## MATH 304

Lecture 3:

Linear Algebra

Row echelon form.
Gauss-Jordan reduction.

#### **Gaussian elimination**

Solution of a system of linear equations splits into two parts:

- (A) elimination and (B) back substitution. Both parts can be done by applying a finite number of elementary operations:
- (1) to multiply an equation by a nonzero scalar;
- (2) to add an equation multiplied by a scalar to another equation;
- (3) to interchange two equations.

#### Example.

$$\begin{cases} x - y & = 2 \\ 2x - y - z & = 3 \\ x + y + z & = 6 \end{cases} \rightarrow \begin{cases} x - y & = 2 \\ y - z & = -1 \\ 2y + z & = 4 \end{cases}$$

$$\rightarrow \begin{cases} x - y & = 2 \\ y - z & = -1 \\ 3z & = 6 \end{cases} \rightarrow \begin{cases} x & = 3 \\ y & = 1 \\ z & = 2 \end{cases}$$

## Another example.

$$\begin{cases} x + y - 2z = 1 \\ y - z = 3 \\ -x + 4y - 3z = 14 \end{cases}$$

Add the 1st equation to the 3rd equation:

$$\begin{cases} x + y - 2z = 1 \\ y - z = 3 \\ 5y - 5z = 15 \end{cases}$$

Add -5 times the 2nd equation to the 3rd equation:

$$\begin{cases} x + y - 2z = 1 \\ y - z = 3 \\ 0 = 0 \end{cases}$$

Add -1 times the 2nd equation to the 1st equation:

$$\begin{cases} x & -z = -2 \\ y - z = 3 \\ 0 = 0 \end{cases} \iff \begin{cases} x = z - 2 \\ y = z + 3 \end{cases}$$

Here z is a free variable (x and y are leading)variables).

It follows that  $\begin{cases} x = t - 2 \\ y = t + 3 \end{cases} \text{ for some } t \in \mathbb{R}.$ 

#### System of linear equations:

$$\int x + y - 2z = 1$$

$$\begin{cases} x + y - 2z = 1 \\ y - z = 3 \\ -x + 4y - 3z = 14 \end{cases}$$

**Solution:** 
$$(x, y, z) = (t - 2, t + 3, t), t \in \mathbb{R}.$$

In vector form, (x, y, z) = (-2, 3, 0) + t(1, 1, 1).

# Yet another example.

$$\begin{cases} x + y - 2z = 1 \\ y - z = 3 \\ -x + 4y - 3z = 1 \end{cases}$$

Add the 1st equation to the 3rd equation:

$$\begin{cases} x + y - 2z = 1 \\ y - z = 3 \\ 5y - 5z = 2 \end{cases}$$

Add -5 times the 2nd equation to the 3rd equation:

$$\begin{cases} x + y - 2z = 1 \\ y - z = 3 \\ 0 = -13 \end{cases}$$

#### System of linear equations:

$$\begin{cases} x+y-2z=1\\ y-z=3\\ -x+4y-3z=1 \end{cases}$$

**Solution:** no solution (inconsistent system).

#### **Matrices**

**Definition.** A *matrix* is a rectangular array of numbers.

Examples: 
$$\begin{pmatrix} 2 & 7 \\ -1 & 0 \\ 3 & 3 \end{pmatrix}$$
,  $\begin{pmatrix} 2 & 7 & 0.2 \\ 4.6 & 1 & 1 \end{pmatrix}$ ,  $\begin{pmatrix} 3/5 \\ 5/8 \\ 4 \end{pmatrix}$ ,  $(\sqrt{2}, 0, -\sqrt{3}, 5)$ ,  $\begin{pmatrix} 1 & 1 \\ 0 & 1 \end{pmatrix}$ .

dimensions =  $(\# \text{ of rows}) \times (\# \text{ of columns})$ 

*n*-by-*n*: **square matrix** *n*-by-1: **column vector** 1-by-*n*: **row vector** 

System of linear equations:

$$\begin{cases} a_{11}x_1 + a_{12}x_2 + \dots + a_{1n}x_n = b_1 \\ a_{21}x_1 + a_{22}x_2 + \dots + a_{2n}x_n = b_2 \\ \vdots \\ a_{m1}x_1 + a_{m2}x_2 + \dots + a_{mn}x_n = b_m \end{cases}$$

Coefficient matrix and column vector of the right-hand sides:

$$\begin{pmatrix} a_{11} & a_{12} & \dots & a_{1n} \\ a_{21} & a_{22} & \dots & a_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ a_{m1} & a_{m2} & \dots & a_{mn} \end{pmatrix} \qquad \begin{pmatrix} b_1 \\ b_2 \\ \vdots \\ b_m \end{pmatrix}$$

System of linear equations:

$$\begin{cases} a_{11}x_1 + a_{12}x_2 + \dots + a_{1n}x_n = b_1 \\ a_{21}x_1 + a_{22}x_2 + \dots + a_{2n}x_n = b_2 \\ \dots \\ a_{m1}x_1 + a_{m2}x_2 + \dots + a_{mn}x_n = b_m \end{cases}$$

Augmented matrix:

$$\begin{pmatrix} a_{11} & a_{12} & \dots & a_{1n} & b_1 \\ a_{21} & a_{22} & \dots & a_{2n} & b_2 \\ \vdots & \vdots & \ddots & \vdots & \vdots \\ a_{m1} & a_{m2} & \dots & a_{mn} & b_m \end{pmatrix}$$

Since the elementary operations preserve the standard form of linear equations, we can trace the solution process by looking on the **augmented matrix**.

