametrized as

$$\vec{R}(r, \theta) = (r \cos \theta, r \sin \theta, r^2).$$

Find the area of the paraboloid for  $z \leq 4$ .

$$\vec{R}_r = (\cos \theta, \sin \theta, 2r)$$

$$\vec{R}_\theta = (-r \sin \theta, r \cos \theta, 0)$$

$$\vec{N} = i(-2r^2 \cos \theta) - j(2r^2 \sin \theta) + k(r \cos^2 \theta + r \sin^2 \theta) = (-2r^2 \cos \theta, -2r^2 \sin \theta, r)$$

$$|\vec{N}| = \sqrt{4r^4 \cos^2 \theta + 4r^4 \sin^2 \theta + r^2} = \sqrt{4r^4 + r^2} = r\sqrt{4r^2 + 1}$$

$$A = \iint |\vec{N}| \, dr \, d\theta = \int_0^{2\pi} \int_0^2 r\sqrt{4r^2 + 1} \, dr \, d\theta = 2\pi \left[ \frac{2(4r^2 + 1)^{3/2}}{3 \cdot 8} \right]_0^2 = \frac{\pi}{6} (17^{3/2} - 1)$$

8. (10 points) A paraboloid in  $\mathbf{R}^4$  with coordinates  $(w, x, y, z)$ , may be parametrized by

$$(w, x, y, z) = \vec{R}(r, \theta) = (r \cos \theta, r \sin \theta, r^2, r^2) \quad \text{for } 0 \leq r \leq 3 \text{ and } 0 \leq \theta \leq 2\pi.$$

Compute  $I = \iint (xz \, dw \, dy - wy \, dx \, dz)$  over the surface.

$$w = r \cos \theta, \quad x = r \sin \theta, \quad y = r^2, \quad z = r^2$$

$$\frac{\partial(w, y)}{\partial(r, \theta)} = \begin{vmatrix} \cos \theta & -r \sin \theta \\ 2r & 0 \end{vmatrix} = 2r^2 \sin \theta \quad \frac{\partial(x, z)}{\partial(r, \theta)} = \begin{vmatrix} \sin \theta & r \cos \theta \\ 2r & 0 \end{vmatrix} = -2r^2 \cos \theta$$

$$I = \int_0^{2\pi} \int_0^3 (r^3 \sin \theta (2r^2 \sin \theta) - r^3 \cos \theta (-2r^2 \cos \theta)) \, dr \, d\theta = \int_0^{2\pi} \int_0^3 2r^5 \, dr \, d\theta = 2\pi \left[ \frac{r^6}{3} \right]_0^3 = 486\pi$$