Sample problems for Test 2

Any problem may be altered or replaced by a different one!

Determine which of the following subsets of \mathbb{R}^3 are subspaces. Problem 1 (20 pts.) Briefly explain.

- (i) The set S_1 of vectors $(x, y, z) \in \mathbb{R}^3$ such that xyz = 0.
- (ii) The set S_2 of vectors $(x, y, z) \in \mathbb{R}^3$ such that x + y + z = 0. (iii) The set S_3 of vectors $(x, y, z) \in \mathbb{R}^3$ such that $y^2 + z^2 = 0$. (iv) The set S_4 of vectors $(x, y, z) \in \mathbb{R}^3$ such that $y^2 z^2 = 0$.

Problem 2 (20 pts.) Let $\mathcal{M}_{2,2}(\mathbb{R})$ denote the space of 2-by-2 matrices with real entries. Consider a linear operator $L: \mathcal{M}_{2,2}(\mathbb{R}) \to \mathcal{M}_{2,2}(\mathbb{R})$ given by

$$L\begin{pmatrix} x & y \\ z & w \end{pmatrix} = \begin{pmatrix} 1 & 2 \\ 3 & 4 \end{pmatrix} \begin{pmatrix} x & y \\ z & w \end{pmatrix}.$$

Find the matrix of the operator L with respect to the basis

$$E_1 = \begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix}, \quad E_2 = \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix}, \quad E_3 = \begin{pmatrix} 0 & 0 \\ 1 & 0 \end{pmatrix}, \quad E_4 = \begin{pmatrix} 0 & 0 \\ 0 & 1 \end{pmatrix}.$$

Problem 3 (30 pts.) Consider a linear operator $f: \mathbb{R}^3 \to \mathbb{R}^3$, $f(\mathbf{x}) = A\mathbf{x}$, where

$$A = \begin{pmatrix} 1 & -1 & -2 \\ -2 & 1 & 3 \\ -1 & 0 & 1 \end{pmatrix}.$$

- (i) Find a basis for the image of f.
- (ii) Find a basis for the null-space of f.

Problem 4 (30 pts.) Let
$$B = \begin{pmatrix} 1 & 2 & 0 \\ 1 & 1 & 1 \\ 0 & 2 & 1 \end{pmatrix}$$
.

- (i) Find all eigenvalues of the matrix B.
- (ii) For each eigenvalue of B, find an associated eigenvector.
- (iii) Is there a basis for \mathbb{R}^3 consisting of eigenvectors of B? Explain.
- (iv) Find a diagonal matrix D and an invertible matrix U such that $B = UDU^{-1}$.
- (v) Find all eigenvalues of the matrix B^2 .

Bonus Problem 5 (20 pts.) Solve the following system of differential equations (find all solutions):

$$\begin{cases} \frac{dx}{dt} = x + 2y, \\ \frac{dy}{dt} = x + y + z, \\ \frac{dz}{dt} = 2y + z. \end{cases}$$