# MATH 311 Topics in Applied Mathematics I Lecture 16: Basis and dimension (continued). Rank of a matrix.

#### Basis

Definition. Let V be a vector space. A linearly independent spanning set for V is called a **basis**.

**Theorem** A nonempty set  $S \subset V$  is a basis for V if and only if any vector  $\mathbf{v} \in V$  is *uniquely represented* as a linear combination  $\mathbf{v} = r_1\mathbf{v}_1 + r_2\mathbf{v}_2 + \cdots + r_k\mathbf{v}_k$ , where  $\mathbf{v}_1, \ldots, \mathbf{v}_k$  are distinct vectors from S and  $r_1, \ldots, r_k \in \mathbb{R}$ .

Remark on uniqueness. Expansions  $\mathbf{v} = 2\mathbf{v}_1 - \mathbf{v}_2$ ,  $\mathbf{v} = -\mathbf{v}_2 + 2\mathbf{v}_1$ , and  $\mathbf{v} = 2\mathbf{v}_1 - \mathbf{v}_2 + 0\mathbf{v}_3$  are considered the same.

### Dimension

**Theorem 1** Any vector space has a basis.

**Theorem 2** If a vector space V has a finite basis, then all bases for V are finite and have the same number of elements.

*Definition.* The **dimension** of a vector space V, denoted dim V, is the number of elements in any of its bases.

*Examples.* • dim  $\mathbb{R}^n = n$ 

- $\mathcal{M}_{m,n}(\mathbb{R})$ : the space of  $m \times n$  matrices; dim  $\mathcal{M}_{m,n} = mn$
- $\mathcal{P}_n$ : polynomials of degree less than n; dim  $\mathcal{P}_n = n$
- $\mathcal{P}:$  the space of all polynomials;  $\mbox{ dim } \mathcal{P} = \infty$
- $\{\boldsymbol{0}\}:$  the trivial vector space;  $\mbox{ dim }\{\boldsymbol{0}\}=0$

#### How to find a basis?

**Theorem** Let V be a vector space. Then (i) any spanning set for V contains a basis; (ii) any linearly independent subset of V is contained in a basis.

Approach 1. Given a spanning set for the vector space, reduce this set to a basis.

Approach 2. Given a linearly independent set, extend this set to a basis.

#### How to find a basis?

Approach 1. Get a spanning set for the vector space, then reduce this set to a basis dropping one vector at a time.

**Proposition** Let  $\mathbf{v}_0, \mathbf{v}_1, \dots, \mathbf{v}_k$  be a spanning set for a vector space V. If  $\mathbf{v}_0$  is a linear combination of vectors  $\mathbf{v}_1, \dots, \mathbf{v}_k$  then  $\mathbf{v}_1, \dots, \mathbf{v}_k$  is also a spanning set for V.

Indeed, if 
$$\mathbf{v}_0 = r_1 \mathbf{v}_1 + \dots + r_k \mathbf{v}_k$$
, then  
 $t_0 \mathbf{v}_0 + t_1 \mathbf{v}_1 + \dots + t_k \mathbf{v}_k =$   
 $= (t_0 r_1 + t_1) \mathbf{v}_1 + \dots + (t_0 r_k + t_k) \mathbf{v}_k.$ 

#### How to find a basis?

Approach 2. Build a maximal linearly independent set adding one vector at a time.

If the vector space V is trivial, it has the empty basis. If  $V \neq \{\mathbf{0}\}$ , pick any vector  $\mathbf{v}_1 \neq \mathbf{0}$ . If  $\mathbf{v}_1$  spans V, it is a basis. Otherwise pick any vector  $\mathbf{v}_2 \in V$  that is not in the span of  $\mathbf{v}_1$ . If  $\mathbf{v}_1$  and  $\mathbf{v}_2$  span V, they constitute a basis. Otherwise pick any vector  $\mathbf{v}_3 \in V$  that is not in the span of  $\mathbf{v}_1$  and  $\mathbf{v}_2$ . And so on...

*Modifications.* Instead of the empty set, we can start with any linearly independent set (if we are given one). If we are given a spanning set S, it is enough to pick new vectors only in S.

