On the complexity of the permanent in various computational models

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Abstract

We answer a question in [10], showing the regular determinantal complexity of the determinant det_m is $O(m^3)$. We answer questions in, and generalize results of [2], showing there is no rank one determinantal expression for perm_m or det_m when $m \ge 3$. Finally we state and prove several "folklore" results relating different models of computation.

1 Introduction

Let $P(y^1, \ldots, y^M) \in S^m \mathbb{C}^M$ be a homogeneous polynomial of degree *m* in *M* variables. A size *n* determinantal expression for *P* is an expression:

$$P = \det_n(\Lambda + \sum_{j=1}^M X^j y^j).$$
(1)

where X^{j} , Λ are $n \times n$ complex matrices.

The determinantal complexity of P, denoted dc(P), is the smallest n for which a size n determinantal expression exists for P. Valiant [17] proved that for any polynomial P, dc(P) is finite. Let $(y^{i,j})$, $1 \leq i, j \leq m$, be linear coordinates on the space of $m \times m$ matrices. Let $perm_m := \sum_{\sigma \in \mathfrak{S}_m} y^{1,\sigma(1)} \cdots y^{m,\sigma(m)}$ where \mathfrak{S}_m is the permutation group on m letters.

Valiant's famous algebraic analog of the $\mathbf{P} \neq \mathbf{NP}$ conjecture [17] is:

Conjecture 1.1 (Valiant [17]). The sequence $dc(perm_m)$ grows super-polynomially fast.

The state of the art regarding determinantal expressions for perm_m is $2^m - 1 \ge \operatorname{dc}(\operatorname{perm}_m) \ge \frac{m^2}{2}$, respectively [6, 12].

In the same paper [17], Valiant also made the potentially stronger conjecture that there is no polynomial sized arithmetic circuit computing perm_m .

There are two approaches towards conjectures such as Conjecture 1.1. One is to first prove them in *restricted models*, i.e., assuming extra hypotheses, with the goal of proving a conjecture by first proving it under weaker and weaker supplementary hypotheses until one arrives at the original conjecture. The second is to fix a complexity measure such as $dc(perm_m)$ and then to prove lower bounds on the complexity measure, which we will call *benchmarks*, and then

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improve the benchmarks. If one takes the first approach, it is important to be able to compare various restrictions. If one takes the second, and would like the flexibility of working in different (polynomially) equivalent models, one needs precise (not just polynomial) relations between the complexity measures. The primary purpose of this paper is to address these two issues.

We begin with comparing restrictions:

The first super-polynomial lower bound for the permanent in any non-trivial restricted model of computation was proved by Nisan in [15]: non-commutative formulas.

To our knowledge, the first exponential lower bound for the permanent that does not also hold for the determinant in any restricted model was $\binom{2m}{m} - 1$ in [10]. This model was *equiv*ariant determinantal expressions (see [10] for the definition). Let $\operatorname{edc}(P)$ denote the equivariant determinantal complexity of P. While $\operatorname{edc}(\operatorname{det}_m) = m$, and for a generic polynomial P, $\operatorname{edc}(P) = \operatorname{dc}(P)$, in [10] it was shown that $\operatorname{edc}(\operatorname{perm}_m) = \binom{2m}{m} - 1$. This paper is a follow-up to [10]. While equivariance is natural for geometry, it is not a typical restriction in computer science.

The restricted models in this paper have already appeared in the computer science literature: Raz's multi-linear circuits [16], Nisan's non-commutative formulas [15] and the "rank-k" determinantal expressions of Aravind and Joglekar [2].

Our results regarding different restricted models are:

- We answer a question in [10] regarding the regular determinantal complexity of the determinant, Proposition 2.3.
- We prove perm_m does not admit a rank one determinantal expression for $m \ge 3$, Theorem 2.9, answering a question posed in [2].

Regarding benchmarks, we make precise comparisons between different complexity measures, Theorem 4.1. Most of these relations were "known to the experts" in terms of the measures being polynomially related, but for the purposes of comparisons we need the more precise results presented here. In particular the homogeneous iterated matrix multiplication complexity is polynomially equivalent to determinantal complexity.

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2 Definitions, results, and overview

We first review the complexity measures corresponding to algebraic branching programs and iterated matrix multiplication:

Definition 2.1 (Nisan [15]). An Algebraic Branching Program (ABP) over \mathbb{C} is a directed acyclic graph Γ with a single source s and exactly one sink t. Each edge e is labeled with an affine linear function ℓ_e in the variables $\{y^i | 1 \leq i \leq M\}$. Every directed path $p = e_1 e_2 \cdots e_k$ represents the product $\Gamma_p := \prod_{j=1}^k \ell_{e_j}$. For each vertex v the polynomial Γ_v is defined as $\sum_{p \in \mathcal{P}_{s,v}} \Gamma_p$ where

 $\mathcal{P}_{s,v}$ is the set of paths from s to v. We say that Γ_v is computed by Γ at v. We also say that Γ_t is computed by Γ or that Γ_t is the output of Γ .

The size of Γ is the number of vertices. Let $\operatorname{abpc}(P)$ denote the smallest size of an algebraic branching program that computes P.

An ABP is *layered* if we can assign a layer $i \in \mathbb{N}$ to each vertex such that for all i, all edges from layer i go to layer i + 1. Let labpc(P) denote the smallest size of a layered algebraic branching program that computes P. Of course $labpc(P) \ge abpc(P)$.

An ABP is *homogeneous* if the polynomials computed at each vertex are all homogeneous.

A homogeneous ABP Γ is *degree layered* if Γ is layered and the layer of a vertex v coincides with the degree of v. For a homogeneous P let dlabpc(P) denote the smallest size of a degree layered algebraic branching program that computes P. Of course $dlabpc(P) \geq labpc(P)$.

Definition 2.2. The *iterated matrix multiplication complexity* of a polynomial P(y) in M variables, immc(P) is the smallest n such that there exists affine linear maps $B_j : \mathbb{C}^M \to \operatorname{Mat}_n(\mathbb{C})$, $j = 1, \ldots, n$, such that $P(y) = \operatorname{trace}(B_n(y) \cdots B_1(y))$. The homogeneous iterated matrix multiplication complexity of a degree m homogeneous polynomial $P \in S^m \mathbb{C}^M$, himmc(P), is the smallest n such that there exist natural numbers n_1, \ldots, n_m with $1 = n_1$, and $n = n_1 + \cdots + n_m$, and linear maps $A_s : \mathbb{C}^M \to \operatorname{Mat}_{n_s \times n_{s+1}}, 1 \leq s \leq m$, with the convention $n_{m+1} = n_1$, such that $P(y) = A_m(y) \cdots A_1(y)$.

A determinantal expression (1) is called *regular* if rank $\Lambda = n - 1$. The *regular determinantal* complexity of P, denoted rdc(P), is the smallest n for which a regular size n determinatal expression exists. Von zur Gathen [18] showed that any determinantal expression of a polynomial whose singular locus has codimension at least five, e.g., the permanent, must be regular. In particular $rdc(perm_m) = dc(perm_m)$.

