MATH 304

Lecture 25:

Linear Algebra

Orthogonal projection (continued).

Least squares problems.

Orthogonality

Definition 1. Vectors $\mathbf{x}, \mathbf{y} \in \mathbb{R}^n$ are said to be **orthogonal** (denoted $\mathbf{x} \perp \mathbf{y}$) if $\mathbf{x} \cdot \mathbf{y} = 0$.

Definition 2. A vector $\mathbf{x} \in \mathbb{R}^n$ is said to be **orthogonal** to a nonempty set $Y \subset \mathbb{R}^n$ (denoted $\mathbf{x} \perp Y$) if $\mathbf{x} \cdot \mathbf{y} = 0$ for any $\mathbf{y} \in Y$.

Definition 3. Nonempty sets $X, Y \subset \mathbb{R}^n$ are said to be **orthogonal** (denoted $X \perp Y$) if $\mathbf{x} \cdot \mathbf{y} = 0$ for any $\mathbf{x} \in X$ and $\mathbf{y} \in Y$.

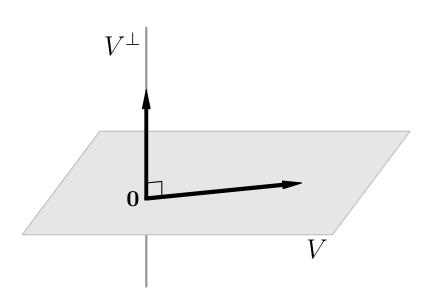
Orthogonal complement

Definition. Let $S \subset \mathbb{R}^n$. The **orthogonal** complement of S, denoted S^{\perp} , is the set of all vectors $\mathbf{x} \in \mathbb{R}^n$ that are orthogonal to S.

Theorem 1 (i) S^{\perp} is a subspace of \mathbb{R}^n . **(ii)** $(S^{\perp})^{\perp} = \operatorname{Span}(S)$.

Theorem 2 If V is a subspace of \mathbb{R}^n , then (i) $(V^{\perp})^{\perp} = V$, (ii) $V \cap V^{\perp} = \{\mathbf{0}\}$, (iii) $\dim V + \dim V^{\perp} = n$.

Theorem 3 If V is the row space of a matrix, then V^{\perp} is the nullspace of the same matrix.



Orthogonal projection

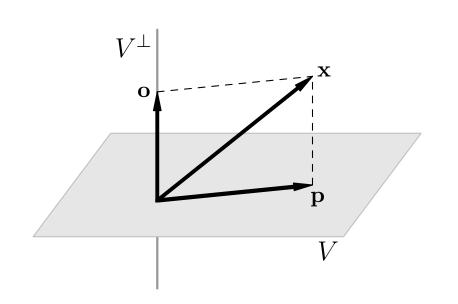
Theorem 1 Let V be a subspace of \mathbb{R}^n . Then any vector $\mathbf{x} \in \mathbb{R}^n$ is uniquely represented as $\mathbf{x} = \mathbf{p} + \mathbf{o}$, where $\mathbf{p} \in V$ and $\mathbf{o} \in V^{\perp}$.

In the above expansion, \mathbf{p} is called the **orthogonal projection** of the vector \mathbf{x} onto the subspace V.

If V is a line spanned by a vector \mathbf{y} then $\mathbf{p} = \frac{\mathbf{x} \cdot \mathbf{y}}{\mathbf{y} \cdot \mathbf{y}} \mathbf{y}$.

Theorem 2 $\|\mathbf{x} - \mathbf{v}\| > \|\mathbf{x} - \mathbf{p}\|$ for any $\mathbf{v} \neq \mathbf{p}$ in V.

Thus $\|\mathbf{o}\| = \|\mathbf{x} - \mathbf{p}\| = \min_{\mathbf{v} \in V} \|\mathbf{x} - \mathbf{v}\|$ is the **distance** from the vector \mathbf{x} to the subspace V.



