

due May 3 2016 at the beginning of class (I will give an extra class at this day)

Solve any 5 out of 6 first problems below, you also can get up to 140 points for solving all these 6 problems and the bonus problem 7

1. A volume form  $\Omega$  on an  $n$ -dimensional manifold  $M$  is an everywhere nonvanishing smooth differential  $n$  form on  $M$ . Given a volume form  $\Omega$  on  $M$ , one can define the divergence of a vector field  $X$  (w.r.t. the volume form) as the unique scalar-valued function, denoted by  $\operatorname{div} X$ , satisfying

$$L_X \Omega = (\operatorname{div} X) \Omega.$$

Prove that if  $M = \mathbb{R}^3$  with coordinates  $(x, y, z)$  and  $\Omega = dx \wedge dy \wedge dz$ , then this coincides with the definition of the divergence of a vector field given in the Multivariable Calculus.

2. (a) Solve Problem 11 page 78;  
 (b) Let  $\omega$  be a smooth 1-form on a smooth manifold  $M$ . A smooth positive function  $\mu$  on some subset  $U \subset M$  is called an integrating factor if  $\mu\omega$  is exact on  $U$ , i.e. there exists a smooth function  $f$  on  $U$  such that  $df = \mu\omega$ . If  $\omega$  is nowhere-vanishing, show that  $\omega$  admits an integrating factor in a neighborhood of each point if and only if  $d\omega \wedge \omega = 0$ .
3. (a) Show that the Example 3.3 (i) on page 83 of Warner is a Lie group.  
 (b) Show that the Example 3.5 (e) on page 84 of Warner is a Lie algebra and it is isomorphic to the Lie algebra of  $3 \times 3$  skew-symmetric matrices.  
 (c) Problem 17, page 135 of Warner.
4. Let  $G$  be Lie group  
 (a) Let  $F : G \times G \rightarrow G$  denote the multiplication map. Identify the space  $T_{(e,e)}(G \times G)$  with  $T_e G \oplus T_e G$  by
 
$$v \in T_{(e,e)}(G \times G) \mapsto (d\pi_1(v), d\pi_2(v))$$
 where  $\pi_1$  and  $\pi_2$  are projections of  $G \times G$  to the first and the second components, respectively. Show that  $dF_e : T_e G \oplus T_e G \rightarrow T_e G$  is given by  $dF(X, Y) = X + Y$ .  
 (b) Let  $J : G \rightarrow G$  denote the inversion map. Show that  $dJ_e : T_e G \rightarrow T_e G$  is given  $dJ_e(X) = -X$ .
5. Problem 15 page 159 of Warner.
6. Problem 16 (a)-(c) page 159 of Warner.
7. (**bonus 20 points**) Prove that if  $G$  is a group and a differentiable manifold such that the multiplication map  $G \times G \rightarrow G$  defined by  $(\sigma, \tau) \mapsto \sigma\tau$  is smooth, then the map  $\tau \mapsto \tau^{-1}$  is smooth (this shows that we can equivalently define a Lie group as a group and a differentiable manifold with a smooth multiplication).