# MATH 311-504 Topics in Applied Mathematics Lecture 12: Evaluation of determinants. Cross product.

Determinant is a scalar assigned to each square matrix.

Notation. The determinant of a matrix  $A = (a_{ij})_{1 \le i,j \le n}$  is denoted det A or

$a_{11}$	<b>a</b> <sub>12</sub>		$a_{1n}$	
<b>a</b> <sub>21</sub>	<b>a</b> 22	•••	<b>a</b> 2n	
:	÷	•••	÷	•
<i>a</i> <sub>n1</sub>	a <sub>n2</sub>	•••	a <sub>nn</sub>	

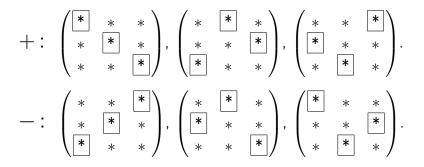
**Principal property:** det A = 0 if and only if the matrix A is not invertible.

#### Definition in low dimensions

Definition. det (a) = a, 
$$\begin{vmatrix} a & b \\ c & d \end{vmatrix} = ad - bc$$
,  
 $\begin{vmatrix} a_{11} & a_{12} & a_{13} \\ a_{21} & a_{22} & a_{23} \\ a_{31} & a_{32} & a_{33} \end{vmatrix} = a_{11}a_{22}a_{33} + a_{12}a_{23}a_{31} + a_{13}a_{21}a_{32} - a_{13}a_{22}a_{31} - a_{12}a_{21}a_{33} - a_{11}a_{23}a_{32}.$ 

÷.

т



Determinants and elementary row operations:

• if a row of a matrix is multiplied by a scalar r, the determinant is also multiplied by r;

• if we add a row of a matrix multiplied by a scalar to another row, the determinant remains the same;

• if we interchange two rows of a matrix, the determinant changes its sign.

Tests for non-invertibility:

- if a matrix A has a zero row then  $\det A = 0$ ;
- if a matrix A has two identical rows then  $\det A = 0$ ;
- if a matrix has two proportional rows then  $\det A = 0$ .

Special matrices:

• det I = 1;

• the determinant of a diagonal matrix is equal to the product of its diagonal entries;

• the determinant of an upper triangular matrix is equal to the product of its diagonal entries.

## Determinant of the transpose:

• If A is a square matrix then det  $A^T = \det A$ .

### Columns vs. rows:

• if one column of a matrix is multiplied by a scalar, the determinant is multiplied by the same scalar;

- adding a scalar multiple of one column to another does not change the determinant;
- interchanging two columns of a matrix changes the sign of its determinant;

• if a matrix A has a zero column or two proportional columns then det A = 0.

Determinants and matrix multiplication:

- if A and B are  $n \times n$  matrices then  $det(AB) = det A \cdot det B;$
- if A and B are n×n matrices then det(AB) = det(BA);
- if A is an invertible matrix then  $det(A^{-1}) = (det A)^{-1}.$

Determinants and scalar multiplication:

• if A is an  $n \times n$  matrix and  $r \in \mathbb{R}$  then  $\det(rA) = r^n \det A$ .

### **Examples**

$$X = \begin{pmatrix} -1 & 2 & 1 \\ 0 & 2 & -2 \\ 0 & 0 & -3 \end{pmatrix}, \quad Y = \begin{pmatrix} 1 & 0 & 0 \\ -1 & 3 & 0 \\ 2 & -2 & 1 \end{pmatrix}.$$

det 
$$X = (-1) \cdot 2 \cdot (-3) = 6$$
, det  $Y = \det Y^T = 3$ ,  
det $(XY) = 6 \cdot 3 = 18$ , det $(YX) = 3 \cdot 6 = 18$ ,  
det $(Y^{-1}) = 1/3$ , det $(XY^{-1}) = 6/3 = 2$ ,  
det $(XYX^{-1}) = \det Y = 3$ , det $(X^{-1}Y^{-1}XY) = 1$ ,  
det $(2X) = 2^3 \det X = 2^3 \cdot 6 = 48$ ,  
det $(-3X^{-1}Y) = (-3)^3 \cdot 6^{-1} \cdot 3 = -27/2$ .