Problem. Let Π be the plane spanned by vectors $\mathbf{v}_1=(1,1,0)$ and $\mathbf{v}_2=(0,1,1).$

(i) Find the orthogonal projection of the vector $\mathbf{x} = (4, 0, -1)$ onto the plane Π .

(ii) Find the distance from \mathbf{x} to Π .

We have $\mathbf{x} = \mathbf{p} + \mathbf{o}$, where $\mathbf{p} \in \Pi$ and $\mathbf{o} \perp \Pi$. Then the orthogonal projection of \mathbf{x} onto Π is \mathbf{p} and the distance from \mathbf{x} to Π is $\|\mathbf{o}\|$.

We have $\mathbf{p} = \alpha \mathbf{v}_1 + \beta \mathbf{v}_2$ for some $\alpha, \beta \in \mathbb{R}$.

Then $\mathbf{o} = \mathbf{x} - \mathbf{p} = \mathbf{x} - \alpha \mathbf{v}_1 - \beta \mathbf{v}_2$.

$$\begin{cases} \mathbf{o} \cdot \mathbf{v}_1 = 0 \\ \mathbf{o} \cdot \mathbf{v}_2 = 0 \end{cases} \iff \begin{cases} \alpha(\mathbf{v}_1 \cdot \mathbf{v}_1) + \beta(\mathbf{v}_2 \cdot \mathbf{v}_1) = \mathbf{x} \cdot \mathbf{v}_1 \\ \alpha(\mathbf{v}_1 \cdot \mathbf{v}_2) + \beta(\mathbf{v}_2 \cdot \mathbf{v}_2) = \mathbf{x} \cdot \mathbf{v}_2 \end{cases}$$

$$\mathbf{x} = (4,0,-1), \quad \mathbf{v}_1 = (1,1,0), \quad \mathbf{v}_2 = (0,1,1)$$

$$\begin{cases} \alpha(\mathbf{v}_1 \cdot \mathbf{v}_1) + \beta(\mathbf{v}_2 \cdot \mathbf{v}_1) = \mathbf{x} \cdot \mathbf{v}_1 \\ \alpha(\mathbf{v}_1 \cdot \mathbf{v}_2) + \beta(\mathbf{v}_2 \cdot \mathbf{v}_2) = \mathbf{x} \cdot \mathbf{v}_2 \end{cases}$$

$$\iff \begin{cases} 2\alpha + \beta = 4 \\ \alpha + 2\beta = -1 \end{cases} \iff \begin{cases} \alpha = 3 \\ \beta = -2 \end{cases}$$

$$\begin{array}{c} \bigcap \quad \alpha + 2\beta = -1 \\ \mathbf{p} = 3\mathbf{v}_1 - 2\mathbf{v}_2 = (3, 1, -2) \end{array}$$

$$\mathbf{p} = 3\mathbf{v}_1 - 2\mathbf{v}_2 = (3, 1, \mathbf{v}_2)$$

 $\mathbf{o} = \mathbf{x} - \mathbf{p} = (1, -1, 1)$

 $\|\mathbf{o}\| = \sqrt{3}$

$$\mathbf{p} = 3\mathbf{v}_1 - 2\mathbf{v}_2 =$$

Problem. Let Π be the plane spanned by vectors $\mathbf{v}_1 = (1, 1, 0)$ and $\mathbf{v}_2 = (0, 1, 1)$.

(i) Find the orthogonal projection of the vector $\mathbf{x} = (4, 0, -1)$ onto the plane Π .

(ii) Find the distance from x to Π .

Alternative solution: We have $\mathbf{x} = \mathbf{p} + \mathbf{o}$, where $\mathbf{p} \in \Pi$ and $\mathbf{o} \perp \Pi$. Then the orthogonal projection of \mathbf{x} onto Π is \mathbf{p} and the distance from \mathbf{x} to Π is $\|\mathbf{o}\|$.