All the interesting regular determinantal expressions for the permanent and determinant that we are aware of correspond to homogeneous iterated matrix multiplication expressions of the exact same complexity. For example, the expressions for det_m at the end of §3 are iterated matrix multiplication, where if the block matrices are labeled from left to right B_1, \ldots, B_m , the product is $B_m \cdots B_1$.

In [10], it was shown that if one assumes that the symmetry group of the expression captures about half the symmetry group of perm_m, then the smallest size such determinantal expression equals the known upper bound of $2^m - 1$. A key to the proof was the utilization of the Howe-Young duality endofunctor that exchanges symmetrization and skew-symmetrization. Indeed, the result was first proved for half equivariant regular determinantal expressions for the determinant, where the proof was not so difficult, and then the endofunctor served as a guide as to how one would need to prove it for the permanent. This motivated Question 2.18 of [10]: What is the growth of the function $rdc(det_m)$?

Proposition 2.3. $rdc(det_m) \le \frac{1}{3}(m^3 - m) + 1.$

Proposition 2.3 is proved in §3, where we show how to translate an ABP for a polynomial P into a regular determinantal expression for P. Translating work of Mahjan-Vinay [11] to determinantal expressions then gives the result.

Consider the following variant on multi-linear circuits and formulas: Let $M = M_1 + \cdots + M_m$ and let $P \in \mathbb{C}^{M_1} \otimes \cdots \otimes \mathbb{C}^{M_m} \subset S^m(\mathbb{C}^{M_1} \oplus \cdots \oplus \mathbb{C}^{M_m})$ be a multi-linear polynomial (sometimes called a *set-multilinear polynomial* in the computer science literature). We say a homogeneous iterated matrix multiplication (IMM) presentation of P is *block multi-linear* if each $A_j : \mathbb{C}^M \to$ $\operatorname{Mat}_{n_j \times n_{j+1}}$ is non-zero on exactly one factor. The size $2^m - 1$ determinantal expressions of [6, 10], as mentioned above, translate directly to homogeneous iterated matrix multiplication expressions. When one does this translation, the resulting expressions are block multilinear, where we assume that the $M = m^2$ variables of perm_m or det_m are grouped column-wise, so $M_j = m$ for all $1 \leq j \leq m$. We call block multilinear expressions with this grouping *column-wise multilinear*. That is, a column-wise multilinear ABP for the determinant is an iterated matrix multiplication, where each matrix only references variables from a single column of the original matrix.

The lower bound in the following result appeared in [15] in slightly different language:

Theorem 2.4. The smallest size column-wise multilinear IMM presentation of det_m and perm_m is $2^m - 1$. When translated to the regular determinantal expression model, these expressions respectively correspond to Grenet's expressions [6] in the case of the permanent and the expressions of [10] in the case of the determinant.

Remark 2.5. The $2^m - 1$ lower bound for the permanent (resp. determinant) of [10] was obtained by assuming "half-equivariance": equivariance with respect to left multiplication by diagonal matrices with determinant one (the torus) and permutation matrices (resp. equivariance with respect to left multiplication by matrices with determinant one and assuming a regular expression). The optimal determinantal expression for the permanent or determinant with half-equivariance is equivalent to a column-wise multilinear homogeneous iterated matrix multiplication expression of the same size, as can be seen in the proofs in [10]. On the other hand, column-wise multilinear IMM presentations do not imply half-equivariance, nor is there an implication in the other direction. It is interesting that these two different restricted models have the same optimal expression.

Theorem 2.4 even holds "locally":

Theorem 2.6. Any IMM presentation of $\det_m(y)$ or $\operatorname{perm}_m(y)$ with a size $L \times R$ sub-matrix of y appearing only in A_1, \ldots, A_L must have size at least $\binom{R}{L}$.

Remark 2.7. Theorem 2.6 shows that if L(m), R(m) are functions such that $\binom{R(m)}{L(m)}$ grows superpolynomially, any sequence of IMM presentations of perm_m (resp. IMM presentations of det_m) of polynomial size cannot have a size $L(m) \times R(m)$ sub-matrix (or a size $R(m) \times L(m)$ sub-matrix) of y appearing only in $A_1, \ldots, A_{L(m)}$ or $A_m, \ldots, A_{m-L(m)}$. In particular, if $R(m) = \alpha m$ for some constant $0 < \alpha \leq 1$, then to have a polynomial size presentation, L(m) must be bounded above by a constant.

Our second restricted model comes from [2]. In [2] they introduce *read-k* determinants, determinantal expressions where the X^{ij} have at most k nonzero entries, and show that perm_m cannot be expressed as a read once determinant over \mathbb{R} when $m \geq 5$. The notion of read-k is not natural from a geometric perspective as it is not preserved by the group preserving det_n, however in section 5 of the same paper they suggest a more meaningful analog inspired by [8] called *rank-k* determinants:

Definition 2.8. A polynomial $P(y^1, \ldots, y^M)$ admits a rank k determinantal expression if there is a determinantal expression $P(y) = \det(\Lambda + \sum_j y^j X^j)$ with rank $X^j \leq k$.

This definition is reasonable when P is the permanent because the individual $y^{i,j}$ are defined up to scale. In §6 we show: **Theorem 2.9.** Neither perm_m nor det_m admits a rank one regular determinantal expression over \mathbb{C} when $m \geq 3$. In particular, either perm_m nor det_m admits a read once regular determinantal expression over \mathbb{C} when $m \geq 3$.

Remark 2.10. Anderson, Shpilka and Volk (personal communication from Shpilka) have shown that if a polynomial P in n variables admits a rank k determinantal expression of size s, then it admits a read-k determinantal expression of size s + 2nk. This combined with the results of [2] gives an alternative proof of Theorem 2.9 over \mathbb{R} and finite fields where -3 is a quadratic non-residue for $m \geq 5$.

3 Algebraic branching programs and determinants

In this section we describe how to obtain a size $O(m^3)$ regular determinantal expression for det_m. We use standard techniques about algebraic branching programs and an algorithm described by Mahajan and Vinay [11].

Proposition 3.1. Let P be a polynomial. Then $dc(P) \leq labpc(P)-1$. Moreover, if the constant term of P is zero, then we also have $rdc(P) \leq labpc(P) - 1$.

Proof. ;From a layered algebraic branching program Γ^{algbp} we create a directed graph Γ^{root} by identifying the source and the sink vertex and by calling the resulting vertex the root vertex. ;From Γ^{root} we create a directed graph Γ^{loops} by adding at each non-root vertex a loop that is labeled with the constant 1. Let A denote the adjacency matrix of Γ^{loops} . Since Γ^{algbp} is layered, each path from the source to the sink in Γ^{algbp} has the same length. If that length is even, then $\det(A)$ equals the output of Γ^{algbp} , otherwise $-\det(A)$ equals the output of Γ^{algbp} . This proves the first part.

