# Lecture 15:

**MATH 614** 

Dynamical Systems and Chaos

Maps of the circle.

### Circle $S^1$ .

(multi-valued function)

Circle 
$$S^1$$
.

 $S^1 = \{(x,y) \in \mathbb{R}^2 : |x|^2 + |y|^2 = 1\}$ 
 $S^1 = \{z \in \mathbb{C} : |z| = 1\}$ 
 $\mathbb{T}^1 = \mathbb{R}/\mathbb{Z}$ 
 $\mathbb{T}^1 = \mathbb{R}/2\pi\mathbb{Z}$ 
 $\alpha : S^1 \to [0, 2\pi),$ 
angular coordinate
 $\alpha : S^1 \to \mathbb{R}/2\pi\mathbb{Z} \to \mathbb{R}$ 

$$\phi: \mathbb{R} o \mathcal{S}^1$$
,

 $\phi: \mathbb{R} \to \mathcal{S}$ ,  $\phi(x) = (\cos x, \sin x), \quad S^1 \subset \mathbb{R}^2.$ 

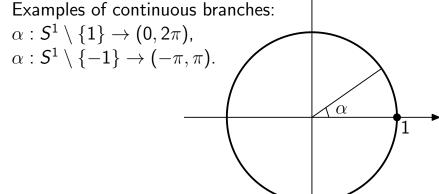
$$\phi(x) = (\cos x, \sin x), \quad S^1 \subset \mathbb{R}^2.$$
  
 $\phi(x) = e^{ix} = \cos x + i \sin x, \quad S^1 \subset \mathbb{C}.$ 

 $\phi$ : wrapping map  $\phi(x + 2\pi k) = \phi(x), k \in \mathbb{Z}.$ 

$$\alpha \in \mathbb{R}$$
 is an angular coordinate of  $x \in S^1$  if and only if  $\phi(\alpha) = x$ .

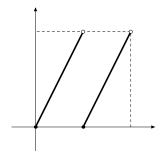
For any arc  $\gamma \subset S^1$  there exists a continuous branch  $\alpha: \gamma \to \mathbb{R}$  of the angular coordinate.

If  $\alpha_1 : \gamma \to \mathbb{R}$  and  $\alpha_2 : \gamma \to \mathbb{R}$  are two continuous branches then  $\alpha_1 - \alpha_2$  is a constant  $2\pi k$ ,  $k \in \mathbb{Z}$ .



 $f: S^1 \to S^1$ , continuous map

Example.  $D: z \mapsto z^2$  (doubling map) in angular coordinates:  $\alpha \mapsto 2\alpha \pmod{2\pi}$ .



The doubling map: smooth, 2-to-1, no critical points.

**Theorem** The doubling map is chaotic.

## Orientation-preserving and orientation-reversing

The real line  $\mathbb{R}$  has two orientations.

For maps of an interval: orientation-preserving = monotone increasing, orientation-reversing = monotone decreasing.

The circle  $S^1$  also has two orientations (clockwise and counterclockwise).

Given a map  $f: S^1 \to S^1$ , we say that a map  $F: \mathbb{R} \to \mathbb{R}$  is a **lift** of f if  $f \circ \phi = \phi \circ F$ , where  $\phi: \mathbb{R} \to S^1$  is the wrapping map. Any continuous map  $f: S^1 \to S^1$  admits a continuous lift F. The lift satisfies  $F(x+2\pi) - F(x) = 2\pi k$  for some  $k \in \mathbb{Z}$  and all  $x \in \mathbb{R}$ . If  $F_0$  is another continuous lift of f, then  $F - F_0$  is a constant function.

A continuous map  $f: S^1 \to S^1$  is **orientation-preserving** (resp., **orientation-reversing**) if so is the continuous lift of f.

Maps of the circle

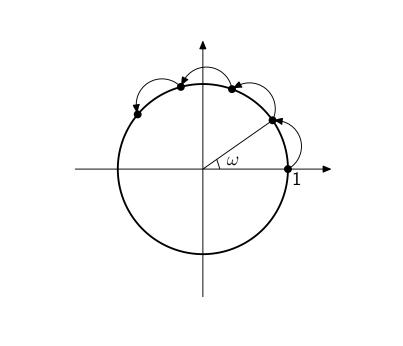
 $f: S^1 \to S^1$ , f an orientation-preserving homeomorphism.

#### Rotations of the circle

 $R_{\omega}: S^1 \to S^1$ , rotation by angle  $\omega \in \mathbb{R}$ .

