## Test 1: Solutions

**Problem 1 (25 pts.)** Let  $\ell_0$  be the line in  $\mathbb{R}^3$  passing through the point  $\mathbf{a} = (1, 1, 0)$  in the direction  $\mathbf{v} = (1, 1, 1)$ . Let  $\Pi$  be the plane in  $\mathbb{R}^3$  passing through the line  $\ell_0$  and the point  $\mathbf{b} = (0, 1, 1)$ . Let  $\ell$  be the line in  $\mathbb{R}^3$  passing through the points  $\mathbf{c} = (1, 0, 1)$  and  $\mathbf{d} = (2, 0, 2)$ .

(i) Find a parametric representation for the line  $\ell$ .

**Solution:** s(1, 0, 1).

Since the points **c** and **d** lie on the line  $\ell$ , the vector  $\mathbf{d} - \mathbf{c} = (1,0,1)$  is parallel to  $\ell$ . Hence a parametric representation  $t(\mathbf{d} - \mathbf{c}) + \mathbf{c} = t(1,0,1) + (1,0,1)$ . Note that the line  $\ell$  passes through the origin (take t = -1). Therefore an equivalent representation is s(1,0,1).

(ii) Find a parametric representation for the plane  $\Pi$ .

**Solution:**  $t_1(1,1,1) + t_2(-1,0,1) + (1,1,0)$ .

We know that the vector  $\mathbf{v}$  is parallel to  $\Pi$ . Besides, the plane contains the points  $\mathbf{a}$  and  $\mathbf{b}$  so that the vector  $\mathbf{b} - \mathbf{a}$  is also parallel to  $\Pi$ . Clearly, the vectors  $\mathbf{v} = (1, 1, 1)$  and  $\mathbf{b} - \mathbf{a} = (-1, 0, 1)$  are not parallel to each other. This leads to a parametric representation  $t_1\mathbf{v} + t_2(\mathbf{b} - \mathbf{a}) + \mathbf{a} = t_1(1, 1, 1) + t_2(-1, 0, 1) + (1, 1, 0)$ .

(iii) Find an equation for the plane  $\Pi$ .

Solution: x - 2y + z = -1.

Since the vectors  $\mathbf{v} = (1, 1, 1)$  and  $\mathbf{b} - \mathbf{a} = (-1, 0, 1)$  are parallel to the plane  $\Pi$ , their cross product  $\mathbf{p} = \mathbf{v} \times (\mathbf{b} - \mathbf{a})$  is orthogonal to  $\Pi$ . We have that

$$\mathbf{p} = \begin{vmatrix} \mathbf{i} & \mathbf{j} & \mathbf{k} \\ 1 & 1 & 1 \\ -1 & 0 & 1 \end{vmatrix} = \begin{vmatrix} 1 & 1 \\ 0 & 1 \end{vmatrix} \mathbf{i} - \begin{vmatrix} 1 & 1 \\ -1 & 1 \end{vmatrix} \mathbf{j} + \begin{vmatrix} 1 & 1 \\ -1 & 0 \end{vmatrix} \mathbf{k} = \mathbf{i} - 2\mathbf{j} + \mathbf{k} = (1, -2, 1).$$

A point  $\mathbf{x} = (x, y, z)$  is in the plane  $\Pi$  if and only if  $\mathbf{p} \cdot (\mathbf{x} - \mathbf{a}) = 0$ . This is an equation for the plane. In coordinate form, (x - 1) - 2(y - 1) + z = 0 or x - 2y + z = -1.

(iv) Find the point where the line  $\ell$  intersects the plane  $\Pi$ .

**Solution:** (-1/2, 0, -1/2).

Let  $\mathbf{x} = (x, y, z)$  be the point of intersection. Then  $\mathbf{x} = s(1, 0, 1)$  for some  $s \in \mathbb{R}$  and also x - 2y + z = -1. Both conditions are satisfied if and only if s = -1/2. Hence  $\mathbf{x} = (-1/2, 0, -1/2)$ .

(v) Find the angle between the line  $\ell$  and the plane  $\Pi$ .

Solution: 
$$\arcsin\frac{1}{\sqrt{3}}$$
.

