

Some Linear Algebra:

2x2 Determinants: $\begin{vmatrix} a & b \\ c & d \end{vmatrix} = ad - bc$

Cramer's Rule: Say we have a system of algebraic equations:

$$\begin{cases} a_{11}x_1 + a_{12}x_2 = b_1 \\ a_{21}x_1 + a_{22}x_2 = b_2 \end{cases}$$

$$A := \begin{pmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{pmatrix}$$

$$A_1 := \begin{pmatrix} \boxed{b_1} & a_{12} \\ b_2 & a_{22} \end{pmatrix}; \quad A_2 := \begin{pmatrix} a_{11} & \boxed{b_1} \\ a_{21} & \boxed{b_2} \end{pmatrix}$$

$$\boxed{\begin{aligned} x_1 &= \frac{\det(A_1)}{\det(A)} \\ x_2 &= \frac{\det(A_2)}{\det(A)} \end{aligned}}$$

$$\begin{cases} x_1 + 2x_2 = 3 \\ 2x_1 - x_2 = 1 \end{cases}$$

$$\det(A) = \begin{vmatrix} 1 & 2 \\ 2 & -1 \end{vmatrix} = -5$$

$$\det(A_1) = \begin{vmatrix} 3 & 2 \\ 1 & -1 \end{vmatrix} = -5$$

$$\det(A_2) = \begin{vmatrix} 1 & 3 \\ 2 & 1 \end{vmatrix} = -5$$

$$x_1 = x_2 = \textcircled{1}$$

Generally:

$$\begin{cases} a_{11}x_1 + a_{12}x_2 + \dots + a_{1n}x_n = b_1 \\ a_{21}x_1 + a_{22}x_2 + \dots + a_{2n}x_n = b_2 \\ \vdots \\ a_{n1}x_1 + a_{n2}x_2 + \dots + a_{nn}x_n = b_n \end{cases}$$

$$\det(A) := \begin{vmatrix} a_{11} & a_{12} & \dots & a_{1n} \\ a_{21} & a_{22} & \dots & a_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ a_{n1} & a_{n2} & \dots & a_{nn} \end{vmatrix}$$

↓
determinant of matrix of coefficients

For every
 $1 \leq k \leq n$:

$$\det(A_k) := \begin{vmatrix} a_{11} & \dots & \boxed{b_1} & \dots & a_{1n} \\ a_{21} & \dots & \boxed{b_2} & \dots & a_{2n} \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ a_{n1} & \dots & \boxed{b_n} & \dots & a_{nn} \end{vmatrix}$$

↓
replace k^{th} column of A by column

$$\begin{bmatrix} b_1 \\ \vdots \\ b_n \end{bmatrix}$$

Cramer's Rule: If $\det(A) \neq 0$, unique solution:

$$\begin{cases} x_1 = \frac{\det(A_1)}{\det(A)} \\ \vdots \\ x_k = \frac{\det(A_k)}{\det(A)} \\ \vdots \\ x_n = \frac{\det(A_n)}{\det(A)} \end{cases}$$

Homogeneous systems



always possess the trivial solution $x_1 = x_2 = \dots = x_n = 0$.

$$\begin{cases} a_{11}x_1 + \dots + a_{1n}x_n = 0 \\ a_{21}x_1 + \dots + a_{2n}x_n = 0 \\ \vdots \\ a_{n1}x_1 + \dots + a_{nn}x_n = 0 \end{cases}$$

→ If $\det(A) \neq 0$, by Cramer's rule, the trivial solution is the only solution.

→ If $\det(A) = 0$,

If $\det(A) = 0$
 homogeneous systems : ∞ -many solutions
 non-homogeneous systems : can have ∞ -many, or no solutions.

3x3 determinants : (Reminder)

$$\begin{vmatrix} 2 & 4 & 7 \\ 1 & 2 & 3 \\ 1 & 5 & 3 \end{vmatrix}$$

Expand on 1st row:

$$\begin{vmatrix} \oplus & \ominus & \oplus \\ 2 & 4 & 7 \\ 1 & 2 & 3 \\ 1 & 5 & 3 \end{vmatrix} = +2 \cdot \begin{vmatrix} 2 & 3 \\ 5 & 3 \end{vmatrix} - 4 \cdot \begin{vmatrix} 1 & 3 \\ 1 & 3 \end{vmatrix} + 7 \cdot \begin{vmatrix} 1 & 2 \\ 1 & 5 \end{vmatrix}$$
$$= 2 \cdot (-9) - 4 \cdot 0 + 7 \cdot 3 = \boxed{3}$$

or, you can expand on any row & column

Expand on 2nd column:

$$\begin{vmatrix} 2 & \ominus & 4 & 7 \\ 1 & \oplus & 2 & 3 \\ 1 & \ominus & 5 & 3 \end{vmatrix} = -4 \begin{vmatrix} 1 & 3 \\ 1 & 3 \end{vmatrix} + 2 \begin{vmatrix} 2 & 7 \\ 1 & 3 \end{vmatrix} - 5 \begin{vmatrix} 2 & 7 \\ 1 & 3 \end{vmatrix}$$
$$= -4 \cdot 0 + 2 \cdot (-1) - 5 \cdot (-1) = \boxed{3}$$

* Useful when you have 0's:

for example, for

$$\begin{vmatrix} 1 & 2 & 0 \\ 3 & 1 & 0 \\ -1 & 4 & 2 \end{vmatrix} \begin{matrix} \oplus \\ \ominus \\ \oplus \end{matrix}$$

it's fastest to expand on the 3rd column :

$$+2 \cdot \begin{vmatrix} 1 & 2 \\ 3 & 1 \end{vmatrix} = \boxed{-10}$$

Linearly Dependent Functions (general def.)