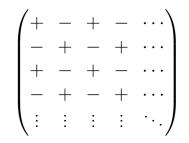
#### Row and column expansions

Given an  $n \times n$  matrix  $A = (a_{ij})$ , let  $A_{ij}$  denote the  $(n-1) \times (n-1)$  submatrix obtained by deleting the *i*th row and the *j*th column of A.

**Theorem** For any  $1 \le k, m \le n$  we have that

$$\det A = \sum_{j=1}^{n} (-1)^{k+j} a_{kj} \det A_{kj},$$
  
(expansion by kth row)  
 $\det A = \sum_{i=1}^{n} (-1)^{i+m} a_{im} \det A_{im}.$   
(expansion by mth column)

### Signs for row/column expansions



Example. 
$$A = \begin{pmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \\ 7 & 8 & 9 \end{pmatrix}$$
.

Expansion by the 1st row:

$$\begin{pmatrix} \boxed{1} & * & * \\ * & 5 & 6 \\ * & 8 & 9 \end{pmatrix} \begin{pmatrix} * & \boxed{2} & * \\ 4 & * & 6 \\ 7 & * & 9 \end{pmatrix} \begin{pmatrix} * & * & \boxed{3} \\ 4 & 5 & * \\ 7 & 8 & * \end{pmatrix}$$
$$\det A = 1 \begin{vmatrix} 5 & 6 \\ 8 & 9 \end{vmatrix} - 2 \begin{vmatrix} 4 & 6 \\ 7 & 9 \end{vmatrix} + 3 \begin{vmatrix} 4 & 5 \\ 7 & 8 \end{vmatrix}$$
$$= (5 \cdot 9 - 6 \cdot 8) - 2(4 \cdot 9 - 6 \cdot 7) + 3(4 \cdot 8 - 5 \cdot 7) = 0.$$

Example. 
$$A = \begin{pmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \\ 7 & 8 & 9 \end{pmatrix}$$
.

Expansion by the 2nd column:

$$\begin{pmatrix} * & 2 & * \\ 4 & * & 6 \\ 7 & * & 9 \end{pmatrix} \begin{pmatrix} 1 & * & 3 \\ * & 5 & * \\ 7 & * & 9 \end{pmatrix} \begin{pmatrix} 1 & * & 3 \\ 4 & * & 6 \\ * & 8 & * \end{pmatrix}$$
$$det A = -2 \begin{vmatrix} 4 & 6 \\ 7 & 9 \end{vmatrix} + 5 \begin{vmatrix} 1 & 3 \\ 7 & 9 \end{vmatrix} - 8 \begin{vmatrix} 1 & 3 \\ 4 & 6 \end{vmatrix}$$
$$= -2(4 \cdot 9 - 6 \cdot 7) + 5(1 \cdot 9 - 3 \cdot 7) - 8(1 \cdot 6 - 3 \cdot 4) = 0.$$

Example. 
$$A = \begin{pmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \\ 7 & 8 & 9 \end{pmatrix}$$
.

Subtract the 1st row from the 2nd row and from the 3rd row:

$$\begin{vmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \\ 7 & 8 & 9 \end{vmatrix} = \begin{vmatrix} 1 & 2 & 3 \\ 3 & 3 & 3 \\ 7 & 8 & 9 \end{vmatrix} = \begin{vmatrix} 1 & 2 & 3 \\ 3 & 3 & 3 \\ 6 & 6 & 6 \end{vmatrix} = 0$$

since the last matrix has two proportional rows.

