

MATH 311

Topics in Applied Mathematics I

**Lecture 14:**  
**Linear independence.**

## Linear independence

*Definition.* Let  $V$  be a vector space. Vectors  $\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_k \in V$  are called **linearly dependent** if they satisfy a relation

$$r_1\mathbf{v}_1 + r_2\mathbf{v}_2 + \dots + r_k\mathbf{v}_k = \mathbf{0},$$

where the coefficients  $r_1, \dots, r_k \in \mathbb{R}$  are not all equal to zero. Otherwise vectors  $\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_k$  are called **linearly independent**. That is, if

$$r_1\mathbf{v}_1 + r_2\mathbf{v}_2 + \dots + r_k\mathbf{v}_k = \mathbf{0} \implies r_1 = \dots = r_k = 0.$$

A set  $S \subset V$  is **linearly dependent** if one can find some distinct linearly dependent vectors  $\mathbf{v}_1, \dots, \mathbf{v}_k$  in  $S$ . Otherwise  $S$  is **linearly independent**.

## Examples of linear independence

- Vectors  $\mathbf{e}_1 = (1, 0, 0)$ ,  $\mathbf{e}_2 = (0, 1, 0)$ , and  $\mathbf{e}_3 = (0, 0, 1)$  in  $\mathbb{R}^3$ .

$$x\mathbf{e}_1 + y\mathbf{e}_2 + z\mathbf{e}_3 = \mathbf{0} \implies (x, y, z) = \mathbf{0} \\ \implies x = y = z = 0$$

- Matrices  $E_{11} = \begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix}$ ,  $E_{12} = \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix}$ ,

$$E_{21} = \begin{pmatrix} 0 & 0 \\ 1 & 0 \end{pmatrix}, \text{ and } E_{22} = \begin{pmatrix} 0 & 0 \\ 0 & 1 \end{pmatrix}.$$

$$aE_{11} + bE_{12} + cE_{21} + dE_{22} = O \implies \begin{pmatrix} a & b \\ c & d \end{pmatrix} = O \\ \implies a = b = c = d = 0$$

## Examples of linear independence

- Polynomials  $1, x, x^2, \dots, x^n$ .

$$a_0 + a_1x + a_2x^2 + \dots + a_nx^n = 0 \text{ identically}$$

$$\implies a_i = 0 \text{ for } 0 \leq i \leq n$$

- The infinite set  $\{1, x, x^2, \dots, x^n, \dots\}$ .

- Polynomials  $p_1(x) = 1$ ,  $p_2(x) = x - 1$ , and  $p_3(x) = (x - 1)^2$ .

$$\begin{aligned} a_1p_1(x) + a_2p_2(x) + a_3p_3(x) &= a_1 + a_2(x - 1) + a_3(x - 1)^2 = \\ &= (a_1 - a_2 + a_3) + (a_2 - 2a_3)x + a_3x^2. \end{aligned}$$

Hence  $a_1p_1(x) + a_2p_2(x) + a_3p_3(x) = 0$  identically

$$\implies a_1 - a_2 + a_3 = a_2 - 2a_3 = a_3 = 0$$

$$\implies a_1 = a_2 = a_3 = 0$$

**Problem** Let  $\mathbf{v}_1 = (1, 2, 0)$ ,  $\mathbf{v}_2 = (3, 1, 1)$ , and  $\mathbf{v}_3 = (4, -7, 3)$ . Determine whether vectors  $\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3$  are linearly independent.

We have to check if there exist  $r_1, r_2, r_3 \in \mathbb{R}$  not all zero such that  $r_1\mathbf{v}_1 + r_2\mathbf{v}_2 + r_3\mathbf{v}_3 = \mathbf{0}$ .

This vector equation is equivalent to a system

$$\begin{cases} r_1 + 3r_2 + 4r_3 = 0 \\ 2r_1 + r_2 - 7r_3 = 0 \\ 0r_1 + r_2 + 3r_3 = 0 \end{cases} \quad \left( \begin{array}{ccc|c} 1 & 3 & 4 & 0 \\ 2 & 1 & -7 & 0 \\ 0 & 1 & 3 & 0 \end{array} \right)$$

The vectors  $\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3$  are linearly dependent if and only if the coefficient matrix  $A = (\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3)$  is singular. We obtain that  $\det A = 0$ .

**Theorem** The following conditions are equivalent:

(i) vectors  $\mathbf{v}_1, \dots, \mathbf{v}_k$  are linearly dependent;

(ii) one of vectors  $\mathbf{v}_1, \dots, \mathbf{v}_k$  is a linear combination of the other  $k - 1$  vectors.

