

MATH 311

Topics in Applied Mathematics I

**Lecture 34:**

**Green's theorem.**

**Conservative vector fields.**

## Scalar line integral

Scalar line integral is an integral of a scalar function  $f$  over a path  $\mathbf{x} : [a, b] \rightarrow \mathbb{R}^n$  of finite length relative to the arclength. It is defined as a limit of Riemann sums

$$\mathcal{S}(f, P, \tau_j) = \sum_{j=1}^k f(\mathbf{x}(\tau_j)) (s(t_j) - s(t_{j-1})),$$

where  $P = \{t_0, t_1, \dots, t_k\}$  is a partition of  $[a, b]$ ,  $\tau_j \in [t_j, t_{j-1}]$  for  $1 \leq j \leq k$ , and  $s$  is the arclength parameter of the path  $\mathbf{x}$ .

**Theorem** Let  $\mathbf{x} : [a, b] \rightarrow \mathbb{R}^n$  be a smooth path and  $f$  be a function defined on the image of this path. Then

$$\int_{\mathbf{x}} f ds = \int_a^b f(\mathbf{x}(t)) \|\mathbf{x}'(t)\| dt.$$

$ds$  is referred to as the arclength element.

## Vector line integral

Vector line integral is an integral of a vector field over a smooth path. It is a scalar.

*Definition.* Let  $\mathbf{x} : [a, b] \rightarrow \mathbb{R}^n$  be a smooth path and  $\mathbf{F}$  be a vector field defined on the image of this path. Then 
$$\int_{\mathbf{x}} \mathbf{F} \cdot d\mathbf{s} = \int_a^b \mathbf{F}(\mathbf{x}(t)) \cdot \mathbf{x}'(t) dt.$$

Alternatively, the integral of  $\mathbf{F}$  over  $\mathbf{x}$  can be represented as the integral of a **differential form**

$$\int_{\mathbf{x}} F_1 dx_1 + F_2 dx_2 + \cdots + F_n dx_n,$$

where  $\mathbf{F} = (F_1, F_2, \dots, F_n)$  and  $dx_i = x_i'(t) dt$ .

## Line integrals and reparametrization

Given a path  $\mathbf{x} : [a, b] \rightarrow \mathbb{R}^n$ , we say that another path  $\mathbf{y} : [c, d] \rightarrow \mathbb{R}^n$  is a **reparametrization** of  $\mathbf{x}$  if there exists a continuous invertible function  $u : [c, d] \rightarrow [a, b]$  such that  $\mathbf{y}(t) = \mathbf{x}(u(t))$  for all  $t \in [c, d]$ .

The reparametrization may be orientation-preserving (when  $u$  is increasing) or orientation-reversing (when  $u$  is decreasing).

**Theorem 1** Any scalar line integral is invariant under reparametrizations.

**Theorem 2** Any vector line integral is invariant under orientation-preserving reparametrizations and changes its sign under orientation-reversing reparametrizations.

As a consequence, we can define the integral of a function over a simple curve and the integral of a vector field over a simple oriented curve.

## Applications of line integrals

- Mass of a wire

If  $f$  is the density on a wire  $C$ , then  $\int_C f \, ds$  is the mass of  $C$ .

- Work of a force

If  $\mathbf{F}$  is a force field, then  $\int_{\mathbf{x}} \mathbf{F} \cdot d\mathbf{s}$  is the work done by  $\mathbf{F}$  on a particle that moves along the path  $\mathbf{x}$ .

- Circulation of fluid

If  $\mathbf{F}$  is the velocity field of a planar fluid, then the circulation of the fluid across a closed curve  $C$  is  $\oint_C \mathbf{F} \cdot d\mathbf{s}$ .

- Flux of fluid

If  $\mathbf{F}$  is the velocity field of a planar fluid, then the flux of the fluid across a closed curve  $C$  is  $\oint_C \mathbf{F} \cdot \mathbf{n} \, ds$ , where  $\mathbf{n}$  is the outward unit normal vector to  $C$ .