*Remark.* This inductive procedure works for finite-dimensional vector spaces. There is an analogous procedure for infinite-dimensional spaces (*transfinite induction*).

Vectors  $\mathbf{v}_1 = (0, 1, 0)$  and  $\mathbf{v}_2 = (-2, 0, 1)$  are linearly independent.

**Problem.** Extend the set  $\{\mathbf{v}_1, \mathbf{v}_2\}$  to a basis for  $\mathbb{R}^3$ .

Our task is to find a vector  $\mathbf{v}_3$  that is not a linear combination of  $\mathbf{v}_1$  and  $\mathbf{v}_2$ .

Then  $\{\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3\}$  will be a basis for  $\mathbb{R}^3$ .

*Hint 1.*  $\mathbf{v}_1$  and  $\mathbf{v}_2$  span the plane x + 2z = 0.

The vector  $\mathbf{v}_3 = (1, 1, 1)$  does not lie in the plane x + 2z = 0, hence it is not a linear combination of  $\mathbf{v}_1$  and  $\mathbf{v}_2$ . Thus  $\{\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3\}$  is a basis for  $\mathbb{R}^3$ .

Vectors  $\mathbf{v}_1 = (0, 1, 0)$  and  $\mathbf{v}_2 = (-2, 0, 1)$  are linearly independent.

**Problem.** Extend the set  $\{\mathbf{v}_1, \mathbf{v}_2\}$  to a basis for  $\mathbb{R}^3$ . Our task is to find a vector  $\mathbf{v}_3$  that is not a linear combination of  $\mathbf{v}_1$  and  $\mathbf{v}_2$ . Then  $\{\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3\}$  will be a basis for  $\mathbb{R}^3$ .

*Hint 2.* Since vectors  $\mathbf{e}_1 = (1, 0, 0)$ ,  $\mathbf{e}_2 = (0, 1, 0)$ , and  $\mathbf{e}_3 = (0, 0, 1)$  form a spanning set for  $\mathbb{R}^3$ , at least one of them can be chosen as  $\mathbf{v}_3$ .

Let us check that  $\{\mathbf{v}_1, \mathbf{v}_2, \mathbf{e}_1\}$  and  $\{\mathbf{v}_1, \mathbf{v}_2, \mathbf{e}_3\}$  are two bases for  $\mathbb{R}^3$ :

$$\begin{vmatrix} 0 & -2 & 1 \\ 1 & 0 & 0 \\ 0 & 1 & 0 \end{vmatrix} = 1 \neq 0, \qquad \begin{vmatrix} 0 & -2 & 0 \\ 1 & 0 & 0 \\ 0 & 1 & 1 \end{vmatrix} = 2 \neq 0.$$

**Problem.** Find a basis for the vector space V spanned by vectors  $\mathbf{w}_1 = (1, 1, 0)$ ,  $\mathbf{w}_2 = (0, 1, 1)$ ,  $\mathbf{w}_3 = (2, 3, 1)$ , and  $\mathbf{w}_4 = (1, 1, 1)$ .

To pare this spanning set, we need to find a relation of the form  $r_1\mathbf{w}_1+r_2\mathbf{w}_2+r_3\mathbf{w}_3+r_4\mathbf{w}_4 = \mathbf{0}$ , where  $r_i \in \mathbb{R}$  are not all equal to zero. Equivalently,

$$\begin{pmatrix} 1 & 0 & 2 & 1 \\ 1 & 1 & 3 & 1 \\ 0 & 1 & 1 & 1 \end{pmatrix} \begin{pmatrix} r_1 \\ r_2 \\ r_3 \\ r_4 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix}$$

To solve this system of linear equations for  $r_1$ ,  $r_2$ ,  $r_3$ ,  $r_4$ , we apply row reduction.