Elementary operations for systems of linear equations correspond to **elementary row operations** for augmented matrices:

- (1) to multiply a row by a nonzero scalar; (2) to add the *i*th row multiplied by some  $r \in \mathbb{R}$  to
- the *j*th row;
- (3) to interchange two rows.

Remark. Rows are added and multiplied by scalars as vectors (namely, row vectors).

Augmented matrix:

$$\begin{pmatrix}
a_{11} & a_{12} & \dots & a_{1n} & b_1 \\
a_{21} & a_{22} & \dots & a_{2n} & b_2 \\
\vdots & \vdots & \ddots & \vdots & \vdots \\
a_{m1} & a_{m2} & \dots & a_{mn} & b_m
\end{pmatrix} = \begin{pmatrix}
\mathbf{v}_1 \\
\mathbf{v}_2 \\
\vdots \\
\mathbf{v}_m
\end{pmatrix},$$

where  $\mathbf{v}_i = (a_{i1} \ a_{i2} \ \dots \ a_{in} \mid b_i)$  is a row vector.

Operation 1: to multiply the *i*th row by  $r \neq 0$ :

$$\left(egin{array}{c} \mathbf{v}_1 \ dots \ \mathbf{v}_i \ dots \ \mathbf{v}_m \end{array}
ight) 
ightarrow \left(egin{array}{c} \mathbf{v}_1 \ dots \ r\mathbf{v}_i \ dots \ \mathbf{v}_m \end{array}
ight)$$

Operation 2: to add the ith row multiplied by r to the jth row:

$$\begin{pmatrix} \mathbf{v}_1 \\ \vdots \\ \mathbf{v}_i \\ \vdots \\ \mathbf{v}_j \\ \vdots \\ \mathbf{v}_m \end{pmatrix} \rightarrow \begin{pmatrix} \mathbf{v}_1 \\ \vdots \\ \mathbf{v}_i \\ \vdots \\ \mathbf{v}_j + r\mathbf{v}_i \\ \vdots \\ \mathbf{v}_m \end{pmatrix}$$

Operation 3: to interchange the *i*th row with the *j*th row:

$$\begin{pmatrix} \mathbf{v}_1 \\ \vdots \\ \mathbf{v}_i \\ \vdots \\ \mathbf{v}_j \\ \vdots \\ \mathbf{v}_m \end{pmatrix} \rightarrow \begin{pmatrix} \mathbf{v}_1 \\ \vdots \\ \mathbf{v}_j \\ \vdots \\ \mathbf{v}_i \\ \vdots \\ \mathbf{v}_m \end{pmatrix}$$

#### Row echelon form

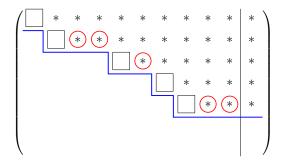
Definition. Leading entry of a matrix is the first nonzero entry in a row.

The goal of the Gaussian elimination is to convert the augmented matrix into **row echelon form**:

- leading entries shift to the right as we go from the first row to the last one;
  - each leading entry is equal to 1.

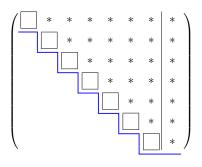
#### Row echelon form

General augmented matrix in row echelon form:



- leading entries are boxed (all equal to 1);
- all the entries below the staircase line are zero;
- each step of the staircase has height 1;
- each circle marks a column without a leading entry that corresponds to a free variable.

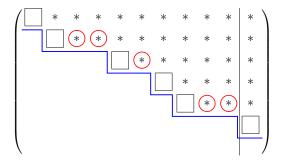
**Strict triangular form** is a particular case of row echelon form that can occur for systems of n equations in n variables:



- no zero rows;
- no free variables.

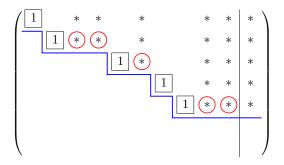
### **Consistency check**

The original system of linear equations is **consistent** if there is no leading entry in the rightmost column of the augmented matrix in row echelon form.



Augmented matrix of an inconsistent system

The goal of the **Gauss-Jordan reduction** is to convert the augmented matrix into **reduced row echelon form**:



- all entries below the staircase line are zero;
- each boxed entry is 1, the other entries in its column are zero;
  - each circle corresponds to a free variable.

