

$$\begin{cases} x_1' = 7x_1 - 21 \\ x_2' = 7x_2 + 14 \end{cases}$$

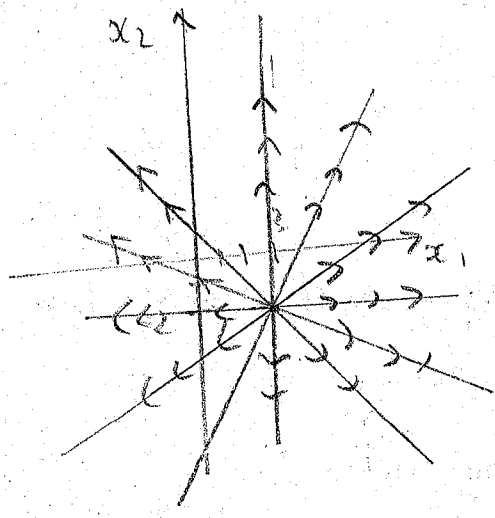
i) Critical points:

$$\begin{cases} 7x_1 - 21 = 0 \Rightarrow x_1 = 3 \\ 7x_2 + 14 = 0 \Rightarrow x_2 = -2 \end{cases} \Rightarrow$$

$(3, -2)$ is the critical point

Classification: $A = \begin{pmatrix} 7 & 0 \\ 0 & 7 \end{pmatrix} = 7I \Rightarrow$ the eigenvalues are 7 with the algebraic and geometric multiplicity equal to 2 \Rightarrow since it is positive \Rightarrow unstable proper node (or star point)

ii) Phase portrait



Problem 2 $\begin{cases} x_1' = 3x_1 + 4x_2 \\ x_2' = -4x_1 - 3x_2 + 7 \end{cases}$

i) Critical points:

$$\begin{cases} 3x_1 + 4x_2 = 0 & (E_1) \\ -4x_1 - 3x_2 + 7 = 0 & (E_2) \end{cases} \Rightarrow \begin{cases} 3x_1 + 4x_2 = 0 & (E_1) \\ 4x_1 + 3x_2 = 7 & (E_2) \end{cases} \Rightarrow$$

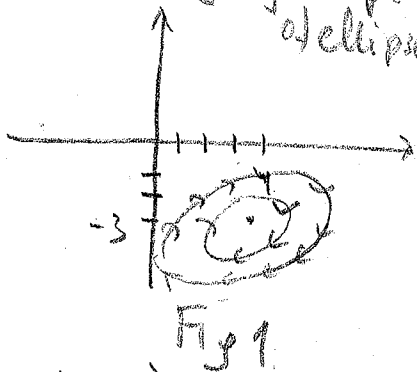
$$4(E_2) - 3(E_1) \Rightarrow (16 - 9)x_2 = 28 \Rightarrow x_2 = 4 \Rightarrow 12 + 4x_2 = 0 \Rightarrow x_2 = -3 \Rightarrow (4, -3) \text{ the critical point}$$

Classification $A = \begin{pmatrix} 3 & 4 \\ -4 & -3 \end{pmatrix}$, $\det A = -9 + 16 = 7$ char. equation $\lambda^2 + 7 = 0 \Rightarrow \lambda = \pm i\sqrt{7}$

ii) Sketch of the phase portrait (without analysis of the shape of ellipses) \Rightarrow center, stable

Since $a_{21} = -4 < 0$ the motion is clockwise (this is enough for the part)

Sketch for part ii) (without analyzing shape of ellipse) (page 2)



Sketch for part iii) (after analyzing the shape of ellipses)



iii) (bonus) More accurate sketch, taking into account the shape of the ellipses

For this first find an eigenvector of $A = \sqrt{7}i$

$$(A - \sqrt{7}i)v = \begin{pmatrix} 3 - \sqrt{7}i & 4 \\ -4 & -3 - \sqrt{7}i \end{pmatrix} \begin{pmatrix} v_1 \\ v_2 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix} \Rightarrow (3 - \sqrt{7}i)v_1 + 4v_2 = 0$$

$$\text{Take } v_1 = 4 \Rightarrow v_2 = -3 + \sqrt{7}i \Rightarrow v = \begin{pmatrix} 4 \\ -3 + \sqrt{7}i \end{pmatrix} = \underbrace{\begin{pmatrix} 4 \\ -3 \end{pmatrix}}_e + i \underbrace{\begin{pmatrix} 0 \\ \sqrt{7} \end{pmatrix}}_b$$