*Proof:* (i)  $\implies$  (ii) Suppose that

$$r_1\mathbf{v}_1 + r_2\mathbf{v}_2 + \cdots + r_k\mathbf{v}_k = \mathbf{0},$$

where  $r_i \neq 0$  for some  $1 \leq i \leq k$ . Then

$$\mathbf{v}_i = -\frac{r_1}{r_i}\mathbf{v}_1 - \cdots - \frac{r_{i-1}}{r_i}\mathbf{v}_{i-1} - \frac{r_{i+1}}{r_i}\mathbf{v}_{i+1} - \cdots - \frac{r_k}{r_i}\mathbf{v}_k.$$

(ii)  $\implies$  (i) Suppose that

$$\mathbf{v}_i = s_1\mathbf{v}_1 + \cdots + s_{i-1}\mathbf{v}_{i-1} + s_{i+1}\mathbf{v}_{i+1} + \cdots + s_k\mathbf{v}_k$$

for some scalars  $s_j$ . Then

$$s_1\mathbf{v}_1 + \cdots + s_{i-1}\mathbf{v}_{i-1} - \mathbf{v}_i + s_{i+1}\mathbf{v}_{i+1} + \cdots + s_k\mathbf{v}_k = \mathbf{0}.$$

**Theorem** Vectors  $\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_m \in \mathbb{R}^n$  are linearly dependent whenever  $m > n$  (i.e., the number of coordinates is less than the number of vectors).

*Proof:* Let  $\mathbf{v}_j = (a_{1j}, a_{2j}, \dots, a_{nj})$  for  $j = 1, 2, \dots, m$ . Then the vector equality  $t_1\mathbf{v}_1 + t_2\mathbf{v}_2 + \dots + t_m\mathbf{v}_m = \mathbf{0}$  is equivalent to the system

$$\begin{cases} a_{11}t_1 + a_{12}t_2 + \dots + a_{1m}t_m = 0, \\ a_{21}t_1 + a_{22}t_2 + \dots + a_{2m}t_m = 0, \\ \dots\dots\dots \\ a_{n1}t_1 + a_{n2}t_2 + \dots + a_{nm}t_m = 0. \end{cases}$$

Note that vectors  $\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_m$  are columns of the coefficient matrix  $(a_{ij})$ . The number of leading entries in the row echelon form is at most  $n$ . If  $m > n$  then there are free variables, therefore the zero solution is not unique.

*Example.* Consider vectors  $\mathbf{v}_1 = (1, -1, 1)$ ,  $\mathbf{v}_2 = (1, 0, 0)$ ,  $\mathbf{v}_3 = (1, 1, 1)$ , and  $\mathbf{v}_4 = (1, 2, 4)$  in  $\mathbb{R}^3$ .

Two vectors are linearly dependent if and only if they are parallel. Hence  $\mathbf{v}_1$  and  $\mathbf{v}_2$  are linearly independent.

Vectors  $\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3$  are linearly independent if and only if the matrix  $A = (\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3)$  is invertible.

$$\det A = \begin{vmatrix} 1 & 1 & 1 \\ -1 & 0 & 1 \\ 1 & 0 & 1 \end{vmatrix} = - \begin{vmatrix} -1 & 1 \\ 1 & 1 \end{vmatrix} = 2 \neq 0.$$

Therefore  $\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3$  are linearly independent.

Four vectors in  $\mathbb{R}^3$  are always linearly dependent.

Thus  $\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3, \mathbf{v}_4$  are linearly dependent.



**Problem.** Let  $A = \begin{pmatrix} -1 & 1 \\ -1 & 0 \end{pmatrix}$ . Determine whether matrices  $A$ ,  $A^2$ , and  $A^3$  are linearly independent.

We have  $A = \begin{pmatrix} -1 & 1 \\ -1 & 0 \end{pmatrix}$ ,  $A^2 = \begin{pmatrix} 0 & -1 \\ 1 & -1 \end{pmatrix}$ ,  $A^3 = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$ .

The task is to check if there exist  $r_1, r_2, r_3 \in \mathbb{R}$  not all zero such that  $r_1A + r_2A^2 + r_3A^3 = O$ .