 $R_{\omega}(z) = e^{i\omega}z$ , complex coordinate z;

 $R_{\omega}(\alpha) = \alpha + \omega \pmod{2\pi}$ , angular coordinate  $\alpha$ .



#### Rotations of the circle

 $R_{\omega}: S^1 \to S^1$ , rotation by angle  $\omega \in \mathbb{R}$ .  $R_{\omega}(z) = e^{i\omega}z$ , complex coordinate z;  $R_{\omega}(\alpha) = \alpha + \omega \pmod{2\pi}$ , angular coordinate  $\alpha$ .

Each  $R_{\omega}$  is an orientation-preserving diffeomorphism; each  $R_{\omega}$  is an isometry; each  $R_{\omega}$  preserves Lebesgue measure on  $S^1$ .

 $R_{\omega}$  is a one-parameter family of maps.  $R_{\omega}$  is a **transformation group**.

Indeed,  $R_{\omega_1}R_{\omega_2}=R_{\omega_1+\omega_2}$ ,  $R_{\omega}^{-1}=R_{-\omega}$ . It follows that  $R_{\omega}^n=R_{n\omega}$ ,  $n=1,2,\ldots$ . Also,  $R_0=\mathrm{id}$  and  $R_{\omega+2\pi k}=R_{\omega}$ ,  $k\in\mathbb{Z}$ . An angle  $\omega$  is called **rational** if  $\omega = r\pi$ ,  $r \in \mathbb{Q}$ . Otherwise  $\omega$  is an **irrational** angle.

If  $\omega$  is a rational angle then  $R_{\omega}$  is a periodic map. All points of  $S^1$  are periodic of the same period.

If  $\omega = 2\pi m/n$ , where m and n are coprime integers, n > 0, then the period of  $R_{\omega}$  is n.

If  $\omega$  is irrational then  $R_{\omega}$  has no periodic points. If  $\omega$  is irrational then  $R_{\omega}$  is **minimal**: each orbit is dense in  $S^1$ .

If  $\omega$  is irrational then each orbit of  $R_{\omega}$  is **uniformly** distributed in  $S^1$ .

## **Minimality**

**Theorem (Jacobi)** Suppose  $\omega$  is an irrational angle. Then the rotation  $R_{\omega}$  is minimal: all orbits of  $R_{\omega}$  are dense in  $S^1$ .

*Proof:* Take an arc  $\gamma \subset S^1$ . Then  $R_\omega^n(\gamma)$ ,  $n \geq 1$ , is an arc of the same length as  $\gamma$ . Since  $S^1$  has finite length, the arcs  $\gamma, R_\omega(\gamma), R_\omega^2(\gamma), \ldots$  cannot all be disjoint. Hence  $R_\omega^n(\gamma) \cap R_\omega^m(\gamma) \neq \emptyset$  for some  $0 \leq n < m$ . But  $R_\omega^n(\gamma) \cap R_\omega^m(\gamma) = R_\omega^n(\gamma \cap R_\omega^{m-n}(\gamma))$  so  $\gamma \cap R_\omega^{m-n}(\gamma) \neq \emptyset$ .

Thus for any  $\varepsilon>0$  there exists  $k\geq 1$  such that  $R_\omega^k=R_{k\omega}$  is the rotation by an angle  $\omega'$ ,  $|\omega'|<\varepsilon$ . Note that  $\omega'\neq 0$  since  $\omega$  is an irrational angle. Pick any  $x\in S^1$ . Let  $n=\lceil 2\pi/|\omega'|\rceil$ . Then points  $x,R_{k\omega}(x),R_{k\omega}^2(x),\ldots,R_{k\omega}^n(x)$  divide  $S^1$  into arcs of length  $<\varepsilon$ .

#### **Uniform distribution**

Let  $T: S^1 \to S^1$  be a homeomorphism and  $x \in S^1$ . Consider the orbit  $x, T(x), T^2(x), \ldots, T^n(x), \ldots$ 

Let  $\gamma \subset S^1$  be an arc. By  $N(x, \gamma; n)$  denote the number of integers  $k \in \{0, 1, ..., n-1\}$  such that  $T^k(x) \in \gamma$ . The orbit of x is **uniformly distributed** in  $S^1$  if

$$\lim_{n\to\infty}\frac{N(x,\gamma_1;n)}{N(x,\gamma_2;n)}=1$$

for any two arcs  $\gamma_1$  and  $\gamma_2$  of the same length.