(By the way, the shortest rotation from b to e is clockwise, confirming our conclusion in item ii)

$$\text{The Gram matrix } \Gamma = \begin{pmatrix} e \cdot a & a \cdot b \\ e \cdot b & b \cdot b \end{pmatrix} = \begin{pmatrix} 4^2 + 3^2 & -3\sqrt{7} \\ -3\sqrt{7} & 7 \end{pmatrix} = \begin{pmatrix} 25 & -3\sqrt{7} \\ -3\sqrt{7} & 7 \end{pmatrix}$$

Find the eigenvalues and the eigenvectors of Γ : $\text{tr } \Gamma = 32$, $\det \Gamma = 175 - 9 \times 7 = 112$

The characteristic equation is $\lambda^2 - 32\lambda + 112 = 0 \Rightarrow D = 32^2 - 4 \cdot 112 = 1024 - 448 = 576 \Rightarrow \sqrt{D} = 24 \Rightarrow \lambda_1 = \frac{32 - 24}{2} = 4, \lambda_2 = \frac{32 + 24}{2} = 28 \Rightarrow \sqrt{\frac{\lambda_2}{\lambda_1}} = \sqrt{7} \approx 2.64$

(recall that by page 6 of notes of April 20 $\sqrt{\frac{\lambda_2}{\lambda_1}}$ represents the stretching scale of the ellipse along the eigenvector of λ_2 (of Γ) compare to the eigenline of λ_1 and the eigenline of λ_1 (then the eigenline of λ_2 is orthogonal to it))

$$-\lambda_1 \mathbf{I} v = \begin{pmatrix} 21 & -3\sqrt{7} \\ -3\sqrt{7} & 3 \end{pmatrix} \begin{pmatrix} v_1 \\ v_2 \end{pmatrix} = 0 \Rightarrow -\sqrt{7}v_1 + v_2 = 0 \Rightarrow E_{\lambda_1} = c \begin{pmatrix} 1 \\ \sqrt{7} \end{pmatrix}$$

The axes of symmetry are $\begin{pmatrix} 4 \\ -3 \end{pmatrix} + \sqrt{7} \begin{pmatrix} 0 \\ 1 \end{pmatrix} = \begin{pmatrix} 4 \\ -3 \end{pmatrix} = 4 \begin{pmatrix} 1 \\ 0 \end{pmatrix} + 2 \begin{pmatrix} 0 \\ -1 \end{pmatrix}$ for λ_1, λ_2

See sketch 2 above

Problem 3.

$$\begin{cases} x_1' = 6x_1 - 2x_2 - 10 \\ x_2' = 9x_1 - 5x_2 - 7 \end{cases}$$

i) Critical point: $\begin{cases} 6x_1 - 2x_2 - 10 = 0 \\ 9x_1 - 5x_2 - 7 = 0 \end{cases} \Leftrightarrow$

$$\begin{cases} 3x_1 - x_2 = 5 & (E_{y1}) \\ 9x_1 - 5x_2 = 7 & (E_{y2}) \end{cases} \quad (E_{y2}) - 3(E_{y1})$$

$$\frac{-5x_2 + 3x_2}{-2x_2} = 7 - 15 = -8 \Rightarrow x_2 = 4$$

$$\stackrel{E_{y1}}{\Rightarrow} 3x_1 - 4 = 5 \Rightarrow 3x_1 = 9 \Rightarrow x_1 = 3$$

$\Rightarrow (3, 4)$ is the critical point.