Now assume P has no constant term. Let Λ denote the constant part of A, so Λ is a complex square matrix. Since Γ^{algbp} is layered we ignore all edges coming out of the sink vertex of Γ^{algbp} and order all vertices of Γ^{algbp} topologically, i.e., if there is an edge from vertex u to vertex v, then u precedes v in the order. We use this order to specify the order in which we write down Λ . Since the order is topological, Λ is lower triangular with one exception: The first row can have additional nonzero entries. By construction of the loops in Γ^{loops} the main diagonal of Λ is filled with 1s everywhere but at the top left where Λ has a 0. Thus corank $(\Lambda) = 1$ or corank $(\Lambda) = 0$. But if corank $(\Lambda) = 0$, then the constant term of P is det $(\Lambda) \neq 0$, which is a contradiction to the assumption.

Proposition 3.2. $\operatorname{labpc}(\det_m) \leq \frac{m^3}{3} - \frac{m}{3} + 2.$

Proof. This is an analysis of the algorithm in [11] with all improvements that are described in the article. We construct an explicit layered ABP Γ . Each vertex of Γ is a triple of three nonnegative integers (h, u, i), where *i* indicates its layer. The following triples appear as vertices in Γ .

- The source (1, 1, 0).
- For all $1 \le i < m$:
 - The vertex (i + 1, i + 1, i).
 - For each $2 \le u \le m$ and each $1 \le h \le \min(i, u)$ the vertex (h, u, i).

• The sink (1, 1, m).

Lemma 3.3. The number of vertices in Γ is $\frac{m^3}{3} - \frac{m}{3} + 2$. There is only the source vertex in layer 0 and only the sink vertex in layer m. The number of vertices in layer $i \in \{1, \ldots, m-1\}$ is i(i+1)/2 + i(m-1).

Proof. By the above construction, the number of vertices in Γ equals

$$2 + \sum_{i=1}^{m-1} \left(1 + \sum_{u=2}^{m} \min(i, u) \right) = 1 + m + \sum_{i=1}^{m-1} \sum_{u=2}^{m} \min(i, u).$$

We see that $\sum_{i=1}^{m-1} \sum_{u=2}^{m} \min(i, u) = (m-2)(m-1)/2 + \sum_{i=1}^{m-1} \sum_{u=1}^{m-1} \min(i, u)$. It is easy to see that $\sum_{i=1}^{m-1} \sum_{u=1}^{m-1} \min(i, u)$ yields the square pyramidal numbers (OEIS¹ A000330): $m(m-1)(m-\frac{1}{2})/3$. Therefore

$$1 + m + \sum_{i=1}^{m-1} \sum_{u=2}^{m} \min(i, u) = 1 + m + m(m-1)(m-\frac{1}{2})/3 + (m-2)(m-1)/2 = \frac{m^3}{3} - \frac{m}{3} + 2.$$

To analyze a single layer $1 \le i \le m - 1$ we observe

$$1 + \sum_{u=2}^{m} \min(i, u) = \sum_{u=1}^{m} \min(i, u) = i(i+1)/2 + i(m-i).$$

We now describe the edges in Γ . The vertex (h, u, i) is positioned in the *i*th layer with only edges to the layer i + 1, with the exception that layer m - 1 has edges only to the sink. From (h, u, i) we have the following outgoing edges.

- If i + 1 < m:
 - for all $h+1 \leq v \leq m$ an edge to (h, v, i+1) labeled with x_v^u .
 - for all $h + 1 \le h' \le m$ an edge to (h', h', i + 1) labeled with $-x_h^u$.
- If i + 1 = m: An edge to the sink labeled with αx_h^u , where $\alpha = 1$ if m is odd and $\alpha = -1$ otherwise.

The fact that Γ actually computes det_m follows from [11].

As an illustration for m = 3, 4, 5 we include the adjacency matrices of the Γ^{loops} that come out of the combination of the constructions in Proposition 3.2 and Proposition 3.1.

0	0	0	0	x21	x31	x22	x32	x33
x12	1	0	0	0	0	0	0	0
x13	0	1	0	0	0	0	0	0
-x11	0	0	1	0	0	0	0	0
0	x22	x32	0	1	0	0	0	0
0	x23	x33	0	0	1	0	0	0
0	-x21	-x31	0	0	0	1	0	0
0	0	0	x23	0	0	0	1	0
0	-x21	-x31	-x22	0	0	0	0	1

¹http://oeis.org/

0	0	0	0	0	0	0	0	0	0	0	0	-x21	-x31	-x41	-x22	-x32	-x42	-x33	-x43	-x44											
x12	1	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0											
x13	0	1	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0											
x14	0	0	1	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0											
-x11	0	0	0	1	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0											
0	x22	x32	x42	0	1	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0											
0	x23	x33	x43	0	0	1	0	0	0	0	0	0	0	0	0	0	0	0	0	0											
0	x24	x34	x44	0	0	0	1	0	0	0	0	0	0	0	0	0	0	0	0	0											
0	-x21	-x31	-x41	0	0	0	0	1	0	0	0	0	0	0	0	0	0	0	0	0											
0	0	0	0	x23	0	0	0	0	1	0	0	0	0	0	0	0	0	0	0	0											
0	0	0	0	x24	0	0	0	0	0	1	0	0	0	0	0	0	0	0	0	0											
0	-x21	-x31	-x41	-x22	0	0	0	0	0	0	1	0	0	0	0	0	0	0	0	0											
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x12 x13 x14 x15 -x11 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	$ \begin{array}{c} 1 \\ 0 \\ 0 \\ 0 \\ 22 \\ x23 \\ x23 \\ x25 \\ -x21 \\ -2 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ $	0 0 1 1 0 0 0 0 1 0 0 0 0 0 0	$\begin{array}{cccccccccccccccccccccccccccccccccccc$	0 0 0 1 0 0 0 0 0 2 2 3 2 2 4 2 2 5 0 0 2 0 0 2 0 0 0 0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	$ \begin{array}{c} 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 $	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0	$\begin{array}{cccccccccccccccccccccccccccccccccccc$	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0	$\begin{array}{cccccccccccccccccccccccccccccccccccc$	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	$ \begin{array}{c} 0\\ 0\\ 0\\ 0\\ 0\\ 0\\ 0\\ 0\\ 0\\ 0\\ 0\\ 0\\ 0\\ $	$\begin{array}{cccccccccccccccccccccccccccccccccccc$	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	$\begin{array}{c} 0\\ 0\\ 0\\ 0\\ 0\\ 0\\ 0\\ 0\\ 0\\ 0\\ 0\\ 0\\ 0\\ $	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	0 C C 0 C C	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	000000000000000000000000000000000000000	$\begin{smallmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 &$	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	$\begin{smallmatrix} 0 & 0 \\ 0 $	$\begin{smallmatrix} 0 & 0 \\ 0 $	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	$\begin{smallmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 &$

See the ancillary files for larger values of m.

4 Iterated matrix multiplication and ABP's

The following result, while "known to the experts", is not easily accessible in the literature. Moreover, we give a precise formulation to facilitate measuring benchmark progress in different models.