Notice that ${\bf o}$ is the orthogonal projection of ${\bf x}$ onto the orthogonal complement Π^\perp . In the previous lecture, we found that Π^\perp is the line spanned by the vector ${\bf y}=(1,-1,1)$. It follows that

$$\mathbf{o} = \frac{\mathbf{x} \cdot \mathbf{y}}{\mathbf{y} \cdot \mathbf{y}} \mathbf{y} = \frac{3}{3} (1, -1, 1) = (1, -1, 1).$$

Then $\mathbf{p} = \mathbf{x} - \mathbf{o} = (4, 0, -1) - (1, -1, 1) = (3, 1, -2)$ and $\|\mathbf{o}\| = \sqrt{3}$.

Overdetermined system of linear equations:

$$\begin{cases} x + 2y = 3 \\ 3x + 2y = 5 \\ x + y = 2.09 \end{cases} \iff \begin{cases} x + 2y = 3 \\ -4y = -4 \\ -y = -0.91 \end{cases}$$

No solution: inconsistent system

Assume that a solution (x_0, y_0) does exist but the system is not quite accurate, namely, there may be some errors in the right-hand sides.

Problem. Find a good approximation of (x_0, y_0) .

One approach is the **least squares fit**. Namely, we look for a pair (x, y) that minimizes the sum $(x + 2y - 3)^2 + (3x + 2y - 5)^2 + (x + y - 2.09)^2$.

Least squares solution

System of linear equations:

$$\begin{cases} a_{11}x_1 + a_{12}x_2 + \dots + a_{1n}x_n = b_1 \\ a_{21}x_1 + a_{22}x_2 + \dots + a_{2n}x_n = b_2 \\ \dots \\ a_{m1}x_1 + a_{m2}x_2 + \dots + a_{mn}x_n = b_m \end{cases} \iff A\mathbf{x} = \mathbf{b}$$

For any $\mathbf{x} \in \mathbb{R}^n$ define a **residual** $r(\mathbf{x}) = \mathbf{b} - A\mathbf{x}$.

The **least squares solution** \mathbf{x} to the system is the one that minimizes $||r(\mathbf{x})||$ (or, equivalently, $||r(\mathbf{x})||^2$).

$$||r(\mathbf{x})||^2 = \sum_{i=1}^m (a_{i1}x_1 + a_{i2}x_2 + \cdots + a_{in}x_n - b_i)^2$$

Let A be an $m \times n$ matrix and let $\mathbf{b} \in \mathbb{R}^m$.

Theorem A vector $\hat{\mathbf{x}}$ is a least squares solution of the system $A\mathbf{x} = \mathbf{b}$ if and only if it is a solution of the associated **normal system** $A^T A \mathbf{x} = A^T \mathbf{b}$.

Proof: $A\mathbf{x}$ is an arbitrary vector in R(A), the column space of A. Hence the length of $r(\mathbf{x}) = \mathbf{b} - A\mathbf{x}$ is minimal if $A\mathbf{x}$ is the orthogonal projection of \mathbf{b} onto R(A). That is, if $r(\mathbf{x})$ is orthogonal to R(A).

We know that $\{\text{row space}\}^{\perp} = \{\text{nullspace}\}\$ for any matrix. In particular, $R(A)^{\perp} = N(A^{T})$, the nullspace of the transpose matrix of A. Thus $\hat{\mathbf{x}}$ is a least squares solution if and only if $A^{T}r(\hat{\mathbf{x}}) = \mathbf{0} \iff A^{T}(\mathbf{b} - A\hat{\mathbf{x}}) = \mathbf{0} \iff A^{T}A\hat{\mathbf{x}} = A^{T}\mathbf{b}$.

Corollary The normal system $A^T A \mathbf{x} = A^T \mathbf{b}$ is always consistent.