Classification

$$A = \begin{pmatrix} 6 & -2 \\ 9 & -5 \end{pmatrix}$$

$$\Rightarrow \text{tr} A = 1, \det A = 6 \cdot (-5) + 18 = -12$$

Characteristic equation: $\lambda^2 - \lambda - 12 = 0$

$$\Delta = 1 + 48 = 49$$

$$\lambda_1 = \frac{1-7}{2} = -3$$

$$\lambda_2 = \frac{1+7}{2} = 4$$

Rem. Actually already from the fact that $\det A < 0$ we know that the critical point is saddle (see Rem on page 15 of notes of April 25)

\rightarrow eigenvalues are real and of opposite signs

$\Rightarrow (3, 4)$ is a saddle point
unstable

ii) Sketch For more accurate sketch we need to find the eigenlines

of A: a) For $\lambda_1 = -3$

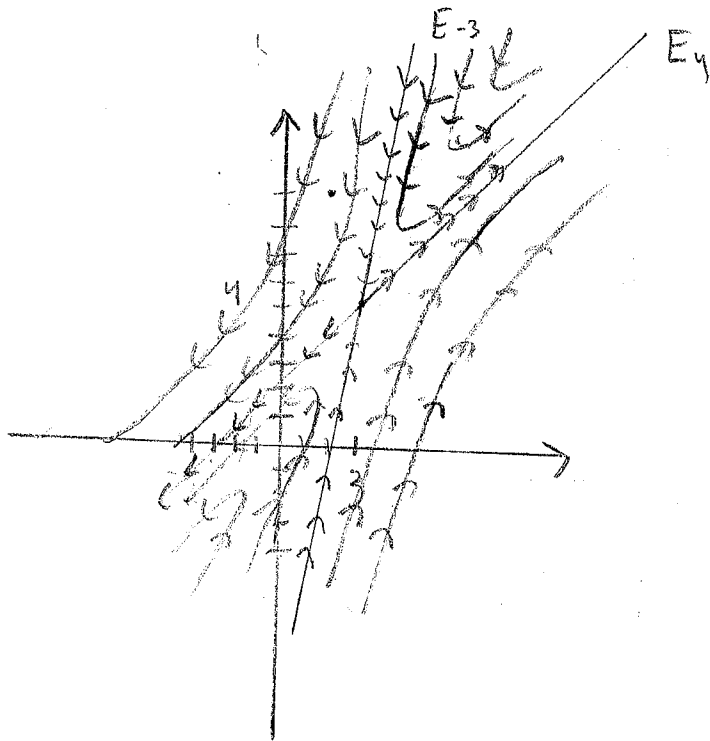
$$(A + 3I)v = \begin{pmatrix} 9 & -2 \\ 9 & -2 \end{pmatrix} v = 0 \Rightarrow 9v_1 - 2v_2 = 0$$

Take $v_1 = 2 \Rightarrow v_2 = 9 \Rightarrow$ the eigenline is generated by the vector $\begin{pmatrix} 2 \\ 9 \end{pmatrix}$

g) For $\lambda = -4$

$$(A - 4I)v = \begin{pmatrix} 2 & -2 \\ 9 & -9 \end{pmatrix} v = 0 \quad (\Leftrightarrow) \quad 2v_1 - 2v_2 = 0 \quad (\Leftrightarrow) \quad v_1 - v_2 = 0 \Rightarrow$$

If $v_2 = 1$, then $v_1 = 1 \Rightarrow$ The eigenline is generated by $\begin{pmatrix} 1 \\ 1 \end{pmatrix}$



Problem 4.

$$\begin{cases} x_1' = 2x_1 + 2x_2 - 6 \\ x_2' = -3x_1 + 7x_2 + 39 \end{cases}$$

i) Critical points: $\begin{cases} 2x_1 + 2x_2 - 6 = 0 \\ -3x_1 + 7x_2 + 39 = 0 \end{cases} \quad (\Leftrightarrow) \quad \begin{cases} x_1 + x_2 = 3 & (Eq 1) \\ 3x_1 - 7x_2 = 39 & (Eq 2) \end{cases}$

$(Eq 2) - 3(Eq 1) : -10x_2 = 30 \Rightarrow x_2 = -3 \xrightarrow{(Eq 1)} x_1 - 3 = 3 \Rightarrow x_1 = 6 \Rightarrow$