Let  $\phi$  denote the angle between the vectors  $\mathbf{d} - \mathbf{c} = (1, 0, 1)$  and  $\mathbf{p} = (1, -2, 1)$ . Then

$$\cos\phi = \frac{(\mathbf{d} - \mathbf{c}) \cdot \mathbf{p}}{|\mathbf{d} - \mathbf{c}| |\mathbf{p}|} = \frac{1 \cdot 1 + 0 \cdot (-2) + 1 \cdot 1}{\sqrt{1^2 + 0^2 + 1^2} \sqrt{1^2 + (-2)^2 + 1^2}} = \frac{2}{\sqrt{2}\sqrt{6}} = \frac{1}{\sqrt{3}}$$

Note that  $0 < \phi < \pi/2$  as  $\cos \phi > 0$ . Since the vector  $\mathbf{d} - \mathbf{c}$  is parallel to the line  $\ell$  while the vector  $\mathbf{p}$  is orthogonal to the plane  $\Pi$ , the angle between  $\ell$  and  $\Pi$  is equal to

$$\frac{\pi}{2} - \phi = \frac{\pi}{2} - \arccos \frac{1}{\sqrt{3}} = \arcsin \frac{1}{\sqrt{3}}.$$

(vi) Find the distance from the point (1, 1, 1) to the plane  $\Pi$ .

Solution: 
$$\frac{1}{\sqrt{6}}$$
.

The plane  $\Pi$  can be defined by the equation x - 2y + z = -1. Hence the distance from a point  $(x_0, y_0, z_0)$  to  $\Pi$  is equal to

$$\frac{|x_0 - 2y_0 + z_0 + 1|}{\sqrt{1^2 + (-2)^2 + 1^2}} = \frac{|x_0 - 2y_0 + z_0 + 1|}{\sqrt{6}}$$

In particular, the distance from the point (1, 1, 1) to the plane is equal to  $\frac{1}{\sqrt{6}}$ .

**Problem 2 (15 pts.)** Find a quadratic polynomial p(x) such that p(-1) = 1, p(2) = -2, and p(3) = 1.

**Solution:**  $p(x) = x^2 - 2x - 2$ .

Let  $p(x) = ax^2 + bx + c$ , where a, b, c are unknown coefficients. Then p(-1) = a - b + c, p(2) = 4a + 2b + c, and p(3) = 9a + 3b + c. The coefficients a, b, and c are to be chosen so that

$$\begin{cases} a-b+c = 1, \\ 4a+2b+c = -2, \\ 9a+3b+c = 1. \end{cases}$$

We solve this system of linear equations using elementary operations:

$$\begin{cases} a-b+c=1\\ 4a+2b+c=-2\\ 9a+3b+c=1 \end{cases} \iff \begin{cases} a-b+c=1\\ 3a+3b=-3\\ 9a+3b+c=1 \end{cases} \iff \begin{cases} a-b+c=1\\ 3a+3b=-3\\ 8a+4b=0 \end{cases} \iff \begin{cases} a-b+c=1\\ 2a+b=0 \end{cases}$$
$$\Leftrightarrow \begin{cases} a-b+c=1\\ a+b=-1\\ a=1 \end{cases} \iff \begin{cases} a-b+c=1\\ b=-2\\ a=1 \end{cases} \iff \begin{cases} c=-2\\ b=-2\\ a=1 \end{cases}$$

Thus the desired polynomial is  $p(x) = x^2 - 2x - 2$ .

Problem 3 (20 pts.) Let 
$$A = \begin{pmatrix} 1 & 1 & 1 & 1 \\ 1 & 1 & 0 & 0 \\ 0 & 1 & -2 & 0 \\ 0 & -1 & 2 & 1 \end{pmatrix}$$
. Find the inverse matrix  $A^{-1}$ .

