

Matrices and Systems of Equations

$$\begin{array}{l}
 \text{Step 1} \quad \left(\begin{array}{cccc|c} x & x & x & x & x \\ x & x & x & x & x \\ x & x & x & x & x \\ x & x & x & x & x \end{array} \right) \rightarrow \left(\begin{array}{cccc|c} x & x & x & x & x \\ 0 & x & x & x & x \\ 0 & x & x & x & x \\ 0 & x & x & x & x \end{array} \right) \\
 \\
 \text{Step 2} \quad \left(\begin{array}{cccc|c} x & x & x & x & x \\ 0 & x & x & x & x \\ 0 & x & x & x & x \\ 0 & x & x & x & x \end{array} \right) \rightarrow \left(\begin{array}{cccc|c} x & x & x & x & x \\ 0 & x & x & x & x \\ 0 & 0 & x & x & x \\ 0 & 0 & x & x & x \end{array} \right) \\
 \\
 \text{Step 3} \quad \left(\begin{array}{cccc|c} x & x & x & x & x \\ 0 & x & x & x & x \\ 0 & 0 & x & x & x \\ 0 & 0 & x & x & x \end{array} \right) \rightarrow \left(\begin{array}{cccc|c} x & x & x & x & x \\ 0 & x & x & x & x \\ 0 & 0 & x & x & x \\ 0 & 0 & 0 & x & x \end{array} \right)
 \end{array}$$

Figure 1.2.

SECTION I EXERCISES

1. Use back substitution to solve each of the following systems of equations:

(a) $x_1 - 3x_2 = 2$ (b) $x_1 + x_2 + x_3 = 8$
 $2x_2 = 6$ $2x_2 + x_3 = 5$
 $3x_3 = 9$

(c) $x_1 + 2x_2 + 2x_3 + x_4 = 5$
 $3x_2 + x_3 - 2x_4 = 1$
 $-x_3 + 2x_4 = -1$
 $4x_4 = 4$

(d) $x_1 + x_2 + x_3 + x_4 + x_5 = 5$
 $2x_2 + x_3 - 2x_4 + x_5 = 1$
 $4x_3 + x_4 - 2x_5 = 1$
 $x_4 - 3x_5 = 0$
 $2x_5 = 2$

2. Write out the coefficient matrix for each of the systems in Exercise 1.

3. In each of the following systems, interpret each equation as a line in the plane. For each system, graph the lines and determine geometrically the number of solutions.

(a) $x_1 + x_2 = 4$ (b) $x_1 + 2x_2 = 4$
 $x_1 - x_2 = 2$ $-2x_1 - 4x_2 = 4$

(c) $2x_1 - x_2 = 3$ (d) $x_1 + x_2 = 1$
 $-4x_1 + 2x_2 = -6$ $x_1 - x_2 = 1$
 $-x_1 + 3x_2 = 3$

4. Write an augmented matrix for each of the systems in Exercise 3.

5. Write out the system of equations that corresponds to each of the following augmented matrices:

(a) $\left[\begin{array}{cc|c} 3 & 2 & 8 \\ 1 & 5 & 7 \end{array} \right]$ (b) $\left[\begin{array}{ccc|c} 5 & -2 & 1 & 3 \\ 2 & 3 & -4 & 0 \end{array} \right]$

(c) $\left[\begin{array}{ccc|c} 2 & 1 & 4 & -1 \\ 4 & -2 & 3 & 4 \\ 5 & 2 & 6 & -1 \end{array} \right]$

(d) $\left[\begin{array}{cccc|c} 4 & -3 & 1 & 2 & 4 \\ 3 & 1 & -5 & 6 & 5 \\ 1 & 1 & 2 & 4 & 8 \\ 5 & 1 & 3 & -2 & 7 \end{array} \right]$

6. Solve each of the following systems:

(a) $x_1 - 2x_2 = 5$ (b) $2x_1 + x_2 = 8$
 $3x_1 + x_2 = 1$ $4x_1 - 3x_2 = 6$

(c) $4x_1 + 3x_2 = 4$ (d) $x_1 + 2x_2 - x_3 = 1$
 $\frac{2}{3}x_1 + 4x_2 = 3$ $2x_1 - x_2 + x_3 = 3$
 $-x_1 + 2x_2 + 3x_3 = 7$