$(6, -3)$ is the critical point

Classification: $A = \begin{pmatrix} 2 & 2 \\ -3 & 7 \end{pmatrix}$, $\text{tr } A = 9$, $\det A = 14 + 6 = 20$

Characteristic equation: $\lambda^2 - 9\lambda + 20 = 0$

$$D = 81 - 80 = 1$$

$$\left. \begin{aligned} \lambda_1 &= \frac{9+1}{2} = 5 \\ \lambda_2 &= \frac{9-1}{2} = 4 \end{aligned} \right\} \begin{array}{l} \text{real positive} \\ \downarrow \end{array}$$

Node source unstable

ii) Sketch of the phase portrait

For more accurate sketch we need to find the eigenlines

a) The eigenline for $\lambda = 5$

$$(A - 5I)v = \begin{pmatrix} -3 & 2 \\ -3 & 2 \end{pmatrix} v = 0 \Rightarrow -3v_1 + 2v_2 = 0 \Rightarrow$$

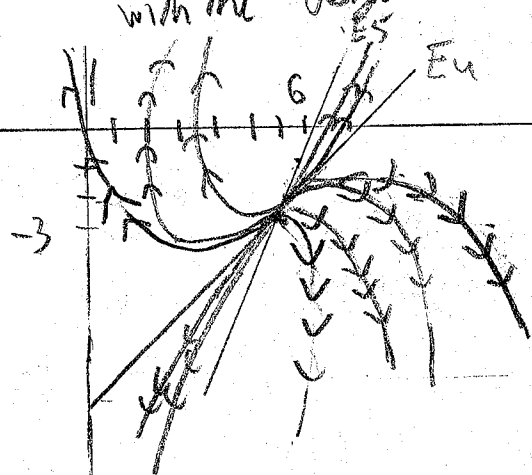
The eigenline E_5 is generated by $\begin{pmatrix} 2 \\ 3 \end{pmatrix}$

b) The eigenline for $\lambda = 4$

$$(A - 4I)v = \begin{pmatrix} -2 & 2 \\ -3 & 3 \end{pmatrix} v = 0 \Rightarrow -v_1 + v_2 = 0 \Rightarrow$$

The eigenline E_4 is generated by $\begin{pmatrix} 1 \\ 1 \end{pmatrix}$

Since $5 > 4$ then all trajectories pass out of the origin with the dominant line almost parallel to E_4



Problem 5

$$\begin{cases} x_1' = -11x_1 - 2x_2 + 13 \\ x_2' = 2x_1 - 7x_2 + 5 \end{cases}$$

i) Critical points

$$\begin{cases} -11x_1 - 2x_2 + 13 = 0 \\ 2x_1 - 7x_2 + 5 = 0 \end{cases} \quad (*)$$

$$\begin{cases} 11x_1 + 2x_2 = 13 & (Eq 1) \\ 2x_1 - 7x_2 = -5 & (Eq 2) \end{cases}$$

$$2(Eq 1) - 11(Eq 2): \quad \underbrace{(4 + 77)}_{81} x_1 = 26 + 55 = 81 \Rightarrow x_1 = 1 \quad (Eq 1) \quad 11 + 2x_2 = 13$$

$$\Rightarrow x_2 = 1 \Rightarrow \boxed{(1, 1) \text{ is the critical point}}$$

Classification: $A = \begin{pmatrix} -11 & -2 \\ 2 & -7 \end{pmatrix} \Rightarrow \text{tr } A = -18$
 $\det A = 77 + 4 = 81 \Rightarrow$

Characteristic equation is $\lambda^2 + 18\lambda + 81 = 0 \Leftrightarrow (\lambda + 9)^2 = 0$
 (or $D = 18^2 - 4 \cdot 81 = 324 - 324 = 0$)

$\Rightarrow \lambda_{1,2} = -9 \Rightarrow$ the eigenvalue $\lambda = -9$ of algebraic multiplicity 2, but of geometric multiplicity 1 (the latter because