Another example. 
$$B = \begin{pmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \\ 7 & 8 & 13 \end{pmatrix}$$

*First let's do some row reduction.* Add -4 times the 1st row to the 2nd row:

$$\begin{vmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \\ 7 & 8 & 13 \end{vmatrix} = \begin{vmatrix} 1 & 2 & 3 \\ 0 & -3 & -6 \\ 7 & 8 & 13 \end{vmatrix}$$

Add -7 times the 1st row to the 3rd row:

$$\begin{vmatrix} 1 & 2 & 3 \\ 0 & -3 & -6 \\ 7 & 8 & 13 \end{vmatrix} = \begin{vmatrix} 1 & 2 & 3 \\ 0 & -3 & -6 \\ 0 & -6 & -8 \end{vmatrix}$$

$$\begin{vmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \\ 7 & 8 & 13 \end{vmatrix} = \begin{vmatrix} 1 & 2 & 3 \\ 0 & -3 & -6 \\ 0 & -6 & -8 \end{vmatrix}$$

Expand the determinant by the 1st column:

$$egin{array}{cc|c} 1 & 2 & 3 \ 0 & -3 & -6 \ 0 & -6 & -8 \ \end{array} = 1 egin{array}{cc|c} -3 & -6 \ -6 & -8 \ \end{array}$$

Thus

$$\det B = \begin{vmatrix} -3 & -6 \\ -6 & -8 \end{vmatrix} = (-3) \begin{vmatrix} 1 & 2 \\ -6 & -8 \end{vmatrix}$$
$$= (-3)(-2) \begin{vmatrix} 1 & 2 \\ 3 & 4 \end{vmatrix} = (-3)(-2)(-2) = -12$$

### **Determinants and linear dependence**

**Theorem** For any *n*-by-*n* matrix *A* the following conditions are equivalent:

- det A = 0;
- A is not invertible;

• the matrix equation  $A\mathbf{x} = \mathbf{0}$  has a nonzero solution  $\mathbf{x} \in \mathbb{R}^n$ ;

- columns of A are linearly dependent vectors;
- rows of *A* are linearly dependent vectors.

**Problem.** Determine whether vectors  $\mathbf{v}_1 = (1, 2, 3)$ ,  $\mathbf{v}_2 = (4, 5, 6)$ , and  $\mathbf{v}_3 = (7, 8, 13)$  are parallel to the same plane.

The vectors  $\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3$  are parallel to the same plane if and only if they are linearly dependent.

Consider a  $3 \times 3$  matrix V whose rows are vectors  $\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3$ . We have

det 
$$V = \begin{vmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \\ 7 & 8 & 13 \end{vmatrix} = -12.$$

det  $V \neq 0 \implies$  the vectors are linearly independent  $\implies$  the vectors are not parallel to the same plane

#### **Cross product**

Definition. Given two vectors  $\mathbf{v} = (v_1, v_2, v_3)$  and  $\mathbf{w} = (w_1, w_2, w_3)$  in  $\mathbb{R}^3$ , the **cross product**  $\mathbf{v} \times \mathbf{w}$  is another vector in  $\mathbb{R}^3$  defined by

$$\mathbf{v} \times \mathbf{w} = (v_2 w_3 - v_3 w_2, v_3 w_1 - v_1 w_3, v_1 w_2 - v_2 w_1).$$