In the following theorem note that himme and dlabpe are only defined for homogeneous polynomials.

Theorem 4.1. The complexity measures rdc, dc, labpc, immc, abpc, himmc, and dlabpc are all polynomially related. More precisely, let P be any polynomial. Let $\varphi(m) := \frac{m^3}{3} - \frac{m}{3} + 2$ denote the layered ABP size of the Mahajan-Vinay construction for det_m. Then

- 1. $dc(P) \leq labpc(P) 1$. If P has no constant part, then $rdc(P) \leq labpc(P) 1$.
- 2. $\operatorname{labpc}(P) \leq \varphi(\operatorname{dc}(P)).$
- 3. By definition $dc(P) \leq rdc(P)$. If P has no constant part, then $rdc(P) \leq \varphi(dc(P)) 1$. If $codim(P_{sing}) \geq 5$, then rdc(P) = dc(P).

- 4. $\operatorname{labpc}(P) = \operatorname{immc}(P) + 1$. If P is homogeneous, then $\operatorname{dlabpc}(P) = \operatorname{himmc}(P) + 1$.
- 5. By definition $\operatorname{abpc}(P) \leq \operatorname{labpc}(P) \leq \operatorname{dlabpc}(P)$, where $\operatorname{dlabpc}(P)$ is defined only if P is homogeneous. If P is homogeneous of degree d then $\operatorname{dlabpc}(P) \leq (d+1)\operatorname{abpc}(P)$.

Remark 4.2. It is an important and perhaps tractable open problem to prove an $\omega(m^2)$ lower bound for dc(perm_m). By Theorem 4.1, it would suffice to prove an $\omega(m^6)$ lower bound for himmc(perm_m).

Remark 4.3. The computation model of homogeneous iterated matrix multiplication has the advantage that one is comparing the homogeneous iterated matrix multiplication polynomial himm directly with the permanent, whereas with the determinant det_n, one must compare with the padded permanent ℓ^{n-m} perm_m. The padding causes insurmountable problems if one wants to find occurrence obstructions in the sense of [13, 14]. The problem was first observed in [9] and then proved insurmountable in [7] and [3]. Thus a priori it might be possible to prove Valiant's conjecture via occurrence obstructions in the himmc model. However, with the determinant already one needed to understand difficult properties about three factor Kronecker coefficients, and for the himmc model, one would need to prove results about *m*-factor Kronecker coefficients, which are not at all understood.

Regarding the geometric search for separating equations, the advantage one gains by removing the padding is offset by the disadvantage of dealing with the himme polynomial that for all known equations such as Young flattenings (which includes the method of shifted partial derivatives as a special case) and equations for degenerate dual varieties, behaves far more generically than the determinant.

Remark 4.4. One can also show that if P is any polynomial of degree d, then $labpc(P) \leq d(abpc(P)^2)$.

Remark 4.5. Another complexity measure is the homogeneous matrix powering complexity: If $P = \text{trace } (A^m)$, then $P = \text{trace } (A \cdot A \cdot \cdots \cdot A)$, thus $\text{himmc}(P) \leq m \cdot \text{hmpc}(P)$.

Conversely, if $\operatorname{himmc}(P) = n$, then $\operatorname{dlabpc}(P) = n + 1$, so there exists a degree layered APB Γ of size n + 1 with value P. Since all paths in Γ from the source to the sink have exactly length m we can identify the source and the sink and get a directed graph Γ' in which all closed directed walks have length exactly m. These closed walks are in bijection to paths from the source to the sink in Γ . Let A be the $n \times n$ adjacency matrix of Γ' . We can interpret trace (A^m) as the sum over all closed directed walks of length exactly m in Γ' , where the value of each walk is the product of its edge weights. We conclude that $P = \operatorname{trace}(A^m)$ and thus $\operatorname{hmpc}(P) \leq \operatorname{himmc}(P)$.

Proof of Theorem 4.1. (1) is Proposition 3.1.

Proof of (2): We first write the determinant polynomial $\det_{dc(P)}$ as a size $\varphi(dc(P))$ layered ABP Γ using 3.2. The projection that maps $\det_{dc(P)}$ to P can now be applied to Γ to yield a size $\varphi(dc(P))$ layered ABP of P.

Proof of (3): To see the second inequality we combine (1) and (2). The last assertion is von zur Gathen's result [18].

Proof of (4): We prove $\operatorname{labpc}(P) \leq \operatorname{immc}(P) + 1$. Given n_1, \ldots, n_m with $n_1 = 1$ and $n_1 + \cdots + n_m = \operatorname{immc}(P)$ and linear maps B_j , $1 \leq j \leq m$, we construct the ABP Γ that has a single vertex at level m+1, n_j vertices at level j, $1 \leq j \leq m$, and is the complete bipartite graph between levels. The labels of Γ are given by the B_j . We now prove $\operatorname{immc}(P) \leq \operatorname{labpc}(P) - 1$. Given a layered ABP Γ with m+1 layers, recall that by definition Γ has only 1 vertex in the

top layer and only one vertex in the bottom layer. Let n_j denote the number of vertices in layer $j, 1 \leq j \leq m$. Define the linear maps B_j by reading off the labels between layer j and layer j + 1. The proof of the second claim is analogous.

Proof of (5): (This argument was outlined in [15].) We first homogenize and then adjust the ABP. Replace each vertex v other than s by d + 1 vertices $v^1, v^2, \ldots, v^{d+1}$ corresponding to the homogeneous parts of Γ_v . Replace each edge e going from a vertex v to a vertex w by (2d + 1) edges, where we split the linear and constant parts: If e is labeled by $\ell + \delta$, where ℓ is linear and $\delta \in \mathbb{C}$, the edge from v^i to $w^i, 1 \leq i \leq d$, is labeled with δ and the edge from v^i to w^{i+1} , $1 \leq i \leq d-1$, is labeled with ℓ . We now have a homogeneous ABP. Our task is to make it degree layered. As a first approach we assign each degree i vertex to be in layer i, but there may be edges labeled with constants between vertices in the same layer. The edges between vertices of different layers are linear forms. Call the vertices in layer i that have edges incoming from layer i-1, layer i entry vertices. Remove the non-entry vertices. From entry vertex of layer i to entry vertex of layer i+1, use the linear form computed by the sub-ABP between them. In other words, for every pair (v, w) of layer i entry vertex v and layer i+1 entry vertex w, put an edge from v to w with weight

$$\sum_{p} \Pi_{e} \mathrm{weight}(e)$$

where the sum is over paths p from v to w and the product is over edges in the path p. The resulting ABP is degree homogeneous and computes P.

5 Proofs of Theorems 2.4 and 2.6

The following arguments appeared in [15] in slightly different language. We reproduce them in the language of this paper for convenience.

Proof of Theorem 2.4. This can be seen directly from a consideration about evaluation dimension that we explain now. We prove the stronger statement that the degree homogeneous ABP must have at least $\binom{m}{s}$ vertices at layer $s, 0 \le s \le m$. Summing up the binomial coefficients and using Theorem 4.1(4) yields the result.