$A \neq -9I$) \Rightarrow improper node, asymptotically stable

(i) Sketch of the phase portrait

a) Since $a_{21} = 2 > 0$ the motion for the part of the

solution which is far of the origin will be counterclockwise (for other way to determine this see * below)

b) Also for accuracy of the sketch, we need to find the eigenline of $\lambda = -9$

$(A + 9I)v = \begin{pmatrix} -2 & -2 \\ 2 & 2 \end{pmatrix} v = 0 \Rightarrow v_1 + v_2 = 0 \Rightarrow$ the eigenline is generated by $\begin{pmatrix} 1 \\ -1 \end{pmatrix}$

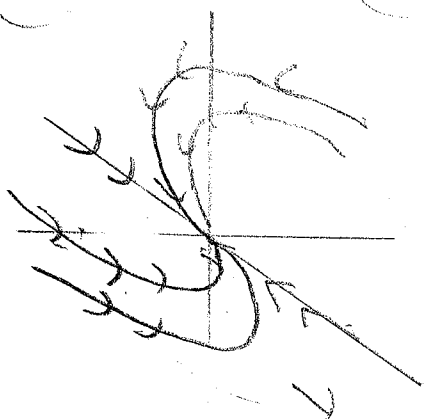


Fig 4

* Another way to determine the right shape of the trajectories is to find w s.t. $(A - \lambda I)w = \begin{pmatrix} 1 \\ -1 \end{pmatrix}$
 $-2w_1 - 2w_2 = 1 \Rightarrow w_2 = 0 \Rightarrow w_1 = -\frac{1}{2}$

$w = \begin{pmatrix} 0 \\ -\frac{1}{2} \end{pmatrix}$

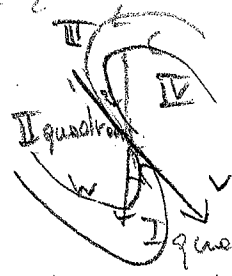


Fig 5

The trajectories must enter the origin from the 1st & 3rd quadrants as in the Fig 5 (that matches Fig 4)

Problem 6

$$\begin{cases} x_1' = -8x_1 + 10x_2 \\ x_2' = -5x_1 + 2x_2 \end{cases}$$

i) Critical points

$$\begin{cases} -8x_1 + 10x_2 = 0 \\ -5x_1 + 2x_2 = 0 \end{cases}$$

$$\det \begin{pmatrix} -8 & 10 \\ -5 & 2 \end{pmatrix} = -16 + 50 = 34 \neq 0$$

$$\Rightarrow x_1 = x_2 = 0$$

The only critical point is $(0, 0)$

Classification

$$A = \begin{pmatrix} -8 & 10 \\ -5 & 2 \end{pmatrix}$$

$$\text{tr } A = -8 + 2 = -6 \Rightarrow$$

$$\det A = 34$$

The characteristic equation is $\lambda^2 + 6\lambda + 34 = 0$

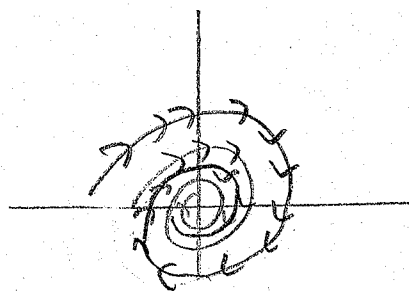
$$D = 36 - 4 \cdot 34 = 36 - 136 = -100$$

$$\lambda_{1,2} = \frac{-6 \pm 10i}{2} = -3 \pm 5i \rightarrow$$

complex, with negative real part \Rightarrow spiral sink,
asymptotically stable

ii) Sketch (without detailed shape)
 $a_{21} = -5 < 0 \Rightarrow$ the rotation is clockwise

Sketch (sufficient for item ii)

iii) (bonus) More accurate sketch, taking into account the shape of the spirals

For this, first find an eigenvector of $\lambda = \lambda = -3 + 5i$

$$(A + (3-5i)I)v = \begin{pmatrix} -5-5i & 10 \\ -5 & 5-5i \end{pmatrix} v = 0 \Rightarrow$$

$$-(1+i)v_1 + 2v_2 = 0 \Rightarrow \text{if } v_1 = 2 \text{ then } v_2 = 1+i \Rightarrow$$

$$v = \begin{pmatrix} 2 \\ 1+i \end{pmatrix} = \underbrace{\begin{pmatrix} 2 \\ 1 \end{pmatrix}}_a + \underbrace{\begin{pmatrix} 0 \\ 1 \end{pmatrix}}_b i$$