$$\begin{pmatrix} 1 & 0 & 2 & 1 \\ 1 & 1 & 3 & 1 \\ 0 & 1 & 1 & 1 \end{pmatrix} \rightarrow \begin{pmatrix} 1 & 0 & 2 & 1 \\ 0 & 1 & 1 & 0 \\ 0 & 1 & 1 & 1 \end{pmatrix} \rightarrow \begin{pmatrix} 1 & 0 & 2 & 1 \\ 0 & 1 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix}$$

$$\rightarrow \begin{pmatrix} 1 & 0 & 2 & 0 \\ 0 & 1 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix}$$

$$\left\{ \begin{array}{c} r_{1} + 2r_{3} = 0 \\ r_{2} + r_{3} = 0 \\ r_{4} = 0 \end{array} \right. \iff \left\{ \begin{array}{c} r_{1} = -2r_{3} \\ r_{2} = -r_{3} \\ r_{4} = 0 \end{array} \right.$$

General solution:  $(r_1, r_2, r_3, r_4) = (-2t, -t, t, 0), t \in \mathbb{R}$ . Particular solution:  $(r_1, r_2, r_3, r_4) = (2, 1, -1, 0)$ . **Problem.** Find a basis for the vector space V spanned by vectors  $\mathbf{w}_1 = (1, 1, 0)$ ,  $\mathbf{w}_2 = (0, 1, 1)$ ,  $\mathbf{w}_3 = (2, 3, 1)$ , and  $\mathbf{w}_4 = (1, 1, 1)$ .

We have obtained that  $2\mathbf{w}_1 + \mathbf{w}_2 - \mathbf{w}_3 = \mathbf{0}$ . Hence any of vectors  $\mathbf{w}_1, \mathbf{w}_2, \mathbf{w}_3$  can be dropped. For instance,  $V = \text{Span}(\mathbf{w}_1, \mathbf{w}_2, \mathbf{w}_4)$ .

Let us check whether vectors  $\mathbf{w}_1, \mathbf{w}_2, \mathbf{w}_4$  are linearly independent:

$$\begin{vmatrix} 1 & 0 & 1 \\ 1 & 1 & 1 \\ 0 & 1 & 1 \end{vmatrix} = \begin{vmatrix} 1 & 0 & 1 \\ 0 & 1 & 0 \\ 0 & 1 & 1 \end{vmatrix} = \begin{vmatrix} 1 & 0 \\ 1 & 1 \end{vmatrix} = 1 \neq 0.$$

They are!!! It follows that  $V = \mathbb{R}^3$  and  $\{\mathbf{w}_1, \mathbf{w}_2, \mathbf{w}_4\}$  is a basis for V.

#### Row space of a matrix

Definition. The **row space** of an  $m \times n$  matrix A is the subspace of  $\mathbb{R}^n$  spanned by rows of A. The dimension of the row space is called the **rank** of the matrix A.

**Theorem 1** The rank of a matrix A is the maximal number of linearly independent rows in A.

**Theorem 2** Elementary row operations do not change the row space of a matrix.

**Theorem 3** If a matrix A is in row echelon form, then the nonzero rows of A are linearly independent.

**Corollary** The rank of a matrix is equal to the number of nonzero rows in its row echelon form.

Problem. Find the rank of the matrix

$$egin{array}{cccc} {m A} = egin{pmatrix} 1 & 1 & 0 \ 0 & 1 & 1 \ 2 & 3 & 1 \ 1 & 1 & 1 \end{pmatrix} \end{array}$$

.

Elementary row operations do not change the row space. Let us convert *A* to row echelon form:

$$\begin{pmatrix} 1 & 1 & 0 \\ 0 & 1 & 1 \\ 2 & 3 & 1 \\ 1 & 1 & 1 \end{pmatrix} \rightarrow \begin{pmatrix} 1 & 1 & 0 \\ 0 & 1 & 1 \\ 0 & 1 & 1 \\ 1 & 1 & 1 \end{pmatrix} \rightarrow \begin{pmatrix} 1 & 1 & 0 \\ 0 & 1 & 1 \\ 0 & 1 & 1 \\ 0 & 0 & 1 \end{pmatrix}$$

# $\begin{pmatrix} 1 & 1 & 0 \\ 0 & 1 & 1 \\ 0 & 1 & 1 \\ 0 & 0 & 1 \end{pmatrix} \rightarrow \begin{pmatrix} 1 & 1 & 0 \\ 0 & 1 & 1 \\ 0 & 0 & 0 \\ 0 & 0 & 1 \end{pmatrix} \rightarrow \begin{pmatrix} 1 & 1 & 0 \\ 0 & 1 & 1 \\ 0 & 0 & 1 \\ 0 & 0 & 0 \end{pmatrix}$

Vectors (1, 1, 0), (0, 1, 1), and (0, 0, 1) form a basis for the row space of A. Thus the rank of A is 3.