Using the standard basis  $\mathbf{i} = (1, 0, 0)$ ,  $\mathbf{j} = (0, 1, 0)$ ,  $\mathbf{k} = (0, 0, 1)$ , the definition can be rewritten as  $\mathbf{v} \times \mathbf{w} = (v_2 w_3 - v_3 w_2)\mathbf{i} + (v_3 w_1 - v_1 w_3)\mathbf{j} + (v_1 w_2 - v_2 w_1)\mathbf{k}$  $= \begin{vmatrix} v_2 & v_3 \\ w_2 & w_3 \end{vmatrix} \mathbf{i} - \begin{vmatrix} v_1 & v_3 \\ w_1 & w_3 \end{vmatrix} \mathbf{j} + \begin{vmatrix} v_1 & v_2 \\ w_1 & w_2 \end{vmatrix} \mathbf{k} = \begin{vmatrix} \mathbf{i} & \mathbf{j} & \mathbf{k} \\ v_1 & v_2 & v_3 \\ w_1 & w_2 & w_3 \end{vmatrix}$ . **Proposition** For any vectors  $\mathbf{u} = (u_1, u_2, u_3)$ ,  $\mathbf{v} = (v_1, v_2, v_3)$ , and  $\mathbf{w} = (w_1, w_2, w_3)$  in  $\mathbb{R}^3$ ,  $\mathbf{u} \cdot (\mathbf{v} \times \mathbf{w}) = \begin{vmatrix} u_1 & u_2 & u_3 \\ v_1 & v_2 & v_3 \\ w_1 & w_2 & w_3 \end{vmatrix}$ .

#### Indeed, since

$$\mathbf{v} \times \mathbf{w} = \begin{vmatrix} v_2 & v_3 \\ w_2 & w_3 \end{vmatrix} \mathbf{i} - \begin{vmatrix} v_1 & v_3 \\ w_1 & w_3 \end{vmatrix} \mathbf{j} + \begin{vmatrix} v_1 & v_2 \\ w_1 & w_2 \end{vmatrix} \mathbf{k},$$

it follows that

$$\mathbf{u} \cdot (\mathbf{v} \times \mathbf{w}) = u_1 \begin{vmatrix} v_2 & v_3 \\ w_2 & w_3 \end{vmatrix} - u_2 \begin{vmatrix} v_1 & v_3 \\ w_1 & w_3 \end{vmatrix} + u_3 \begin{vmatrix} v_1 & v_2 \\ w_1 & w_2 \end{vmatrix}$$

Algebraic properties of the cross product:

- $\mathbf{x} \times \mathbf{y}$  is orthogonal to both  $\mathbf{x}$  and  $\mathbf{y}$
- $\mathbf{y} \times \mathbf{x} = -\mathbf{x} \times \mathbf{y}$  (anticommutativity)
- $\mathbf{x} \times (\mathbf{y} + \mathbf{z}) = \mathbf{x} \times \mathbf{y} + \mathbf{x} \times \mathbf{z}$  (distributive law)

• 
$$r(\mathbf{x} \times \mathbf{y}) = (r\mathbf{x}) \times \mathbf{y} = \mathbf{x} \times (r\mathbf{y})$$

- $\mathbf{x} \times (\mathbf{y} \times \mathbf{z}) = (\mathbf{x} \cdot \mathbf{z})\mathbf{y} (\mathbf{x} \cdot \mathbf{y})\mathbf{z}$
- In general,  $(\mathbf{x} \times \mathbf{y}) \times \mathbf{z} \neq \mathbf{x} \times (\mathbf{y} \times \mathbf{z})$
- $(\mathbf{x} \times \mathbf{y}) \times \mathbf{z} + (\mathbf{y} \times \mathbf{z}) \times \mathbf{x} + (\mathbf{z} \times \mathbf{x}) \times \mathbf{y} = \mathbf{0}$ (Jacobi's identity)
- $\mathbf{i} \times \mathbf{j} = \mathbf{k}$ ,  $\mathbf{j} \times \mathbf{k} = \mathbf{i}$ ,  $\mathbf{k} \times \mathbf{i} = \mathbf{j}$

#### Geometric properties of the cross product:

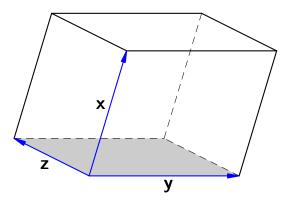
•  $\mathbf{x} \times \mathbf{y}$  is orthogonal to both  $\mathbf{x}$  and  $\mathbf{y}$ .

