

Chapter 11. Three dimensional analytic geometry and vectors.  
 Section 11.6 Vector functions and space curves.

Let  $\vec{r}$  be a **vector function** whose range is a set of three-dimensional vectors.

$$\vec{r}(t) = \langle f(t), g(t), h(t) \rangle = f(t)\vec{i} + g(t)\vec{j} + h(t)\vec{k}$$

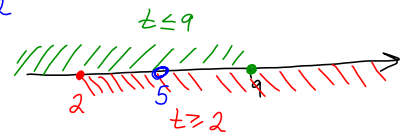
Functions  $f$ ,  $g$ , and  $h$  are real-valued functions called the **component functions** of  $\vec{r}$ .

The domain of  $\vec{r}$  consists of all values of  $t$  for which the expression for  $\vec{r}(t)$  is defined.

**Example 1.** Find the domain of the vector function  $\vec{r}(t) = \left\langle \sqrt{9-t}, \sqrt{t-2}, \frac{e^t}{t-5} \right\rangle$ .

$$\begin{aligned} f(t) &= \sqrt{9-t} & 9-t \geq 0 & \quad t \leq 9 \\ g(t) &= \sqrt{t-2} & t-2 \geq 0 & \quad t \geq 2 \\ h(t) &= \frac{e^t}{t-5} & t \neq 5 & \end{aligned}$$

Domain:  $[2, 5) \cup (5, 9]$



**Definition.** If  $\vec{r}(t) = \langle f(t), g(t), h(t) \rangle$ , then

$$\lim_{t \rightarrow a} \vec{r}(t) = \left\langle \lim_{t \rightarrow a} f(t), \lim_{t \rightarrow a} g(t), \lim_{t \rightarrow a} h(t) \right\rangle$$

provided the limits of the component function exist.

**Example 2.** Find the limit

$$\begin{aligned} & \lim_{t \rightarrow 0} \left\langle \frac{1 - \cos t}{t}, t^3, e^{-1/t^2} \right\rangle \\ &= \left\langle \lim_{t \rightarrow 0} \frac{1 - \cos t}{t}, \lim_{t \rightarrow 0} t^3, \lim_{t \rightarrow 0} e^{-1/t^2} \right\rangle \\ &= \left\langle \lim_{t \rightarrow 0} \frac{\sin t}{1}, 0, 0 \right\rangle \\ &= \boxed{\langle 0, 0, 0 \rangle} \end{aligned}$$

**Definition.** A vector function  $\vec{r}$  is **continuous at**  $a$  if  $\lim_{t \rightarrow a} \vec{r}(t) = \vec{r}(a)$ .

$\vec{r}$  is continuous at  $a$  if and only if its component functions  $f$ ,  $g$ , and  $h$  are continuous at  $a$ .

**Space curves.** Suppose that  $f$ ,  $g$ , and  $h$  are continuous real-valued functions on an interval  $I$ . Then the set  $C$  of all points  $(x, y, z)$  in space, where

$$x = f(t), \quad y = g(t) \quad z = h(t)$$

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and  $t$  varies throughout the interval  $I$ , is called a **space curve**. Equations

$$x = f(t), \quad y = g(t) \quad z = h(t)$$

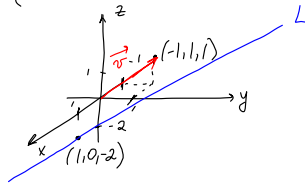
are called **parametric equations of C** and  $t$  is called a **parameter**.

**Example 3.** Sketch the curve with the given vector equation.

1.  $\vec{r}(t) = \langle 1-t, t, t-2 \rangle$

$$\begin{cases} x = 1-t \\ y = t \\ z = t-2 \end{cases}$$

line  $L$  passes through  $(1, 0, -2)$   
and is parallel to the vector  $\langle -1, 1, 1 \rangle$

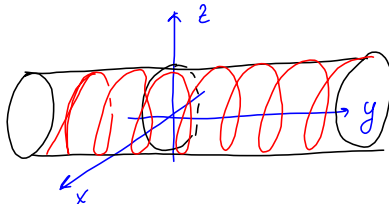


2.  $\vec{r}(t) = \langle \cos 4t, t, \sin 4t \rangle$

Parametric equations:

$$\begin{cases} x = \cos 4t \\ y = t \\ z = \sin 4t \end{cases}$$

$x^2 + z^2 = 1$  circular cylinder  
directed along the  $y$ -axis



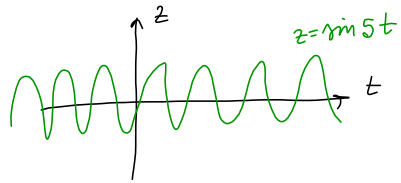
3.  $\vec{r}(t) = \langle \cos t, \sin t, \sin 5t \rangle$