Solution: 
$$A^{-1} = \begin{pmatrix} -2 & 3 & 1 & 2 \\ 2 & -2 & -1 & -2 \\ 1 & -1 & -1 & -1 \\ 0 & 0 & 1 & 1 \end{pmatrix}.$$

First we merge the matrix A with the identity matrix into one  $4 \times 8$  matrix

$$(A \mid I) = \begin{pmatrix} 1 & 1 & 1 & 1 & 1 & 1 & 0 & 0 & 0 \\ 1 & 1 & 0 & 0 & 0 & 1 & 0 & 0 \\ 0 & 1 & -2 & 0 & 0 & 0 & 1 & 0 \\ 0 & -1 & 2 & 1 & 0 & 0 & 0 & 1 \end{pmatrix}.$$

Then we apply elementary row operations to this matrix until the left part becomes the identity matrix.

Subtract the first row from the second row:

$$\begin{pmatrix} 1 & 1 & 1 & 1 & 1 & 1 & 0 & 0 & 0 \\ 1 & 1 & 0 & 0 & 0 & 1 & 0 & 0 \\ 0 & 1 & -2 & 0 & 0 & 0 & 1 & 0 \\ 0 & -1 & 2 & 1 & 0 & 0 & 0 & 1 \end{pmatrix} \rightarrow \begin{pmatrix} 1 & 1 & 1 & 1 & 1 & 1 & 1 & 0 & 0 & 0 \\ 0 & 0 & -1 & -1 & 1 & 0 & 0 & 0 \\ 0 & 1 & -2 & 0 & 0 & 0 & 1 & 0 \\ 0 & -1 & 2 & 1 & 0 & 0 & 0 & 1 \end{pmatrix}.$$

Interchange the second row with the third row:

.

$$\begin{pmatrix} 1 & 1 & 1 & 1 \\ 0 & 0 & -1 & -1 \\ 0 & 1 & -2 & 0 \\ 0 & -1 & 2 & 1 \\ \end{pmatrix} \begin{array}{c|cccc} 1 & 1 & 0 & 0 & 0 \\ -1 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \\ \end{pmatrix} \rightarrow \begin{pmatrix} 1 & 1 & 1 & 1 & 1 \\ 0 & 1 & -2 & 0 \\ 0 & 0 & -1 & -1 \\ 0 & 0 & 0 & 1 \\ \end{pmatrix} \cdot \begin{pmatrix} 1 & 1 & 1 & 1 \\ 0 & 0 & 0 \\ 0 & 0 & -1 & -1 \\ 0 & 0 & 0 & 1 \\ \end{pmatrix} \cdot$$

Add the second row to the fourth row:

$$\begin{pmatrix} 1 & 1 & 1 & 1 & 1 & 1 & 1 & 0 & 0 & 0 \\ 0 & 1 & -2 & 0 & 0 & 0 & 1 & 0 \\ 0 & 0 & -1 & -1 & -1 & 1 & 0 & 0 \\ 0 & -1 & 2 & 1 & 0 & 0 & 0 & 1 \end{pmatrix} \rightarrow \begin{pmatrix} 1 & 1 & 1 & 1 & 1 & 1 & 0 & 0 & 0 \\ 0 & 1 & -2 & 0 & 0 & 0 & 1 & 0 \\ 0 & 0 & -1 & -1 & -1 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 & 0 & 1 & 1 \end{pmatrix}.$$

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Multiply the third row by -1:

$$\begin{pmatrix} 1 & 1 & 1 & 1 & 1 & 1 & 1 & 0 & 0 & 0 \\ 0 & 1 & -2 & 0 & 0 & 0 & 1 & 0 \\ 0 & 0 & -1 & -1 & -1 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 & 0 & 1 & 1 \end{pmatrix} \rightarrow \begin{pmatrix} 1 & 1 & 1 & 1 & 1 & 1 & 0 & 0 & 0 \\ 0 & 1 & -2 & 0 & 0 & 0 & 1 & 0 \\ 0 & 0 & 1 & 1 & 1 & -1 & 0 & 0 \\ 0 & 0 & 0 & 1 & 1 & 0 & 0 & 1 & 1 \end{pmatrix}.$$

Subtract the fourth row from the third row:

$$\begin{pmatrix} 1 & 1 & 1 & 1 & 1 & 0 & 0 & 0 \\ 0 & 1 & -2 & 0 & 0 & 0 & 1 & 0 \\ 0 & 0 & 1 & 1 & 1 & -1 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 & 0 & 1 & 1 \end{pmatrix} \rightarrow \begin{pmatrix} 1 & 1 & 1 & 1 & 1 & 1 & 0 & 0 & 0 \\ 0 & 1 & -2 & 0 & 0 & 0 & 1 & 0 \\ 0 & 0 & 1 & 0 & 1 & -1 & -1 & -1 \\ 0 & 0 & 0 & 1 & 0 & 0 & 1 & 1 \end{pmatrix}.$$