We consider the degree homogeneous ABP Γ with m + 1 layers that computes \det_m (or perm_m). Keeping the labels from the source to layer s and setting the labels on all other layers to constants we see that all terms of the form $\sum_{\sigma \in \mathfrak{S}_m} c_\sigma y^{1,\sigma(1)} \cdots y^{s,\sigma(s)}$ can be computed by taking linear combinations of the polynomials Γ_v , where v is a vertex in layer s. Since these terms span a vector space of dimension $\binom{m}{s}$ there must be at least $\binom{m}{s}$ linearly independent polynomials Γ_v , so there must be at least $\binom{m}{s}$ vertices on layer s.

The Grenet determinantal presentation of $\operatorname{perm}_m[6]$ and the regular determinantal presentation of det_m of [10] give rise to column-wise multilinear IMM presentations of size $2^m - 1$. \Box

Proof of Theorem 2.6. The proof is essentially the same as the proof of Theorem 2.4. Without loss of generality assume it is the upper left $L \times R$ sub-matrix appearing in the first L terms. The terms of the form $\sum_{\sigma \in \mathfrak{S}_R} c_{\sigma} y_{\sigma(1)}^1 \cdots y_{\sigma(L)}^L$, with the c_{σ} nonzero constants, all appear in det_m and perm_m, so they must appear independently in the row vector $A_L \cdots A_1$. There are $\binom{R}{L}$ such terms so we conclude.

6 Proof of Theorem 2.9

6.1 Regular determinantal expressions

For $P \in S^m \mathbb{C}^M$ define the symmetry group of P:

$$G_P := \{ g \in GL_M \mid P(g \cdot y) = P(y) \; \forall y \in \mathbb{C}^M \}$$

The group G_{\det_n} essentially consists of multiplying an $n \times n$ matrix X on the left and right by matrices of determinant one, and the transpose map, $X \mapsto X^T$. Using G_{\det_n} , without loss of generality we may assume Λ in a regular determinantal expression is the identity matrix except with the (1, 1)-entry set equal to zero. We call a regular determinantal representation *standard* if Λ is so normalized.

Let the upper indices stand for variable names (i.e. positions in a small $m \times m$ matrix) and the lower indices stand for positions in a big $n \times n$ matrix. If A is an $n \times n$ matrix whose entries are affine linear forms in m^2 variables, then we write

$$A = \Lambda + y^{1,1}X^{1,1} + y^{1,2}X^{1,2} + \dots + y^{m,m}X^{m,m}$$

with $m^2 + 1$ matrices $\Lambda, X^{1,1}, X^{1,2}, \ldots, X^{m,m}$ of format $n \times n$. Lemma 6.1. If $det(A) \in \{\pm det_m, \pm perm_m\}$ and Λ is standard, then

- (I) $A_{1,1} = 0$,
- (II) $\sum_{j=2}^{n} A_{1,j} A_{j,1} = 0$
- (III) In the first column of A there are at least m different entries. The same holds for the first row of A.

Proof. As observed in [1], (I) and (II) hold in any regular determinantal expression for a homogeneous polynomial of degree $m \ge 2$ with standard Λ . To prove (III), by [5] (resp. [4]) $\{\det_m = 0\} \subset \mathbb{C}^{m^2}$ (resp. $\{\operatorname{perm}_m = 0\} \subset \mathbb{C}^{m^2}$) does not admit a linear subspace of dimension m(m-1) + 1. This implies that neither polynomial admits an expression of the form $\ell_1 p_1 + \cdots + \ell_{m-1} p_{m-1}$ with ℓ_j linear and p_j of degree m-1, as otherwise the common zero set of $\ell_1, \ldots, \ell_{m-1}$ would provide a linear space of dimension m(m-1) + 1 on the hypersurface. If we have a regular determinantal expression of perm_m or \det_m , this implies that at least m different linear forms appear in the first column of X and at least m different linear forms appear in the first row of X.

We are free to change our determinantal expression by elements of the group $G_{\det_n,\Lambda}$ preserving both \det_n and Λ , which by [10] is, for $M \in \operatorname{Mat}_{n \times n}(\mathbb{C})$:

$$\{M \mapsto \begin{pmatrix} \lambda & 0 \\ v & g \end{pmatrix} M \begin{pmatrix} 1 & w^T \\ 0 & g \end{pmatrix}^{-1} \mid g \in \operatorname{GL}_{n-1}, v \in \mathbb{C}^{n-1}, w \in \mathbb{C}^{n-1}, \lambda \in \mathbb{C}^*\} \cdot \langle \operatorname{transp} \rangle,$$

Where $\langle \text{transp} \rangle \simeq \mathbb{Z}_2$ is the group generated by transpose.

6.2 Rank one regular determinantal expressions

Theorem 2.9 will follow from Lemmas 6.2 and 6.3.

Lemma 6.2. Let $P_m \in S^m(Mat_{m \times m})$ be the permanent or determinant.

- 1. If P_{m_0} does not admit a rank k determinantal expression, then P_m does not admit a rank k determinantal expression for all $m \ge m_0$.
- 2. If P_{m_0} does not admit a rank k regular determinantal expression, then P_m does not admit a rank k regular determinantal expression for all $m \ge m_0$.

Proof. Without loss of generality $m = m_0 + 1$. Say P_m admitted a rank $k \ n \times n$ determinantal expression $A = \Lambda + \sum_{i,j=1}^{m} X^{i,j} y^{i,j}$. Set $y^{m,u} = y^{v,m} = 0$ for $1 \le u, v, \le m_0 = m - 1$. We obtain the matrix $\Lambda + X^{m,m} y^{m,m} + \sum_{u,v=1}^{m_0} X^{u,v} y^{u,v}$. This yields a rank k determinantal expression for $y^{m,m} \cdot P_{m_0}$, which proves the first part if we set $y^{m,m} = 1$.

For the second part, first note that every determinantal expression $P_{m_0} = \det(\Lambda' + \sum_{u,v=1}^{m_0} X^{u,v} y^{u,v})$ satisfies $\operatorname{rank}\Lambda' \leq n-1$ because P_{m_0} has no constant part. Thus to prove that a determinantal expression for P_{m_0} is regular it suffices to show that $\operatorname{rank}\Lambda' \geq n-1$.

Say P_m admitted a rank $k \ n \times n$ regular determinantal expression $A = \Lambda + \sum_{i,j=1}^m X^{i,j} y^{i,j}$, so rank $\Lambda = n - 1$. Then rank $(\Lambda + y_0^{m,m} X^{m,m}) \ge n - 1$ for almost all $y_0^{m,m} \in \mathbb{C}$. Choosing such a $y_0^{m,m} \ne 0$ we obtain a regular determinantal expression for $y_0^{m,m} \cdot P_{m_0}$. Rescaling the first rows of Λ and all $X^{i,j}$ with $\frac{1}{y_0^{m,m}}$ we get a regular determinantal expression for P_{m_0} . \Box

Lemma 6.3. Neither det_3 nor $perm_3$ admits a rank one regular determinantal representation.