(e) $2x_1 + x_2 + 3x_3 = 1$
 $4x_1 + 3x_2 + 5x_3 = 1$
 $6x_1 + 5x_2 + 5x_3 = -3$

(f) $3x_1 + 2x_2 + x_3 = 0$
 $-2x_1 + x_2 - x_3 = 2$
 $2x_1 - x_2 + 2x_3 = -1$

(g) $\frac{1}{3}x_1 + \frac{2}{3}x_2 + 2x_3 = -1$
 $x_1 + 2x_2 + \frac{3}{2}x_3 = \frac{3}{2}$
 $\frac{1}{2}x_1 + 2x_2 + \frac{12}{5}x_3 = \frac{1}{10}$

(h) $x_2 + x_3 + x_4 = 0$
 $3x_1 + 3x_3 - 4x_4 = 7$
 $x_1 + x_2 + x_3 + 2x_4 = 6$
 $2x_1 + 3x_2 + x_3 + 3x_4 = 6$

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7. The two systems

$$\begin{array}{l} 2x_1 + x_2 = 3 \\ 4x_1 + 3x_2 = 5 \end{array} \quad \text{and} \quad \begin{array}{l} 2x_1 + x_2 = -1 \\ 4x_1 + 3x_2 = 1 \end{array}$$

have the same coefficient matrix but different right-hand sides. Solve both systems simultaneously by eliminating the first entry in the second row of the augmented matrix

$$\left[\begin{array}{cc|cc} 2 & 1 & 3 & -1 \\ 4 & 3 & 5 & 1 \end{array} \right]$$

and then performing back substitutions for each of the columns corresponding to the right-hand sides.

8. Solve the two systems

$$\begin{array}{l} x_1 + 2x_2 - 2x_3 = 1 \\ 2x_1 + 5x_2 + x_3 = 9 \\ x_1 + 3x_2 + 4x_3 = 9 \end{array} \quad \begin{array}{l} x_1 + 2x_2 - 2x_3 = 9 \\ 2x_1 + 5x_2 + x_3 = 9 \\ x_1 + 3x_2 + 4x_3 = -2 \end{array}$$

by doing elimination on a 3×5 augmented matrix and then performing two back substitutions.

9. Given a system of the form

$$\begin{array}{l} -m_1x_1 + x_2 = b_1 \\ -m_2x_1 + x_2 = b_2 \end{array}$$

where $m_1, m_2, b_1,$ and b_2 are constants,

- (a) Show that the system will have a unique solution if $m_1 \neq m_2$.
- (b) Show that if $m_1 = m_2$, then the system will be consistent only if $b_1 = b_2$.
- (c) Give a geometric interpretation of parts (a) and (b).

10. Consider a system of the form

$$\begin{array}{l} a_{11}x_1 + a_{12}x_2 = 0 \\ a_{21}x_1 + a_{22}x_2 = 0 \end{array}$$

where $a_{11}, a_{12}, a_{21},$ and a_{22} are constants. Explain why a system of this form must be consistent.

11. Give a geometrical interpretation of a linear equation in three unknowns. Give a geometrical description of the possible solution sets for a 3×3 linear system.

2 Row Echelon Form

In Section 1 we learned a method for reducing an $n \times n$ linear system to strict triangular form. However, this method will fail if, at any stage of the reduction process, all the possible choices for a pivot element in a given column are 0.

EXAMPLE I Consider the system represented by the augmented matrix

$$\left[\begin{array}{ccccc|c} 1 & 1 & 1 & 1 & 1 & 1 \\ -1 & -1 & 0 & 0 & 1 & -1 \\ -2 & -2 & 0 & 0 & 3 & 1 \\ 0 & 0 & 1 & 1 & 3 & -1 \\ 1 & 1 & 2 & 2 & 4 & 1 \end{array} \right] \quad \leftarrow \text{pivotal row}$$

If row operation III is used to eliminate the nonzero entries in the last four rows of the first column, the resulting matrix will be

$$\left[\begin{array}{ccccc|c} 1 & 1 & 1 & 1 & 1 & 1 \\ 0 & 0 & 1 & 1 & 2 & 0 \\ 0 & 0 & 2 & 2 & 5 & 3 \\ 0 & 0 & 1 & 1 & 3 & -1 \\ 0 & 0 & 1 & 1 & 3 & 0 \end{array} \right] \quad \leftarrow \text{pivotal row}$$

At this stage, the reduction to strict triangular form breaks down. All four possible choices for the pivot element in the second column are 0. How do we proceed from