Find the least squares solution to

$$\begin{cases} x + 2y = 3\\ 3x + 2y = 5\\ x + y = 2.09 \end{cases}$$

$$3x + 2y - 2$$

$$x + y = 2$$

$$3 - 2$$

$$4x$$

$$\begin{pmatrix} 2 \\ 2 \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix}$$

$$\begin{pmatrix} 1 & 2 \\ 3 & 2 \\ 1 & 1 \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} 3 \\ 5 \\ 2.09 \end{pmatrix}$$

$$\begin{pmatrix} 1 & 3 & 1 \\ 2 & 2 & 1 \end{pmatrix} \begin{pmatrix} 1 & 2 \\ 3 & 2 \\ 1 & 1 \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} 1 & 3 & 1 \\ 2 & 2 & 1 \end{pmatrix} \begin{pmatrix} 3 \\ 5 \\ 2.09 \end{pmatrix}$$

$$\begin{pmatrix} 1 \end{pmatrix} \begin{pmatrix} y \end{pmatrix}$$

$$\begin{pmatrix} 2 \\ 1 \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix} =$$

$$\begin{pmatrix} 2 \\ 1 \end{pmatrix} \begin{pmatrix} y \end{pmatrix} = \begin{pmatrix} 1 \\ 1 \end{pmatrix}$$

$$\int \left(y\right) = \begin{pmatrix} 3 \\ 2.0 \end{pmatrix}$$

$$\frac{1}{2.09}$$

 $\begin{pmatrix} 11 & 9 \\ 9 & 9 \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} 20.09 \\ 18.09 \end{pmatrix} \iff \begin{cases} x = 1 \\ y = 1.01 \end{cases}$

Problem. Find the constant function that is the least squares fit to the following data

$$f(x) = c \implies \begin{cases} c = 1 \\ c = 0 \\ c = 1 \\ c = 2 \end{cases} \implies \begin{pmatrix} 1 \\ 1 \\ 1 \\ 1 \end{pmatrix} (c) = \begin{pmatrix} 1 \\ 0 \\ 1 \\ 2 \end{pmatrix}$$

$$(1,1,1,1)egin{pmatrix} 1\ 1\ 1\ 1 \end{pmatrix}(c)=(1,1,1,1)egin{pmatrix} 1\ 0\ 1\ 2 \end{pmatrix}$$

$$c = \frac{1}{4}(1+0+1+2) = 1$$
 (mean arithmetic value)

Find the linear polynomial that is the least squares fit to the following data

$$f(x) \parallel 1 \mid 0 \mid 1 \mid 2$$

$$\begin{cases} c_1 = 1 \\ c_1 + c_2 = 0 \end{cases} \implies \begin{cases} c_1 = 1 \\ c_1 + c_2 = 0 \end{cases}$$

$$f(x)=c_1+c_2x \implies \left\{ egin{array}{ll} c_1=1 & & & \ c_1+c_2=0 & & \ c_1+2c_2=1 & & \ c_1+3c_2=2 & \end{array}
ight.$$

$$f(x) = c_1 + c_2 x \implies egin{cases} c_1 = 1 \ c_1 + c_2 = 0 \ c_1 + 2c_2 = 1 \ c_1 + 3c_2 = 2 \end{cases} \implies egin{cases} 1 & 0 \ 1 & 1 \ 1 & 2 \ 1 & 3 \end{pmatrix} egin{cases} c_1 \ c_2 \end{pmatrix} = egin{cases} 1 \ 0 \ 1 \ 2 \ 1 \end{cases}$$

$$c_1 = 1$$
 $c_1 + c_2 = 0$
 $c_1 + 2c_2 = 1$
 $c_1 + 3c_2 = 2$

$$\begin{pmatrix} 1 & 1 & 1 & 1 \\ 0 & 1 & 2 & 3 \end{pmatrix} \begin{pmatrix} 1 & 0 \\ 1 & 1 \\ 1 & 2 \\ 1 & 3 \end{pmatrix} \begin{pmatrix} c_1 \\ c_2 \end{pmatrix} = \begin{pmatrix} 1 & 1 & 1 & 1 \\ 0 & 1 & 2 & 3 \end{pmatrix} \begin{pmatrix} 1 \\ 0 \\ 1 \\ 2 \end{pmatrix}$$