• If  $\mathbf{x} \times \mathbf{y} \neq \mathbf{0}$  then the triple of vectors  $\mathbf{x}$ ,  $\mathbf{y}$ ,  $\mathbf{x} \times \mathbf{y}$  obeys the same rule (right-hand or left-hand rule) as the standard basis  $\mathbf{i}$ ,  $\mathbf{j}$ ,  $\mathbf{k}$ .

• The area of the parallelogram with vectors  $\mathbf{x}$  and  $\mathbf{y}$  as adjacent sides is equal to  $|\mathbf{x} \times \mathbf{y}|$ . That is,  $|\mathbf{x} \times \mathbf{y}| = |\mathbf{x}| |\mathbf{y}| \sin \angle (\mathbf{x}, \mathbf{y})$ .

• The area of the triangle with vectors  $\mathbf{x}$  and  $\mathbf{y}$  as adjacent sides is equal to  $\frac{1}{2}|\mathbf{x} \times \mathbf{y}|$ .

• The volume of the parallelepiped with vectors  $\mathbf{x}$ ,  $\mathbf{y}$ , and  $\mathbf{z}$  as adjacent edges is equal to  $|\mathbf{x} \cdot (\mathbf{y} \times \mathbf{z})|$ .



Area of the grey parallelogram  $= |\mathbf{y} \times \mathbf{z}|$ . Volume of the parallelepiped  $= |\mathbf{x} \cdot (\mathbf{y} \times \mathbf{z})|$ . The triple  $\mathbf{x}, \mathbf{y}, \mathbf{z}$  obeys the right-hand rule. **Problem.** (i) Find volume of the parallelepiped with vectors  $\mathbf{a} = (1, 4, 7)$ ,  $\mathbf{b} = (2, 5, 8)$ , and  $\mathbf{c} = (3, 6, 13)$  as adjacent edges. (ii) Determine whether the triple  $\mathbf{a}, \mathbf{b}, \mathbf{c}$  obeys the same hand rule as the standard basis  $\mathbf{i}, \mathbf{j}, \mathbf{k}$ .

$$\mathbf{a} \cdot (\mathbf{b} \times \mathbf{c}) = \begin{vmatrix} 1 & 4 & 7 \\ 2 & 5 & 8 \\ 3 & 6 & 13 \end{vmatrix} = \begin{vmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \\ 7 & 8 & 13 \end{vmatrix} = -12.$$

Volume of the parallelepiped  $= |\mathbf{a} \cdot (\mathbf{b} \times \mathbf{c})| = 12$ . Since  $\mathbf{a} \cdot (\mathbf{b} \times \mathbf{c}) < 0$ , the triple  $\mathbf{a}, \mathbf{b}, \mathbf{c}$  does not obey the same hand rule as the triple  $\mathbf{i}, \mathbf{j}, \mathbf{k}$ . Suppose  $\Pi$  is a plane in  $\mathbb{R}^3$  with a parametric representation  $t_1\mathbf{v} + t_2\mathbf{w} + \mathbf{u}$ , where  $\mathbf{u} = (u_1, u_2, u_3)$ ,  $\mathbf{v} = (v_1, v_2, v_3)$ ,  $\mathbf{w} = (w_1, w_2, w_3)$ .

Recall that **u** is a point in  $\Pi$  while **v** and **w** are vectors parallel to the plane. Then the vector **v**  $\times$  **w** is orthogonal to the plane.

Therefore the plane  $\Pi$  is given by the equation  $({\bf x}-{\bf u})\cdot({\bf v}\times{\bf w})=0 \ \, {\rm or}$ 

$$\begin{vmatrix} x - u_1 & y - u_2 & z - u_3 \\ v_1 & v_2 & v_3 \\ w_1 & w_2 & w_3 \end{vmatrix} = 0,$$

where  $\mathbf{x} = (x, y, z)$ .