Subtract the fourth row from the first row:

$$\begin{pmatrix} 1 & 1 & 1 & 1 & 1 & 1 & 0 & 0 & 0 \\ 0 & 1 & -2 & 0 & 0 & 0 & 1 & 0 \\ 0 & 0 & 1 & 0 & 1 & -1 & -1 & -1 \\ 0 & 0 & 0 & 1 & 0 & 0 & 1 & 1 \end{pmatrix} \rightarrow \begin{pmatrix} 1 & 1 & 1 & 0 & 1 & 0 & -1 & -1 \\ 0 & 1 & -2 & 0 & 0 & 0 & 1 & 0 \\ 0 & 0 & 1 & 0 & 1 & -1 & -1 \\ 0 & 0 & 0 & 1 & 0 & 0 & 1 & 1 \end{pmatrix}.$$

Add 2 times the third row to the second row:

$$\begin{pmatrix} 1 & 1 & 1 & 0 & | & 1 & 0 & -1 & -1 \\ 0 & 1 & -2 & 0 & | & 0 & 0 & 1 & 0 \\ 0 & 0 & 1 & 0 & | & 1 & -1 & -1 & -1 \\ 0 & 0 & 0 & 1 & | & 0 & 0 & 1 & 1 \end{pmatrix} \rightarrow \begin{pmatrix} 1 & 1 & 1 & 0 & | & 1 & 0 & -1 & -1 \\ 0 & 1 & 0 & 0 & | & 2 & -2 & -1 & -2 \\ 0 & 0 & 1 & 0 & | & 1 & -1 & -1 & -1 \\ 0 & 0 & 0 & 1 & | & 0 & 0 & 1 & 1 \end{pmatrix} .$$

Subtract the third row from the first row:

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$$\begin{pmatrix} 1 & 1 & 1 & 0 & | & 1 & 0 & -1 & -1 \\ 0 & 1 & 0 & 0 & | & 2 & -2 & -1 & -2 \\ 0 & 0 & 1 & 0 & | & 1 & -1 & -1 & -1 \\ 0 & 0 & 0 & 1 & | & 0 & 0 & 1 & 1 \end{pmatrix} \rightarrow \begin{pmatrix} 1 & 1 & 0 & 0 & | & 0 & 1 & 0 & 0 \\ 0 & 1 & 0 & 0 & | & 2 & -2 & -1 & -2 \\ 0 & 0 & 1 & 0 & | & 1 & -1 & -1 & -1 \\ 0 & 0 & 0 & 1 & | & 0 & 0 & 1 & 1 \end{pmatrix} .$$

Subtract the second row from the first row:

$$\begin{pmatrix} 1 & 1 & 0 & 0 & | & 0 & 1 & 0 & 0 \\ 0 & 1 & 0 & 0 & | & 2 & -2 & -1 & -2 \\ 0 & 0 & 1 & 0 & | & 1 & -1 & -1 & -1 \\ 0 & 0 & 0 & 1 & | & 0 & 0 & 1 & 1 \end{pmatrix} \rightarrow \begin{pmatrix} 1 & 0 & 0 & 0 & | & -2 & 3 & 1 & 2 \\ 0 & 1 & 0 & 0 & | & 2 & -2 & -1 & -2 \\ 0 & 0 & 1 & 0 & | & 2 & -2 & -1 & -2 \\ 0 & 0 & 1 & 0 & | & 1 & -1 & -1 & -1 \\ 0 & 0 & 0 & 1 & | & 0 & 0 & 1 & 1 \end{pmatrix}.$$

Finally the left part of our  $4 \times 8$  matrix is transformed into the identity matrix. Therefore the current right part is the inverse matrix of A. Thus

$$A^{-1} = \begin{pmatrix} 1 & 1 & 1 & 1 \\ 1 & 1 & 0 & 0 \\ 0 & 1 & -2 & 0 \\ 0 & -1 & 2 & 1 \end{pmatrix}^{-1} = \begin{pmatrix} -2 & 3 & 1 & 2 \\ 2 & -2 & -1 & -2 \\ 1 & -1 & -1 & -1 \\ 0 & 0 & 1 & 1 \end{pmatrix}.$$

**Problem 4 (20 pts.)** Let A be the same matrix as in Problem 3. Evaluate the following determinants:

(i) det A; (ii) det(A - I); (iii) det(2A).