The idea of the proof is simple: each monomial in the expression of perm₃ (or det₃) must have a contribution from the first column and the first row, say slots (s, 1) and (1, t). But then to have a homogeneous degree three expression, the third variable in the monomial must appear in the (t, s)-slot. This is sufficiently restrictive that one can conclude. Now for the details:

6.3 Proof of Lemma 6.3

Before proving the Lemma, we establish some preliminary results.

Lemma 6.4. Let $\det(A) \in \{\pm \det_3, \pm \operatorname{perm}_3\}$ and let Λ be standard. Let $1 \leq i_1, j_1, i_2, j_2, i_3, j_3 \leq 3$. If the monomial $y^{i_1,j_1} \cdot y^{i_2,j_2} \cdot y^{i_3,j_3}$ appears in $\det(A)$, then there exists a permutation $\pi \in \mathfrak{S}_3$ and integers $2 \leq k, \ell \leq n, k \neq \ell$ such that $X_{k,1}^{i_{\pi(1)},j_{\pi(1)}} \neq 0, X_{1,\ell}^{i_{\pi(2)},j_{\pi(2)}} \neq 0$, and $X_{\ell,k}^{i_{\pi(3)},j_{\pi(3)}} \neq 0$.

Proof. By Lemma 6.1(I) we have $A_{1,1} = 0$. For subsets $L, K \subseteq \{1, \ldots, n\}$ let A(L, K) denote the matrix that results from A by striking out the rows L and the columns K. In A set all variables to zero besides y^{i_1,j_1}, y^{i_2,j_2} , and y^{i_3,j_3} and call the resulting matrix B. Since det(A)is homogeneous of degree 3, every other monomial in det(A) involves one of the variables that were set to zero. Hence det $(B) = y^{i_1,j_1} \cdot y^{i_2,j_2} \cdot y^{i_3,j_3}$. In particular det $(B) \neq 0$. Since Λ has only zeros in the first row, we conclude that there exists a nonzero variable entry in the first row of B (in column $2, \ldots, n$), w.l.o.g. $X_{1,\ell}^{i_2,j_2} \neq 0$, whose minor det $(B(\{1\}, \{\ell\}))$ contains the summand $y^{i_1,j_1}y^{i_3,j_3}$. Since $B(\{1\}, \{\ell\})$ has no constant terms in the first column, a variable y^{i_1,j_1} or y^{i_3,j_3} must appear in the first column of $B(\{1\}, \{\ell\})$, w.l.o.g. $X_{k,1}^{i_1,j_1} \neq 0$, such that its minor det $(B(\{1,k\}, \{\ell, 1\}))$ contains the summand y^{i_3,j_3} . Assume for a moment that $k = \ell$, i.e., in the first column no other position has a y^{i_1,j_1} and in the first row no other position has a y^{i_2,j_2} . This is impossible due to Lemma 6.1(II).

Finally assume $k \neq \ell$. Since the constant part of $B(\{1,k\},\{\ell,1\})$ is a permutation matrix with a single hole, this hole is where $B(\{1,k\},\{\ell,1\})$ must have a nonzero entry y^{i_3,j_3} . In A this is at position (ℓ,k) .

We now give names to some standard operations on matrices that we will use in the upcoming arguments. We continue to assume Λ is standard.

- Adding/subtracting a multiple of the first column of A to other columns of A is called a first column operation. Analogously for first row operations. First row or first column operations belong to $G_{\det_n,\Lambda}$.
- If we add/subtract multiples of other rows/columns from each other we call this a *Gauss-Jordan operation*. Gauss-Jordan operations belong to G_{\det_n} but not $G_{\det_n,\Lambda}$.
- Let $2 \leq i, j \leq n$. Permuting rows *i* and *j* and then permuting columns *i* and *j* is called a *permutation conjugation*. Permutation conjugations belong to $G_{\det_n,\Lambda}$.
- Let $2 \leq i, j \leq n$. For $\alpha \in \mathbb{C}$, adding α times the *i*th row to the *j*th row of A and then subtracting α times the *j*th column from the *i*th column of A is called a *elimination* conjugation. Elimination conjugations belong to $G_{\det_n,\Lambda}$.

We are now ready to prove Lemma 6.3. We assume the contrary and let $P = \text{det}_3$ or $P = \text{perm}_3$ such that

- (1) A is an $n \times n$ matrix,
- (2) $\det(A) \in \{-P, P\},\$
- (3) $\operatorname{rk}\Lambda = n 1$,
- (4) $\operatorname{rk}(X^{i,j}) = 1$ for all $1 \le i, j \le 3$.

Note that the operations defined above all preserve (1)-(4). Thus performing a Gauss-Jordan elimination on Λ (and performing the operations on the whole matrix A) we can make Λ standard while preserving (1)-(4). So we can additionally assume:

(5) Λ is standard and hence properties (I),(II),(III) from Lemma 6.1 hold.

Using (5)(III) we pick a variable that appears in A in the first column. It cannot appear at position (1,1) because of (5)(I).

The operation of *permuting variable names* by permuting rows and/or columns of the 3×3 variable matrix preserves (1)-(5) and belongs to G_{perm_3} . Doing so we can assume that $X^{1,1}$ has a nonzero entry in column 1, not in position (1,1). Using permutation conjugation we can move this position to position (2,1). Using first column operations we can make $X^{1,1}$ have only zeros in row 2, besides the nonzero entry at position (2,1). Using elimination conjugation we can make $X^{1,1}$ have only zeros in column 1, besides the nonzero entry at position (2,1). Using (4) we see that $X^{1,1}$ only has a single nonzero entry: at position (2,1). So besides (1)-(5) we can assume:

(6) $X_{i,j}^{1,1} \neq 0$ iff (i,j) = (2,1).

Combining (5)(II) with (6) it follows that

$$A_{1,2} = 0.$$
 (6b)

We want to deduce more facts about A by setting several variables to zero. Set all variables in A to zero besides $y^{1,1}$, $y^{2,2}$, $y^{3,3}$ and call the resulting matrix B. From (2) it follows that we have

$$\det(B) = \pm y^{1,1} y^{2,2} y^{3,3}.$$
 (2b)

By (2b) the first row of B cannot be all zeros, so by (6) and the standardness granted by (5) we have that $X^{2,2}$ or $X^{3,3}$ have a nonzero entry in the first row. If $X^{2,2}$ has a nonzero entry, we permute the 2nd and 3rd row and column in the 3×3 variable matrix. This operation preserves (1)-(6), so we conclude that we can assume

(7) $X^{3,3}$ has a nonzero entry in the first row.

Combining (4) and (5)(I) it follows that

The first column of
$$X^{3,3}$$
 is zero. (7b)

Using permutation conjugation we want to move the nonzero entry from (7) in $X^{3,3}$ to position (1, n). Note that according to (5)(I) and (6b) this entry is in row 1 in some column $3, \ldots, n$. Permutation conjugation on indices $3, \ldots, n$ preserves (1)-(7). Thus we can use permutation conjugations to assume that

(8)
$$X_{1,n}^{3,3} \neq 0.$$

Using first row operations preserves (1)-(8), for example they preserve (6) because of (5)(I). Thus we can use first row operations to assume that

(9) The only nonzero entry of $X^{3,3}$ in column *n* is (1, n).