## Green's Theorem

**Theorem** Let  $D \subset \mathbb{R}^2$  be a closed, bounded region with piecewise smooth boundary  $\partial D$  oriented so that  $D$  is on the left as one traverses  $\partial D$ . Then for any smooth vector field  $\mathbf{F} = (M, N)$  on  $D$ ,

$$\oint_{\partial D} \mathbf{F} \cdot d\mathbf{s} = \iint_D \left( \frac{\partial N}{\partial x} - \frac{\partial M}{\partial y} \right) dx dy$$

or, equivalently,

$$\oint_{\partial D} M dx + N dy = \iint_D \left( \frac{\partial N}{\partial x} - \frac{\partial M}{\partial y} \right) dx dy.$$

## Green's Theorem

*Proof in the case*  $D = [0, 1] \times [0, 1]$  *and*  $\mathbf{F} = (0, N)$ :

$$\int_0^1 \frac{\partial N}{\partial x}(\xi, y) d\xi = N(1, y) - N(0, y)$$

for any  $y \in [0, 1]$  due to the Fundamental Theorem of Calculus. Integrating this equality by  $y$  over  $[0, 1]$ , we obtain

$$\iint_D \frac{\partial N}{\partial x} dx dy = \int_0^1 N(1, y) dy - \int_0^1 N(0, y) dy.$$

Let  $P_1 = (0, 0)$ ,  $P_2 = (1, 0)$ ,  $P_3 = (1, 1)$ , and  $P_4 = (0, 1)$ . The first integral in the right-hand side equals the vector integral of the field  $\mathbf{F}$  over the segment  $P_2P_3$ . The second integral equals the integral of  $\mathbf{F}$  over the segment  $P_1P_4$ . Also, the integral of  $\mathbf{F}$  over any horizontal segment is 0. It follows that the entire right-hand side equals the integral of  $\mathbf{F}$  over the broken line  $P_1P_2P_3P_4P_1$ , that is, over  $\partial D$ .

## Example

Consider vector fields  $\mathbf{F}(x, y) = (-y, 0)$ ,  
 $\mathbf{G}(x, y) = (0, x)$ , and  $\mathbf{H}(x, y) = (y, x)$ .

According to Green's Theorem,

$$\oint_{\partial D} -y \, dx = \iint_D 1 \, dx \, dy = \text{area}(D),$$

$$\oint_{\partial D} x \, dy = \iint_D 1 \, dx \, dy = \text{area}(D),$$

$$\oint_{\partial D} y \, dx + x \, dy = \iint_D 0 \, dx \, dy = 0.$$



## Divergence Theorem

**Theorem** Let  $D \subset \mathbb{R}^2$  be a closed, bounded region with piecewise smooth boundary  $\partial D$  oriented so that  $D$  is on the left as one traverses  $\partial D$ . Then for any smooth vector field  $\mathbf{F}$  on  $D$ ,

$$\oint_{\partial D} \mathbf{F} \cdot \mathbf{n} \, ds = \iint_D \nabla \cdot \mathbf{F} \, dA.$$

*Proof:* Let  $\mathcal{L}$  denote the rotation of the plane  $\mathbb{R}^2$  by  $90^\circ$  about the origin (counterclockwise).  $\mathcal{L}$  is a linear transformation preserving the dot product. Therefore

$$\oint_{\partial D} \mathbf{F} \cdot \mathbf{n} \, ds = \oint_{\partial D} \mathcal{L}(\mathbf{F}) \cdot \mathcal{L}(\mathbf{n}) \, ds.$$

Note that  $\mathcal{L}(\mathbf{n})$  is the unit tangent vector to  $\partial D$ . It follows that the right-hand side is the vector integral of  $\mathcal{L}(\mathbf{F})$  over  $\partial D$ . If  $\mathbf{F} = (M, N)$  then  $\mathcal{L}(\mathbf{F}) = (-N, M)$ . By Green's Theorem,

$$\oint_{\partial D} \mathcal{L}(\mathbf{F}) \cdot d\mathbf{s} = \oint_{\partial D} -N \, dx + M \, dy = \iint_D \left( \frac{\partial M}{\partial x} + \frac{\partial N}{\partial y} \right) dx \, dy.$$

## Conservative vector fields

Let  $R$  be an open region in  $\mathbb{R}^n$  such that any two points in  $R$  can be connected by a continuous path. Such regions are called **(arcwise) connected**.