A set of functions $f_1(x), f_2(x), \dots, f_n(x)$ is said to be linearly dependent on an interval I if there exist constants c_1, c_2, \dots, c_n NOT ALL ZERO such that:

$$c_1 f_1(x) + \dots + c_n f_n(x) = 0 \quad \text{for all } x \in I.$$

Otherwise, they are called linearly independent.

→ i.e.: f_1, \dots, f_n are linearly independent on an interval I if the only constants c_1, \dots, c_n for which $c_1 f_1(x) + \dots + c_n f_n(x) = 0$, for all $x \in I$ are $c_1 = c_2 = \dots = c_n = 0$.

→ Linear dependence means at least one function is a linear combination of the others.

Ex.:
$$\left. \begin{array}{l} f_1(x) = \sqrt{x} + 5 \\ f_2(x) = \sqrt{x} + 5x \\ f_3(x) = x - 1 \\ f_4(x) = x^2 \end{array} \right\} \begin{array}{l} \text{linearly dependent on } (0, \infty) \text{ b/c} \\ f_2 \text{ can be written as a linear combination} \\ \text{of } f_1, f_3, f_4: \end{array}$$

$$f_2(x) = 1 \cdot f_1(x) + 5 \cdot f_3(x) + 0 \cdot f_4(x) \quad \text{holds for all } x \in (0, \infty).$$

THE WRONSKIAN: If n functions f_1, f_2, \dots, f_n have at least $(n-1)$ derivatives, their Wronskian is the $n \times n$ determinant:

$$\begin{vmatrix} f_1 & f_2 & \dots & f_n \\ f_1' & f_2' & \dots & f_n' \\ \vdots & \vdots & \dots & \vdots \\ f_1^{(n-1)} & f_2^{(n-1)} & \dots & f_n^{(n-1)} \end{vmatrix} =: W(f_1, \dots, f_n)(x)$$

THEOREM: If the Wronskian $W(f_1, \dots, f_n)$ of n functions f_1, \dots, f_n is not zero for at least one point in an interval I , then the set of functions $\{f_1, f_2, \dots, f_n\}$ is linearly independent on the interval I .

Proof for case $(n=2)$: By contradiction.

Assume that $W(f_1(x), f_2(x)) \neq 0$ for a fixed point $x_0 \in I$:

$$W(f_1(x_0), f_2(x_0)) \neq 0$$

and that f_1, f_2 are linearly dependent on I .

\Rightarrow there exist constants c_1, c_2 not both zero such that

$$c_1 f_1(x) + c_2 f_2(x) = 0, \text{ for all } x \in I$$

$$\Rightarrow c_1 f_1'(x) + c_2 f_2'(x) = 0 \text{ also, for all } x \in I$$

\Rightarrow system of linear equations: (w/ unknowns c_1, c_2)

$$\begin{cases} c_1 f_1(x_0) + c_2 f_2(x_0) = 0 \\ c_1 f_1'(x_0) + c_2 f_2'(x_0) = 0 \end{cases}$$

has a nontrivial solution $\Rightarrow \begin{vmatrix} f_1(x_0) & f_2(x_0) \\ f_1'(x_0) & f_2'(x_0) \end{vmatrix} = 0 \Rightarrow$ Contradiction!

Examples:

① $f_1(x) = e^{2x}$; $f_2(x) = e^{-x}$

$$W(f_1, f_2) = \begin{vmatrix} e^{2x} & e^{-x} \\ 2e^{2x} & -e^{-x} \end{vmatrix} = -e^x - 2e^x = -3e^x \neq 0 \text{ for all real } x$$

$\Rightarrow \{f_1, f_2\}$ lin. indep. on \mathbb{R} .

② $f_1(x) = \sin^2(x)$, $f_2(x) = \cos^2(x)$

$$W(f_1, f_2) = \begin{vmatrix} \sin^2(x) & \cos^2(x) \\ 2\sin(x)\cos(x) & -2\sin(x)\cos(x) \end{vmatrix} = \begin{vmatrix} \sin^2(x) & \cos^2(x) \\ \sin(2x) & -\sin(2x) \end{vmatrix}$$

$$= -\sin(2x) \cdot \sin^2(x) - \sin(2x) \cdot \cos^2(x)$$

$$= -\sin(2x) \underbrace{(\sin^2(x) + \cos^2(x))}_1$$

$$= -\sin(2x)$$

$\hookrightarrow \sin(2x)$ is non-zero at at least one point of \mathbb{R} .
(∞ -many actually)

\Rightarrow linearly independent on \mathbb{R} .

③ $f_1(x) = \sin^2(x)$; $f_2(x) = \cos^2(x)$; $f_3(x) = 2$

$$W(f_1, f_2, f_3) = \begin{vmatrix} \sin^2(x) & \cos^2(x) & 2 \\ \sin(2x) & -\sin(2x) & 0 \\ 2\cos(2x) & -2\cos(2x) & 0 \end{vmatrix}$$

$$= 2 \begin{vmatrix} \sin(2x) & -\sin(2x) \\ 2\cos(2x) & -2\cos(2x) \end{vmatrix} = 2 \left(-2\sin(2x)\cos(2x) + 2\sin(2x)\cos(2x) \right) = 0$$

\Rightarrow Linearly dependent on \mathbb{R} ($W=0$ for all real x)