#### Example.

$$\begin{cases} x - y & = 2 \\ 2x - y - z & = 3 \\ x + y + z & = 6 \end{cases} \qquad \begin{pmatrix} 1 & -1 & 0 & 2 \\ 2 & -1 & -1 & 3 \\ 1 & 1 & 1 & 6 \end{pmatrix}$$

Row echelon form (also strict triangular):

$$\begin{cases} x - y & = 2 \\ y - z = -1 \\ z = 2 \end{cases} \begin{pmatrix} \boxed{1} & -1 & 0 & 2 \\ 0 & \boxed{1} & -1 & -1 \\ 0 & 0 & \boxed{1} & 2 \end{pmatrix}$$

Reduced row echelon form:

Reduced row echelon form:
$$\begin{cases}
x & = 3 \\
y & = 1 \\
z & = 2
\end{cases}$$

$$\begin{pmatrix}
\boxed{1} & 0 & 0 & 3 \\
0 & \boxed{1} & 0 & 1 \\
0 & 0 & \boxed{1} & 2
\end{pmatrix}$$

### Another example.

$$\begin{cases} x + y - 2 \\ y - y - 1 \end{cases}$$

$$\begin{cases} x + y - 2z = 1 \\ y - z = 3 \\ -x + 4y - 3z = 14 \end{cases} \begin{pmatrix} 1 & 1 & -2 & 1 \\ 0 & 1 & -1 & 3 \\ -1 & 4 & -3 & 14 \end{pmatrix}$$

Row echelon form:

$$\begin{cases} x + y - 2z = 1 \\ y - z = 3 \\ 0 = 0 \end{cases} \qquad \begin{pmatrix} \boxed{1} \\ 0 \\ 0 \end{pmatrix}$$

Reduced row echelon form:

# Yet another example.

$$\begin{cases} x + y - 2z = 1 \\ y - z = 3 \\ -x + 4y - 3z = 1 \end{cases}$$

$$\begin{pmatrix}
1 & 1 & -2 & | & 1 \\
0 & 1 & -1 & | & 3 \\
-1 & 4 & -3 & | & 1
\end{pmatrix}$$

Row echelon form:

$$\begin{cases} x + y - 2z = 1 \\ y - z = 3 \\ 0 = 1 \end{cases}$$

$$\begin{pmatrix}
\boxed{1} & 1 & -2 & | & 1 \\
0 & \boxed{1} & -1 & | & 3 \\
0 & 0 & 0 & \boxed{1}
\end{pmatrix}$$

Reduced row echelon form:

$$\begin{cases} x & -z = 0 \\ y - z = 0 \\ 0 = 1 \end{cases}$$

$$\begin{pmatrix}
\boxed{1} & 0 & -1 & 0 \\
0 & \boxed{1} & -1 & 0 \\
0 & 0 & 0 & \boxed{1}
\end{pmatrix}$$

### How to solve a system of linear equations

- Order the variables.
- Write down the augmented matrix of the system.
- Convert the matrix to row echelon form.
- Check for consistency.
- Convert the matrix to **reduced row echelon form**.
- Write down the system corresponding to the reduced row echelon form.
- Determine leading and free variables.
- Rewrite the system so that the leading variables are on the left while everything else is on the right.
- Assign parameters to the free variables and write down the general solution in parametric form.

New example. 
$$\begin{cases} x_2 + 2x_3 + 3x_4 = 6 \\ x_1 + 2x_2 + 3x_3 + 4x_4 = 10 \end{cases}$$

Variables:  $x_1, x_2, x_3, x_4$ .

Augmented matrix: 
$$\begin{pmatrix} 0 & 1 & 2 & 3 & 6 \\ 1 & 2 & 3 & 4 & 10 \end{pmatrix}$$

To get it into row echelon form, we exchange the two rows:

$$\left(\begin{array}{ccc|c}
1 & 2 & 3 & 4 & 10 \\
0 & 1 & 2 & 3 & 6
\end{array}\right)$$

Consistency check is passed. To convert into reduced row echelon form, add -2 times the 2nd row to the 1st row:

$$\begin{pmatrix}
\boxed{1} & 0 & -1 & -2 & | & -2 \\
0 & \boxed{1} & 2 & 3 & | & 6
\end{pmatrix}$$

The leading variables are  $x_1$  and  $x_2$ ; hence  $x_3$  and  $x_4$  are free variables.

Back to the system:

$$\begin{cases} x_1 - x_3 - 2x_4 = -2 \\ x_2 + 2x_3 + 3x_4 = 6 \end{cases} \iff \begin{cases} x_1 = x_3 + 2x_4 - 2 \\ x_2 = -2x_3 - 3x_4 + 6 \end{cases}$$

 $(t, s \in \mathbb{R})$ 

General solution:

$$\begin{cases} x_1 = t + 2s - 2 \\ x_2 = -2t - 3s + 6 \\ x_3 = t \\ x_4 = s \end{cases} (t, s \in \mathbb{R})$$
In vector form,  $(x_1, x_2, x_3, x_4) = (-2, 6, 0, 0) + t(1, -2, 1, 0) + s(2, -3, 0, 1).$