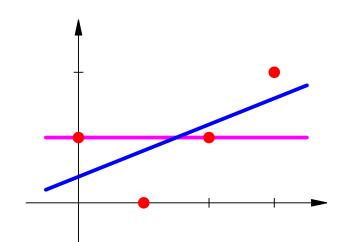
$$\begin{pmatrix} 1 \\ 3 \end{pmatrix}$$

$$\begin{pmatrix} 0\\1\\2 \end{pmatrix}$$

$$\begin{pmatrix} 4 & 6 \\ 6 & 14 \end{pmatrix} \begin{pmatrix} c_1 \\ c_2 \end{pmatrix} = \begin{pmatrix} 4 \\ 8 \end{pmatrix} \iff \begin{cases} c_1 = 0.4 \\ c_2 = 0.4 \end{cases}$$

$$c_1 = 0.2$$

 $c_2 = 0.4$



Problem. Find the quadratic polynomial that is the least squares fit to the following data

$$f(x) = c_1 + c_2 x + c_3 x$$

$$f(x) = c_1 + c_2 x + c_3 x^2$$

$$\Rightarrow \begin{cases} c_1 = 1 \\ c_1 + c_2 + c_3 = 0 \\ c_1 + 2c_2 + 4c_3 = 1 \\ c_1 + 3c_2 + 9c_3 = 2 \end{cases} \Rightarrow \begin{pmatrix} 1 & 0 & 0 \\ 1 & 1 & 1 \\ 1 & 2 & 4 \\ 1 & 3 & 9 \end{pmatrix} \begin{pmatrix} c_1 \\ c_2 \\ c_3 \end{pmatrix} = \begin{pmatrix} 1 \\ 0 \\ 1 \\ 2 \end{pmatrix}$$

$$\Rightarrow \begin{cases} c_1 + c_2 + c_3 = 0 \\ c_1 + 2c_2 + 4c_3 = 1 \\ c_1 + 3c_2 + 9c_3 = 2 \end{cases} \Rightarrow \begin{bmatrix} 1 & 1 & 1 \\ 1 & 2 & 4 \\ 1 & 3 & 9 \end{bmatrix} \begin{bmatrix} c_2 \\ c_3 \end{bmatrix} = \begin{bmatrix} 0 & 1 \\ 1 & 2 \\ 2 & 3 \end{bmatrix}$$

$$\begin{pmatrix} 1 & 1 & 1 & 1 \\ 0 & 1 & 2 & 3 \\ 0 & 1 & 4 & 9 \end{pmatrix} \begin{pmatrix} 1 & 0 & 0 \\ 1 & 1 & 1 \\ 1 & 2 & 4 \\ 1 & 3 & 9 \end{pmatrix} \begin{pmatrix} c_1 \\ c_2 \\ c_3 \end{pmatrix} = \begin{pmatrix} 1 & 1 & 1 & 1 \\ 0 & 1 & 2 & 3 \\ 0 & 1 & 4 & 9 \end{pmatrix} \begin{pmatrix} 1 \\ 0 \\ 1 \\ 2 \end{pmatrix}$$

$$\begin{pmatrix} 0 & 1 & 4 & 9 \end{pmatrix} \begin{pmatrix} 1 & 2 & 1 \\ 1 & 3 & 9 \end{pmatrix} \begin{pmatrix} c_3 \end{pmatrix} \begin{pmatrix} 0 & 1 & 4 & 9 \end{pmatrix}$$
$$\begin{pmatrix} 4 & 6 & 14 \\ 6 & 14 & 36 \\ 14 & 36 & 98 \end{pmatrix} \begin{pmatrix} c_1 \\ c_2 \\ c_3 \end{pmatrix} = \begin{pmatrix} 4 \\ 8 \\ 22 \end{pmatrix} \iff \begin{cases} c_1 = 0.9 \\ c_2 = -1.1 \\ c_3 = 0.5 \end{cases}$$