**Solution:** det A = det(A - I) = 1, det(2A) = 16.

In the solution of Problem 3, the matrix A has been transformed into the identity matrix using elementary row operations. The latter included one row exchange and one row multiplications by -1. It follows that det  $I = -(-1) \det A$ . Therefore det  $A = \det I = 1$ .

Since A is a  $4 \times 4$  matrix, we have that  $det(2A) = 2^4 det A = 16 det A = 16$ . The determinant of the matrix

The determinant of the matrix

$$A - I = \begin{pmatrix} 0 & 1 & 1 & 1 \\ 1 & 0 & 0 & 0 \\ 0 & 1 & -3 & 0 \\ 0 & -1 & 2 & 0 \end{pmatrix}$$

is easily evaluated using column expansions:

$$\det(A-I) = \begin{vmatrix} 0 & 1 & 1 & 1 \\ 1 & 0 & 0 & 0 \\ 0 & 1 & -3 & 0 \\ 0 & -1 & 2 & 0 \end{vmatrix} = - \begin{vmatrix} 1 & 1 & 1 \\ 1 & -3 & 0 \\ -1 & 2 & 0 \end{vmatrix} = - \begin{vmatrix} 1 & -3 \\ -1 & 2 \end{vmatrix} = -(-1) = 1.$$

Bonus Problem 5 (20 pts.) Let  $\mathbf{v}_1 = (1, 1, 0)$ ,  $\mathbf{v}_2 = (0, 1, 1)$ ,  $\mathbf{v}_3 = (1, 1, 1)$ , and  $\mathbf{v}_4 = (0, 1, 0)$ . Determine which of the following sets of vectors are linearly independent:

(i)  $\mathbf{v}_1, \, \mathbf{v}_2;$ 

(ii)  $\mathbf{v}_1, \, \mathbf{v}_2, \, \mathbf{v}_3;$ 

(iii)  $\mathbf{v}_1, \, \mathbf{v}_2, \, \mathbf{v}_3, \, \mathbf{v}_4.$ 

**Solution:** The vectors  $\mathbf{v}_1$  and  $\mathbf{v}_2$  are linearly independent. The vectors  $\mathbf{v}_1$ ,  $\mathbf{v}_2$ , and  $\mathbf{v}_3$  are also linearly independent. The vectors  $\mathbf{v}_1$ ,  $\mathbf{v}_2$ ,  $\mathbf{v}_3$ , and  $\mathbf{v}_4$  are linearly dependent.

The vectors  $\mathbf{v}_1$  and  $\mathbf{v}_2$  are linearly independent since they are not scalar multiples of each other. Consider the  $3 \times 3$  matrix V whose rows are vectors  $\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3$ . We obtain

$$\det V = \begin{vmatrix} 1 & 1 & 0 \\ 0 & 1 & 1 \\ 1 & 1 & 1 \end{vmatrix} = \begin{vmatrix} 1 & 1 & 0 \\ 0 & 1 & 1 \\ 0 & 0 & 1 \end{vmatrix} = 1.$$

Since det  $V \neq 0$ , the vectors  $\mathbf{v}_1$ ,  $\mathbf{v}_2$ , and  $\mathbf{v}_3$  are linearly independent.

Finally, the vectors  $\mathbf{v}_1$ ,  $\mathbf{v}_2$ ,  $\mathbf{v}_3$ , and  $\mathbf{v}_4$  are linearly dependent as there are more vectors in this set than coordinates. Besides, it is easy to observe a nontrivial linear relation between these vectors:  $\mathbf{v}_1 + \mathbf{v}_2 - \mathbf{v}_3 - \mathbf{v}_4 = \mathbf{0}$ .