This matrix equation is equivalent to a system

$$\begin{cases} -r_1 + 0r_2 + r_3 = 0 \\ r_1 - r_2 + 0r_3 = 0 \\ -r_1 + r_2 + 0r_3 = 0 \\ 0r_1 - r_2 + r_3 = 0 \end{cases} \quad \left( \begin{array}{ccc|c} -1 & 0 & 1 & 0 \\ 1 & -1 & 0 & 0 \\ -1 & 1 & 0 & 0 \\ 0 & -1 & 1 & 0 \end{array} \right) \rightarrow \left( \begin{array}{ccc|c} 1 & -1 & 0 & 0 \\ 0 & 1 & -1 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{array} \right)$$

The row echelon form of the augmented matrix shows there is a free variable. Hence the system has a nonzero solution so that the matrices are linearly dependent (one relation is  $A + A^2 + A^3 = O$ ).

**Problem.** Show that functions  $e^x$ ,  $e^{2x}$ , and  $e^{3x}$  are linearly independent in  $C^\infty(\mathbb{R})$ .

Suppose that  $ae^x + be^{2x} + ce^{3x} = 0$  for all  $x \in \mathbb{R}$ , where  $a, b, c$  are constants. We have to show that  $a = b = c = 0$ .

Differentiate this identity twice:

$$\begin{aligned}ae^x + be^{2x} + ce^{3x} &= 0, \\ae^x + 2be^{2x} + 3ce^{3x} &= 0, \\ae^x + 4be^{2x} + 9ce^{3x} &= 0.\end{aligned}$$

It follows that  $A(x)\mathbf{v} = \mathbf{0}$ , where

$$A(x) = \begin{pmatrix} e^x & e^{2x} & e^{3x} \\ e^x & 2e^{2x} & 3e^{3x} \\ e^x & 4e^{2x} & 9e^{3x} \end{pmatrix}, \quad \mathbf{v} = \begin{pmatrix} a \\ b \\ c \end{pmatrix}.$$

$$A(x) = \begin{pmatrix} e^x & e^{2x} & e^{3x} \\ e^x & 2e^{2x} & 3e^{3x} \\ e^x & 4e^{2x} & 9e^{3x} \end{pmatrix}, \quad \mathbf{v} = \begin{pmatrix} a \\ b \\ c \end{pmatrix}.$$

$$\begin{aligned} \det A(x) &= e^x \begin{vmatrix} 1 & e^{2x} & e^{3x} \\ 1 & 2e^{2x} & 3e^{3x} \\ 1 & 4e^{2x} & 9e^{3x} \end{vmatrix} = e^x e^{2x} \begin{vmatrix} 1 & 1 & e^{3x} \\ 1 & 2 & 3e^{3x} \\ 1 & 4 & 9e^{3x} \end{vmatrix} \\ &= e^x e^{2x} e^{3x} \begin{vmatrix} 1 & 1 & 1 \\ 1 & 2 & 3 \\ 1 & 4 & 9 \end{vmatrix} = e^{6x} \begin{vmatrix} 1 & 1 & 1 \\ 1 & 2 & 3 \\ 1 & 4 & 9 \end{vmatrix} = e^{6x} \begin{vmatrix} 1 & 1 & 1 \\ 0 & 1 & 2 \\ 1 & 4 & 9 \end{vmatrix} \\ &= e^{6x} \begin{vmatrix} 1 & 1 & 1 \\ 0 & 1 & 2 \\ 0 & 3 & 8 \end{vmatrix} = e^{6x} \begin{vmatrix} 1 & 2 \\ 3 & 8 \end{vmatrix} = 2e^{6x} \neq 0. \end{aligned}$$

Since the matrix  $A(x)$  is invertible, we obtain

$$A(x)\mathbf{v} = \mathbf{0} \implies \mathbf{v} = \mathbf{0} \implies a = b = c = 0$$

## Wronskian

Let  $f_1, f_2, \dots, f_n$  be smooth functions on an interval  $[a, b]$ . The **Wronskian**  $W[f_1, f_2, \dots, f_n]$  is a function on  $[a, b]$  defined by

$$W[f_1, f_2, \dots, f_n](x) = \begin{vmatrix} f_1(x) & f_2(x) & \cdots & f_n(x) \\ f_1'(x) & f_2'(x) & \cdots & f_n'(x) \\ \vdots & \vdots & \ddots & \vdots \\ f_1^{(n-1)}(x) & f_2^{(n-1)}(x) & \cdots & f_n^{(n-1)}(x) \end{vmatrix}.$$

**Theorem** If  $W[f_1, f_2, \dots, f_n](x_0) \neq 0$  for some  $x_0 \in [a, b]$  then the functions  $f_1, f_2, \dots, f_n$  are linearly independent in  $C[a, b]$ .