Worksheet 6

1. Consider the curve:

$$\mathbf{r}(t) = \left\langle t^2, \sin t, t \right\rangle; \ 3 \le t \le 9$$

Give a new parametrization $\mathbf{r}_1(s)$ of this curve in terms of the parameter s, given by $t = e^s$.

2. Find the arc length parametrization for the line $\mathbf{r}(t) = \langle 2t, 1-2t, t \rangle$, taking (0, 1, 0) as your basepoint.

3. Recall the definition of *curvature* of a curve $\mathbf{r}(t)$:

$$\kappa(t) = \left| \frac{d\mathbf{T}}{ds} \right| = \frac{1}{|\mathbf{v}(t)|} \left| \frac{d\mathbf{T}}{dt} \right|,$$

where $\mathbf{v}(t)$ is the velocity and $\mathbf{T}(t)$ is the unit tangent vector.

a). Show that curvature can also be expressed as:

$$\kappa(t) = \frac{|\mathbf{v}(t) \times \mathbf{a}(t)|}{|\mathbf{v}(t)|^3},$$

where $\mathbf{a}(t)$ is the acceleration. As highlighted in the next example, this latter formula is often easier to use than the original definition. Follow the steps below to prove this new formula:

• Show that:

$$\mathbf{v}(t) = rac{ds}{dt}\mathbf{T}(t) ext{ and } \mathbf{a}(t) = rac{d^2s}{dt^2}\mathbf{T}(t) + rac{ds}{dt}rac{d\mathbf{T}}{dt}.$$

• Use the expressions above to show that

$$\mathbf{v}(t) \times \mathbf{a}(t) = |\mathbf{v}(t)|^2 \left(\mathbf{T}(t) \times \frac{d\mathbf{T}}{dt} \right).$$

• Take the length of both sides above to show that

$$\mathbf{v}(t) \times \mathbf{a}(t)| = |\mathbf{v}(t)|^2 \left| \frac{d\mathbf{T}}{dt} \right|.$$

- Conclude the new formula for curvature.
- b). Compute the curvature of $\mathbf{r}(t) = \langle t, t^2, t^3 \rangle$.

4. At what point on the curve $\mathbf{r}(t) = \langle t^3, 3t, t^4 \rangle$ is the normal plane parallel to the plane 6x + 6y - 8z = 1? Recall that the normal plane is the one determined by **B** and **N**.

5. Suppose a Ferris wheel is a circle of radius R = 30m. At time $t = t_0$, a person is seated in the car at the lowest point of the wheel (see figure), which is rotating counterclockwise with a speed of 30m/min and is slowing down at a rate of $15m/min^2$ at this time. Find the acceleration vector $\mathbf{a}(t_0)$. How would your answer change if the wheel was rotating *clockwise*?