It follows that the row space of A is the entire space  $\mathbb{R}^3$ .

**Problem.** Find a basis for the vector space V spanned by vectors  $\mathbf{w}_1 = (1, 1, 0)$ ,  $\mathbf{w}_2 = (0, 1, 1)$ ,  $\mathbf{w}_3 = (2, 3, 1)$ , and  $\mathbf{w}_4 = (1, 1, 1)$ .

The vector space V is the row space of a matrix

$$\begin{pmatrix} 1 & 1 & 0 \\ 0 & 1 & 1 \\ 2 & 3 & 1 \\ 1 & 1 & 1 \end{pmatrix}$$

According to the solution of the previous problem, vectors (1, 1, 0), (0, 1, 1), and (0, 0, 1) form a basis for V.

## Column space of a matrix

*Definition.* The **column space** of an  $m \times n$  matrix *A* is the subspace of  $\mathbb{R}^m$  spanned by columns of *A*.

**Theorem 1** The column space of a matrix A coincides with the row space of the transpose matrix  $A^{T}$ .

**Theorem 2** Elementary row operations do not change linear relations between columns of a matrix.

**Theorem 3** Elementary row operations do not change the dimension of the column space of a matrix (however they can change the column space).

**Theorem 4** If a matrix is in row echelon form, then the columns with leading entries form a basis for the column space.

**Corollary** For any matrix, the row space and the column space have the same dimension.

**Problem.** Find a basis for the column space of the matrix

$$A=egin{pmatrix} 1 & 1 & 0 \ 0 & 1 & 1 \ 2 & 3 & 1 \ 1 & 1 & 1 \end{pmatrix}$$

The column space of A coincides with the row space of  $A^{T}$ . To find a basis, we convert  $A^{T}$  to row echelon form:

$$A^{T} = \begin{pmatrix} 1 & 0 & 2 & 1 \\ 1 & 1 & 3 & 1 \\ 0 & 1 & 1 & 1 \end{pmatrix} \rightarrow \begin{pmatrix} 1 & 0 & 2 & 1 \\ 0 & 1 & 1 & 0 \\ 0 & 1 & 1 & 1 \end{pmatrix} \rightarrow \begin{pmatrix} 1 & 0 & 2 & 1 \\ 0 & 1 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix}$$

Vectors (1, 0, 2, 1), (0, 1, 1, 0), and (0, 0, 0, 1) form a basis for the column space of A.

**Problem.** Find a basis for the column space of the matrix

$$A = \begin{pmatrix} 1 & 1 & 0 \\ 0 & 1 & 1 \\ 2 & 3 & 1 \\ 1 & 1 & 1 \end{pmatrix}$$

Alternative solution: We already know from a previous problem that the rank of A is 3. It follows that the columns of A are linearly independent. Therefore these columns form a basis for the column space.

**Problem.** Let V be a vector space spanned by vectors  $\mathbf{w}_1 = (1, 1, 0)$ ,  $\mathbf{w}_2 = (0, 1, 1)$ ,  $\mathbf{w}_3 = (2, 3, 1)$ , and  $\mathbf{w}_4 = (1, 1, 1)$ . Pare this spanning set to a basis for V.

Alternative solution: The vector space V is the column space of a matrix

$$B = \begin{pmatrix} 1 & 0 & 2 & 1 \\ 1 & 1 & 3 & 1 \\ 0 & 1 & 1 & 1 \end{pmatrix}.$$

The row echelon form of *B* is  $C = \begin{pmatrix} 1 & 0 & 2 & 1 \\ 0 & 1 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix}$ .

Columns of *C* with leading entries (1st, 2nd, and 4th) form a basis for the column space of *C*. It follows that the corresponding columns of *B* (i.e., 1st, 2nd, and 4th) form a basis for the column space of *B*. Thus  $\{\mathbf{w}_1, \mathbf{w}_2, \mathbf{w}_4\}$  is a basis for *V*.