Elimination conjugation (adding α times column n to column $3 \le k \le n-1$ and then subtracting α times row k from row n) preserves (1)-(9). We use these operations together with (5)(I) and (6b) to assume that

(10) The only nonzero entry of $X^{3,3}$ in row 1 is (1, n).

Combining (4) with (9) and (10) we conclude

$$X_{i,j}^{3,3} \neq 0$$
 iff $(i,j) = (1,n).$ (10b)

With (5)(II) we conclude

$$A_{n,1} = 0.$$
 (10c)

Let A' denote the submatrix of A obtained by deleting the rows 1 and 2 and the columns 1 and n. By assumption det(A) has a summand $y^{1,1}y^{2,2}y^{3,3}$. Using (6) and (10b), a double Laplace expansion implies that det(A') has a term $y^{2,2}$. By the standardness granted by (5), the homogeneous degree 1 part of det(A') is precisely the entry at position (n, 2) in A. It follows that

$$X_{n,2}^{2,2} \neq 0.$$
 (10d)

We claim that

$$X_{n,2}^{i,j} = 0$$
 for all $(i,j) \neq (2,2)$. (10e)

Assume that $X_{n,2}^{i,j} \neq 0$ for some $1 \leq i, j \leq 3$. Set all variables in A to zero but $y^{1,1}, y^{3,3}$, and $y^{i,j}$, and call the resulting matrix E. Since $y^{1,1}$ and $y^{3,3}$ appear only once in A and since Λ is standard, the degree 3 part of det(E) contains all summands that appear in $y^{1,1} \cdot y^{3,3} \cdot q$, where q is the linear part of det $(A(\{1,2\},\{1,n\}))$. Indeed, q equals the linear part of A at position (n,2). Since det $(A) \in \{\det_3, \operatorname{perm}_3\}$ it follows that $q = y^{2,2}$, thus (i,j) = (2,2). This proves the claim (10e).

We deduce more facts about A by setting several other variables to zero. Set all variables in A to zero besides $y^{1,1}$, $y^{2,3}$, $y^{3,2}$ and call the resulting matrix C. From (2) it follows that we have

$$\det(C) = \pm y^{1,1} y^{2,3} y^{3,2}.$$
 (2c)

By (2c) the first row of C cannot be all zeros, so by (5) and (6) we have that $X^{2,3}$ or $X^{3,2}$ have a nonzero entry in the first row. If it is $X^{3,2}$ and not $X^{2,3}$, then we can apply the transposition from G_{perm_3} (preserving (1)-(10) because $X^{1,1}$, $X^{2,2}$, and $X^{3,3}$ are fixed) to ensure:

(11) $X^{2,3}$ has at least one nonzero entry in row 1.

Combining (11) and (4) and (5)(I) we see that

$$X^{2,3}$$
 is zero in the first column. (11b)

There are two cases:

Case 1: In row 1, $X^{2,3}$ is nonzero only in column n

We will show that this case cannot appear.

; From the assumption of case 1 we conclude with (4) that

$$X^{2,3}$$
 is zero everywhere but in the last column. (11)

We apply Lemma 6.4 with the monomial $y^{1,1}y^{2,3}y^{3,2}$ that appears in det(A), so

- one of the three variables goes to the first column in some row $k \neq 1$,
- one goes to the first row in some column $\ell \neq 1$,
- and one goes to position (ℓ, k) .

Since by (6) $y^{1,1}$ only appears in the first column, it must be the variable that goes to the first column. Again, by (6) we have k = 2. By (11') $y^{2,3}$ cannot go to the second column, in particular not to position (ℓ, k) , so $y^{2,3}$ goes to the first row. By (11) and (11'), $y^{2,3}$ goes to position (1, n). Therefore $y^{3,2}$ goes to position (n, 2). This is a contradiction to (10e). We conclude that case 1 cannot appear.

Case 2: In row 1, $X^{2,3}$ is nonzero in some column which is not n

Permutation conjugation on the indices $3, \ldots, n-1$ preserves (1)-(11). By (5)(I) and (6b) and the case assumption these permutation conjugations are sufficient to assume

(12)
$$X_{1,n-1}^{2,3} \neq 0.$$

Since elimination conjugations (subtracting multiples of column n-1 from columns $3, \ldots, n-2$ and then adding multiples of rows $3, \ldots, n-2$ to row n-1) preserve (1)-(12) we can assume that

(13) In row 1, the only positions of nonzero entries in $X^{2,3}$ are (1, n-1) and possibly additionally (1, n).

Using (4) we conclude

(13b) $X^{2,3}$ vanishes in columns $1, \ldots, n-2$.

Using elimination conjugation (subtract a multiple of column n-1 from column n and add a multiple of row n to row n-1), which preserves (1)-(13), we can assume that

(14)
$$X_{1,n}^{2,3} = 0.$$

Then (4), (12), (13b), and (14) imply

(14b) $X^{2,3}$ is nonzero only in column n-1.

Lemma 6.4 applied to the monomial $y^{1,1}y^{2,3}y^{3,2}$ gives

- one of the three variables goes to the first column in some row $k \neq 1$,
- one goes to the first row in some column $\ell \neq 1$,
- and one goes to position (ℓ, k) .

Since by (6) $y^{1,1}$ only appears in the first column, $y^{1,1}$ must be the variable that goes to the first column. Again, k = 2 by (6). By (13b) $y^{2,3}$ cannot go to the second column, so $y^{2,3}$ goes to the first row. By (14b) $y^{2,3}$ appears at position (1, n - 1). Therefore $y^{3,2}$ goes to position (n - 1, 2). Summarizing:

(14c) $X_{1,n-1}^{2,3} \neq 0$ and $X_{n-1,2}^{3,2} \neq 0$.

Using (14b) and (5)(II) we conclude

(14d)
$$A_{n-1,1} = 0$$

Lemma 6.4 applied to the monomial $y^{1,2}y^{2,1}y^{3,3}$ gives

- one of the three variables goes to the first column in some row $k \neq 1$,
- one goes to the first row in some column $\ell \neq 1$,
- and one goes to position (ℓ, k) .

Since the only position for $y^{3,3}$ is fixed, $y^{3,3}$ goes to the first row to position (1, n), so $\ell = n$. Using (10c) and (14d) we see $k \leq n-2$. Moreover (5)(I) says $k \neq 1$ and (10e) says $k \neq 2$. So in total we have $3 \leq k \leq n-2$. Using permutation conjugation we can assume k = 3, so that the only cases left to consider are: Case 2.1: $X_{3,1}^{1,2} \neq 0$ and $X_{n,3}^{2,1} \neq 0$

Using elimination conjugation we can get rid of any occurrences of $y^{1,2}$ at positions (k, 1) for $4 \le k \le n-2$. So with (6b) and (5)(II) it follows

(15)
$$A_{1,3} = 0$$

Lemma 6.4 applied to the monomial $y^{1,2}y^{2,3}y^{3,1}$ gives

- one of the three variables goes to the first column in some row $k \neq 1$,
- one goes to the first row in some column $\ell \neq 1$,
- and one goes to position (ℓ, k) .