$$x(t) = \cos t$$

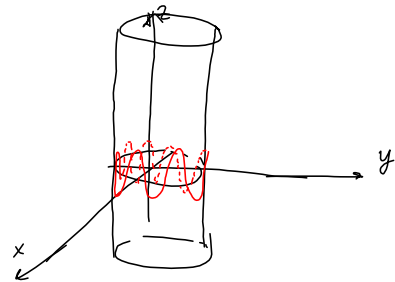
$$y(t) = \sin t$$

$$z(t) = \sin 5t$$

$$x^2 + y^2 = 1$$

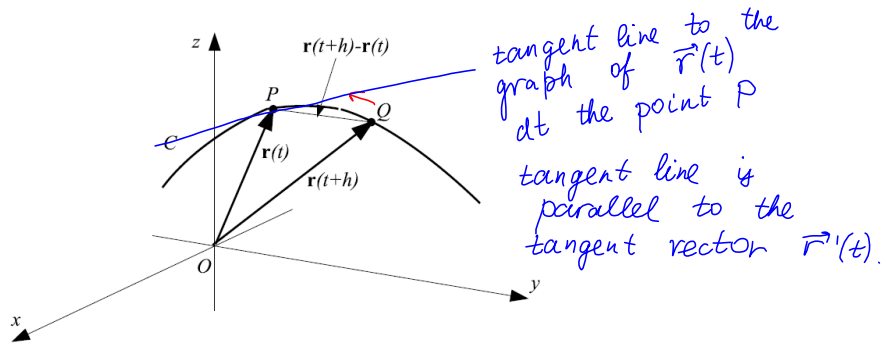


$$-1 \leq z \leq 1$$



**Derivatives and integrals.** The derivative  $\vec{r}'$  of a vector function  $\vec{r}$  is

$$\frac{d\vec{r}}{dt} = \vec{r}'(t) = \lim_{h \rightarrow 0} \frac{\vec{r}(t+h) - \vec{r}(t)}{h}$$



The vector  $\vec{r}'(t)$  is called the **tangent vector** to the curve defined by  $\vec{r}$  at the point  $P$ , provided that  $\vec{r}'(t)$  exists and  $\vec{r}'(t) \neq \vec{0}$ . The **tangent line** to  $C$  at  $P$  is defined to be the line through  $P$  parallel to the tangent vector  $\vec{r}'(t)$ . The **unit tangent vector**

$$\vec{T}(t) = \frac{\vec{r}'(t)}{|\vec{r}'(t)|}$$

**Theorem.** If  $\vec{r}(t) = \langle f(t), g(t), h(t) \rangle$ , then

$$\vec{r}'(t) = \langle f'(t), g'(t), h'(t) \rangle$$

**Example 4.** Find the derivative of the vector function  $\vec{r}(t) = \ln(4-t^2)\vec{i} + \sqrt{1+t}\vec{j} - 4e^{3t}\vec{k}$ .

$$\vec{r}'(t) = \left\langle \frac{-2t}{4-t^2}, \frac{1}{2}(1+t)^{-1/2}, -12e^{3t} \right\rangle$$

**Example 5.** At what point do the curves  $\vec{r}_1(t) = \langle t, 1-t, 3+t^2 \rangle$  and  $\vec{r}_2(s) = \langle 3-s, s-2, s^2 \rangle$  intersect? Find their angle of intersection.

$$\vec{r}_1(t) = \langle t, 1-t, 3+t^2 \rangle, \quad \vec{r}_2(s) = \langle 3-s, s-2, s^2 \rangle$$

1) Point of intersection.

Parametric equations:

$$\vec{r}_1(t): \begin{cases} x=t \\ y=1-t \\ z=3+t^2 \end{cases}$$

$$\vec{r}_2(s): \begin{cases} x=3-s \\ y=s-2 \\ z=s^2 \end{cases}$$

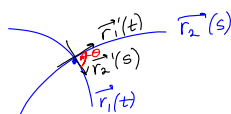
$$\begin{cases} t=3-s \\ 1-t=s-2 \\ 3+t^2=s^2 \end{cases} \quad \text{solve for } s \text{ and } t$$

$$\begin{cases} t=3-s \\ 1-t=s-2 \\ 3+t^2=s^2 \end{cases} \rightarrow \begin{cases} 1-(3-s)=s-2 \\ 1-3+s=s-2 \\ s-2=s-2 \end{cases}$$

$$\begin{cases} t=3-s \\ 3+t^2=s^2 \\ 3+(3-s)^2=s^2 \\ 3+9-6s+s^2=s^2 \\ 12-6s=0 \\ s=2 \end{cases} \quad \begin{cases} t=1 \\ s=2 \end{cases}$$

Point of intersection  $\vec{r}_1(1) = (1, 0, 4)$   
 $\vec{r}_2(2) = (1, 0, 4)$

2)