*Definition.* A continuous vector field  $\mathbf{F} : R \rightarrow \mathbb{R}^n$  is called **conservative** if 
$$\int_{C_1} \mathbf{F} \cdot d\mathbf{s} = \int_{C_2} \mathbf{F} \cdot d\mathbf{s}$$

for any two simple, piecewise smooth, oriented curves  $C_1, C_2 \subset R$  with the same initial and terminal points.

An equivalent condition is that 
$$\oint_C \mathbf{F} \cdot d\mathbf{s} = 0$$
 for any piecewise smooth closed curve  $C \subset R$ .

## Conservative vector fields

**Theorem** The vector field  $\mathbf{F}$  is conservative if and only if it is a gradient field, that is,  $\mathbf{F} = \nabla f$  for some function  $f : R \rightarrow \mathbb{R}$ . If this is the case, then

$$\int_C \mathbf{F} \cdot d\mathbf{s} = f(B) - f(A)$$

for any piecewise smooth, oriented curve  $C \subset R$  that connects the point  $A$  to the point  $B$ .

*Remark.* In the case  $\mathbf{F}$  is a force field, conservativity means that energy is conserved. Moreover, in this case the function  $f$  is the potential energy.

## Test of conservativity

**Theorem** If a smooth field  $\mathbf{F} = (F_1, F_2, \dots, F_n)$  is conservative in a region  $R \subset \mathbb{R}^n$ , then the Jacobian matrix

$$\frac{\partial(F_1, F_2, \dots, F_n)}{\partial(x_1, x_2, \dots, x_n)}$$
 is symmetric everywhere in  $R$ , that is,  
$$\frac{\partial F_i}{\partial x_j} = \frac{\partial F_j}{\partial x_i} \text{ for } i \neq j.$$

Indeed, if the field  $\mathbf{F}$  is conservative, then  $\mathbf{F} = \nabla f$  for some smooth function  $f : R \rightarrow \mathbb{R}$ . It follows that the Jacobian matrix of  $\mathbf{F}$  is the **Hessian matrix** of  $f$ , that is, the matrix of

second-order partial derivatives: 
$$\frac{\partial F_i}{\partial x_j} = \frac{\partial^2 f}{\partial x_j \partial x_i}.$$

*Remark.* The converse of the theorem holds provided that the region  $R$  is **simply-connected**, which means that any closed path in  $R$  can be continuously shrunk within  $R$  to a point.

## Finding scalar potential

*Example.*  $\mathbf{F}(x, y) = (2xy^3 + 3y \cos 3x, 3x^2y^2 + \sin 3x)$ .

The vector field  $\mathbf{F}$  is conservative if  $\partial F_1/\partial y = \partial F_2/\partial x$ .

$$\frac{\partial F_1}{\partial y} = 6xy^2 + 3 \cos 3x, \quad \frac{\partial F_2}{\partial x} = 6xy^2 + 3 \cos 3x.$$

Thus  $\mathbf{F} = \nabla f$  for some function  $f$  (**scalar potential** of  $\mathbf{F}$ ),

that is,  $\frac{\partial f}{\partial x} = 2xy^3 + 3y \cos 3x, \quad \frac{\partial f}{\partial y} = 3x^2y^2 + \sin 3x$ .

Integrating the second equality by  $y$ , we get

$$f(x, y) = \int (3x^2y^2 + \sin 3x) dy = x^2y^3 + y \sin 3x + g(x).$$

Substituting this into the first equality, we obtain that

$2xy^3 + 3y \cos 3x + g'(x) = 2xy^3 + 3y \cos 3x$ . Hence

$g'(x) = 0$  so that  $g(x) = c$ , a constant. Then

$f(x, y) = x^2y^3 + y \sin 3x + c$ .