An equivalent condition:

$$\lim_{n\to\infty}\frac{N(x,\gamma_1;n)}{N(x,\gamma_2;n)}=\frac{length(\gamma_1)}{length(\gamma_2)}$$

for any arcs  $\gamma_1$  and  $\gamma_2$ .

Another equivalent condition:

$$\lim_{n\to\infty} \frac{N(x,\gamma;n)}{n} = \frac{length(\gamma)}{2\pi}$$

for any arc  $\gamma$ .

**Theorem (Kronecker-Weyl)** Suppose  $\omega$  is an irrational angle. Then all orbits of the rotation  $R_{\omega}$  are uniformly distributed in  $S^1$ .

## Fractional linear transformations of $S^1$

A fractional linear transformation of the complex plane  $\mathbb C$  is given by

$$f(z) = \frac{az+b}{cz+d},$$
  $a, b, c, d \in \mathbb{C}.$ 

How can we tell if  $f(S^1) = S^1$ ? This happens in the case

$$f(z)=e^{i\psi}\frac{z-z_0}{\overline{z}_0z-1},$$

where  $|z_0| \neq 1$  and  $\psi \in \mathbb{R}$ . Indeed, if  $z \in S^1$  then  $z = e^{i\alpha}$ ,  $z_0 = re^{i\beta}$ ,  $z - z_0 = e^{i\alpha} - re^{i\beta} = e^{i\alpha}(1 - re^{i\beta}e^{-i\alpha})$ ,  $\bar{z}_0z - 1 = re^{-i\beta}e^{i\alpha} - 1$  so that  $f(z) \in S^1$ .

## Fractional linear transformations of $S^1$

$$S^1 = \{ z \in \mathbb{C} : |z| = 1 \},$$
  
 $f : S^1 \to S^1,$ 

$$f(z) = -e^{i\omega}\frac{z-z_0}{\overline{z}_0z-1},$$

where  $z \in \mathbb{C}$ ,  $|z_0| \neq 1$  and  $\omega \in \mathbb{R}$ .

Fractional linear transformations of  $S^1$  form a **group**. Rotations of the circle form a **subgroup**  $(z_0 = 0)$ .

f is orientation-preserving if  $|z_0| < 1$  and orientation-reversing if  $|z_0| > 1$ .

$$rac{az+b}{cz+d}\mapsto \left(egin{array}{cc} a&b\c&d \end{array}
ight).$$

 $f(z) = \frac{az+b}{cz+d}, \quad g(z) = \frac{a'z+b'}{c'z+d'},$ 

 $f(g(z)) = \frac{a\frac{a'z+b'}{c'z+d'}+b}{c\frac{a'z+b'}{c'z+d'}+d} = \frac{(aa'+bc')z+ab'+bd'}{(ca'+dc')z+cb'+dd'},$ 

Composition of fractional linear transformations corresponds to matrix multiplication.

$$f(z)=-e^{i\omega}rac{z-z_0}{ar{z}_0z-1}, \ -e^{i\omega/2}\left(egin{array}{cc} e^{i\omega/2} & -z_0e^{i\omega/2} \ -ar{z}_0e^{-i\omega/2} & e^{-i\omega/2} \end{array}
ight).$$

$$\det = 1 - |z_0|^2$$
,  $\operatorname{Tr} = e^{i\omega/2} + e^{-i\omega/2} = 2\cos(\omega/2)$ .

Characteristic equation:

$$\lambda^2 - 2\cos(\omega/2)\lambda + 1 - |z_0|^2 = 0.$$

Discriminant:

$$D = \cos^2(\omega/2) - 1 + |z_0|^2 = |z_0|^2 - \sin^2(\omega/2).$$

If D < 0 then f is **elliptic**.

If D = 0 then f is parabolic. If D > 0 then f is hyperbolic. **Theorem (i)** If f is elliptic then f has no fixed points and is topologically conjugate to a rotation. **(ii)** If f is parabolic then f has a unique fixed point, which is neutral. Besides, the fixed point is weakly semi-attracting and semi-repelling.

(iii) If f is hyperbolic then f has two fixed points; one is attracting, the other is repelling.

Example. Given  $\omega \in (0, \pi)$ , the one-parameter family

$$f_r(z) = e^{i\omega} \frac{z-r}{1-rz}, \quad 0 \le r < 1$$

undergoes a saddle-node bifurcation at  $r = r_0 = |\sin(\omega/2)|$ .