Tangent vectors:

$$\vec{r}_1'(t) = \langle 1, -1, 2t \rangle$$

$$\vec{r}_2'(s) = \langle -1, 1, 2s \rangle$$

Tangent vectors at  $(1, 0, 4)$

$$\vec{r}_1'(1) = \langle 1, -1, 2 \rangle$$

$$\vec{r}_2'(2) = \langle -1, 1, 4 \rangle$$

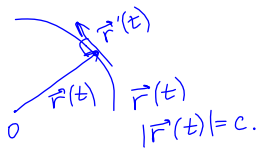
$$\cos \theta = \frac{\langle 1, -1, 2 \rangle \cdot \langle -1, 1, 4 \rangle}{\sqrt{1+1+4} \sqrt{1+1+16}} = \frac{6}{\sqrt{6} \sqrt{18}} = \frac{1}{\sqrt{3}}$$

$$\theta = \cos^{-1}\left(\frac{1}{\sqrt{3}}\right)$$

**Theorem.** Suppose  $\vec{u}$  and  $\vec{v}$  are differentiable vector functions,  $c$  is a scalar, and  $f$  is a real-valued function. Then

1.  $\frac{d}{dt}[\vec{u}(t) + \vec{v}(t)] = \vec{u}'(t) + \vec{v}'(t)$
2.  $\frac{d}{dt}[c\vec{u}(t)] = c\vec{u}'(t)$
3.  $\frac{d}{dt}[f(t)\vec{u}(t)] = f'(t)\vec{u}(t) + f(t)\vec{u}'(t)$
4.  $\frac{d}{dt}[\vec{u}(t) \cdot \vec{v}(t)] = \vec{u}'(t) \cdot \vec{v}(t) + \vec{u}(t) \cdot \vec{v}'(t)$
5.  $\frac{d}{dt}[\vec{u}(t) \times \vec{v}(t)] = \vec{u}'(t) \times \vec{v}(t) + \vec{u}(t) \times \vec{v}'(t)$
6.  $\frac{d}{dt}[\vec{u}(f(t))] = f'(t)\vec{u}'(t)$

**Example 6.** Show that if  $|\vec{r}(t)| = c$ , where  $c$  is a constant, then  $\vec{r}'(t)$  is orthogonal to  $\vec{r}(t)$  for all  $t$ .



$$\begin{aligned} \vec{r}(t) \cdot \vec{r}(t) &= |\vec{r}(t)| \cdot |\vec{r}(t)| \cos 0 \\ &= |\vec{r}(t)|^2 = c^2, \quad c \text{ is a constant} \\ \vec{r}(t) \cdot \vec{r}(t) &= c^2 \\ \frac{d}{dt}(\vec{r}(t) \cdot \vec{r}(t)) &= \frac{d}{dt}(c^2) \\ \vec{r}'(t) \cdot \vec{r}(t) + \vec{r}(t) \cdot \vec{r}'(t) &= 0 \\ \text{OR } 2\vec{r}(t) \cdot \vec{r}'(t) &= 0 \\ \text{OR } \vec{r}(t) \cdot \vec{r}'(t) &= 0 \rightarrow \boxed{\vec{r}(t) \perp \vec{r}'(t)} \end{aligned}$$

The **definite integral** of a continuous vector function  $\int_a^b \vec{r}(t) dt = \left\langle \int_a^b f(t) dt, \int_a^b g(t) dt, \int_a^b h(t) dt \right\rangle$

The Fundamental Theorem of Calculus for continuous vector functions says that

$$\int_a^b \vec{r}(t) dt = \vec{R}(t) \Big|_a^b = \vec{R}(b) - \vec{R}(a)$$

where  $\vec{R}$  is an antiderivative of  $\vec{r}$ . We use the notation  $\int \vec{r}(t) dt$  for indefinite integrals (antiderivatives).

**Example 7.** Find  $\vec{r}(t)$  if  $\vec{r}'(t) = \langle \sin t, -\cos t, 2t \rangle$  and  $\vec{r}(0) = \vec{i} + \vec{j} + 2\vec{k}$ .  
 $= \langle 1, 1, 2 \rangle$

$$\begin{aligned} \vec{r}(t) &= \int \vec{r}'(t) dt = \langle \int \sin t dt, \int (-\cos t) dt, \int 2t dt \rangle \\ &= \langle -\cos t + C_1, -\sin t + C_2, t^2 + C_3 \rangle \end{aligned}$$

$$\langle 1, 1, 2 \rangle = \vec{r}(0) = \langle -1 + C_1, C_2, C_3 \rangle$$

$$\begin{cases} 1 = -1 + C_1 & C_1 = 2 \\ 1 = C_2 & C_2 = 1 \\ 2 = C_3 & C_3 = 2 \end{cases}$$

$$\boxed{\vec{r}(t) = \langle -\cos t + 2, -\sin t + 1, t^2 + 2 \rangle}$$