By (14b), $y^{2,3}$ only appears in column n-1, so $y^{2,3}$ does not go to the first column. We make a small case distinction: First assume that $y^{2,3}$ does not go in the first row. Then $y^{2,3}$ goes to position (ℓ, k) with k = n-1. But k = n-1 is impossible because $A_{n-1,1} = 0$ by (14d).

On the other hand, if we assume that $y^{2,3}$ gos in the first row, then $\ell = n - 1$. By (4) and the case assumption 2.1, since $\ell = n - 1$, $y^{1,2}$ cannot go to (ℓ, k) , so it must go in the first column. Therefore $y^{3,1}$ goes to position (n - 1, k). Since $A_{n-1,1} = 0$ by (14d) and $A_{n,1} = 0$ by (10c) and $X_{n,2}^{2,2} \neq 0$ by (10d) the variables $y^{3,1}$ and $y^{2,2}$ cannot appear in column 1 because of (4). Thus using Lemma 6.4 for the monomial $y^{2,2}y^{1,3}y^{3,1}$ we see that $y^{1,3}$ must appear in the first column. But for the sake of contradiction we now use Lemma 6.4 for the monomial $y^{1,3}y^{3,2}y^{2,1}$ as follows: We have $A_{1,1} = A_{1,2} = A_{1,3} = 0$ by (5)(I) and (6b) and (15). The variable $y^{1,3}$ appears in column 1, the variable $y^{3,2}$ appears in column 2 by (14c), and the variable $y^{2,1}$ appears in column 3 (case assumption 2.1). Thus by (4) none of these three variables appears in row 1, which is a contradiction to Lemma 6.4. Therefore case 2.1 cannot appear.

Case 2.2: $X_{3,1}^{2,1} \neq 0$ and $X_{n,3}^{1,2} \neq 0$

Using elimination conjugation we get rid of any occurrences of $y^{2,1}$ at positions (k, 1) for $k \neq 3$:

(15) In the first column $y^{2,1}$ appears only at position (3, 1).

So with (6b) and (5)(II) it follows

(15b) $A_{1,3} = 0.$

Lemma 6.4 applied to the monomial $y^{1,2}y^{2,3}y^{3,1}$ gives

- one of the three variables goes to the first column in some row $k \neq 1$,
- one goes to the first row in some column $\ell \neq 1$,
- and one goes to position (ℓ, k) .

Since $X_{n,3}^{1,2} \neq 0$ and since (4) combined with (10c) and (15b) implies that $A_{n,1} = A_{1,3} = 0$, it follows that $y^{1,2}$ is the variable that appears at position (ℓ, k) . Since by (14b) $y^{2,3}$ only appears in column n-1, $y^{2,3}$ must be the variable that appears in the first row at position (1, n-1). Thus $\ell = n-1$. Moreover, the third variable $y^{3,1}$ must appear in the first column.

In the first column $y^{3,1}$ cannot appear in rows 1, n-1, or n by (5)(I), (10c), (14d). We want to use elimination conjugation on rows/columns 2,..., n-2 to ensure that $y^{3,1}$ appears only once in the first column. But not every operation preserves (1)-(15).

Case 2.2.1: In column 1 $y^{3,1}$ appears in a row $4 \le j \le n-2$

If $y^{3,1}$ appears in column 1 in a row $4 \le j \le n-2$, then elimination conjugation can be used to ensure that

(16) In column 1 $y^{3,1}$ appears only in row j.

Thus k = j. Thus $y^{1,2}$ occurs at position $(\ell, k) = (n - 1, j)$. With (4) and with case assumption 2.2 we see that

(16b) $X_{n,j}^{1,2} \neq 0.$

Since $y^{3,3}$ occurs only at position (1, n) and Λ is zero in the first row, $y^{3,1}y^{1,2}y^{3,3}$ occurs in det(A) iff $y^{3,1}y^{1,2}$ occurs in det $(A(\{1\}, \{n\}))$. Also Λ is zero in the first column and by (4) there can be no occurrence of $y^{1,2}$ in the first column, so an occurrence of $y^{3,1}y^{1,2}y^{3,3}$ in det(A) must involve $y^{3,1}$ in the first column, which only occurs at position (j, 1). So $y^{3,1}y^{1,2}y^{3,3}$ occurs in det(A) iff $y^{1,2}$ occurs in det $(A(\{1,j\}, \{1,n\}))$. But by the special form of Λ it follows that the degree 1 term of det $(A(\{1,j\}, \{1,n\}))$ is a nonzero scalar multiple of $X_{n,j}$. With (16b), it follows that $y^{3,1}y^{1,2}y^{3,3}$ appears in det(A). This is a contradiction to (2). Therefore we ruled out case 2.2.1.

Case 2.2.2: In column 1 $y^{3,1}$ only appears in rows 2 and/or 3

Clearly $2 \le k \le 3$.

If k = 2, then $X_{n-1,2}^{1,2} \neq 0$. By (4) and case assumption 2.2 it follows $X_{n,2}^{1,2} \neq 0$, in contradiction to (10e).

So from now on assume that k = 3. In particular $X_{3,1}^{3,1} \neq 0$. We adjust the argument from case 2.2.1 as follows.

Since $y^{3,3}$ occurs only at position (1, n) and Λ is zero in the first row, $y^{3,1}y^{1,2}y^{3,3}$ occurs in det(A) iff $y^{3,1}y^{1,2}$ occurs in det $(A(\{1\}, \{n\}))$. Also Λ is zero in the first column and by (4) there can be no occurrence of $y^{1,2}$ in the first column, so an occurrence of $y^{3,1}y^{1,2}y^{3,3}$ in det(A) must involve $y^{3,1}$ in the first column. Since k = 3 this occurs at position (3, 1), but by case assumption 2.2.2 it might also occur at position (2, 1). But even though $y^{3,1}$ can appear at position (2, 1), this $y^{3,1}$ cannot contribute to the coefficient of $y^{3,1}y^{1,2}y^{3,3}$ in det(A), because the special form of Δ together with (10e) ensures that det $(A(\{1,2\},\{1,n\}))$ has no term $y^{1,2}$. So $y^{3,1}y^{1,2}y^{3,3}$ occurs in det(A) iff $y^{1,2}$ occurs in det $(A(\{1,3\},\{1,n\}))$. But by the special form of Λ it follows that the degree 1 term of det $(A(\{1,3\},\{1,n\}))$ is a nonzero scalar multiple of $X_{n,3}$. Using the case assumption 2.2, it follows that $y^{3,1}y^{1,2}y^{3,3}$ appears in det(A). This is a contradiction to (2). Therefore we ruled out case 2.2.2.

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