(By the way this gives another justification that the direction of rotation is clockwise, because the shortest direction of rotation from b to a is clockwise)

Consider the Gram matrix

$$\Gamma = \begin{pmatrix} a \cdot a & a \cdot b \\ a \cdot b & b \cdot b \end{pmatrix} = \begin{pmatrix} 2 \cdot 2 + 1 \cdot 1 & 1 \cdot 1 \\ 1 \cdot 1 & 1 \cdot 1 \end{pmatrix} = \begin{pmatrix} 5 & 1 \\ 1 & 1 \end{pmatrix}$$

Find the eigenvalues of Γ : $\text{tr } \Gamma = 6$, $\det \Gamma = 5 - 1 = 4$

Char. equation of Γ is

$$\lambda^2 - 6\lambda + 4 = 0$$

$$D = 36 - 4 \cdot 4 = 20, \sqrt{D} = 2\sqrt{5}$$

$$\lambda_1 = \frac{6 - 2\sqrt{5}}{2} = 3 - \sqrt{5}$$

$$\lambda_2 = 3 + \sqrt{5}$$

$$\Rightarrow \frac{\lambda_2}{\lambda_1} = \frac{3 + \sqrt{5}}{3 - \sqrt{5}} = \frac{(3 + \sqrt{5})^2}{(3 - \sqrt{5})(3 + \sqrt{5})} = \frac{9 + 5 + 6\sqrt{5}}{9 - 5} = \frac{14 + 6\sqrt{5}}{4} = \frac{7 + 3\sqrt{5}}{2}$$

$\sqrt{\frac{\lambda_2}{\lambda_1}} \approx 2.62 \rightarrow$ the coefficient of the stretch

of the spirals along E_{λ_2} compared to E_{λ_1}

Find an eigenline of E_{λ_1} for Γ (then $E_{\lambda_2} \perp E_{\lambda_1}$)

$$(\Gamma - \lambda_1 I)v = \begin{pmatrix} 5 - 3 + \sqrt{5} & 1 \\ 1 & 1 - 3 + \sqrt{5} \end{pmatrix} v = \begin{pmatrix} 2 + \sqrt{5} & 1 \\ 1 & -2 + \sqrt{5} \end{pmatrix} v$$

$$\Rightarrow (2 + \sqrt{5})v_1 + v_2 = 0 \Rightarrow E_{\lambda_1} \text{ is generated by } \begin{pmatrix} -1 \\ 2 + \sqrt{5} \end{pmatrix} \Rightarrow$$

$$E_{\lambda_2} \text{ is generated by } \begin{pmatrix} 2 + \sqrt{5} \\ 1 \end{pmatrix}$$

Project

Then the axes of symmetries of ellipses (before multiplication by exponentially decaying factor)

$$\vec{a} = -a + (2+\sqrt{5})b = \begin{pmatrix} -2 \\ -1+2+\sqrt{5} \end{pmatrix} = \begin{pmatrix} -2 \\ 1+\sqrt{5} \end{pmatrix}$$

$$\text{slope } \vec{a} = -\frac{1+\sqrt{5}}{2} \approx -1.62$$

$$\vec{b} = (2+\sqrt{5})a + b = \begin{pmatrix} 4+2\sqrt{5} \\ 3+\sqrt{5} \end{pmatrix} \text{ which is parallel}$$

$$\text{to } \begin{pmatrix} 1+\sqrt{5} \\ 2 \end{pmatrix} \text{ (and perpendicular to } \begin{pmatrix} -2 \\ 1+\sqrt{5} \end{pmatrix})$$
$$\text{slope } \vec{b} = \frac{2}{1+\sqrt{5}} \approx 0.62$$

Sketch

