## Section 13.1 Vector functions and space curves.

Let $\mathbf{r}$ be a vector function whose range is a set of three-dimensional vectors.

$$
\mathbf{r}(t)=<f(t), g(t), h(t)>=f(t) \mathbf{i}+g(t) \mathbf{j}+h(t) \mathbf{k}
$$

Functions $f, g$, and $h$ are real-valued functions called the component functions of $\mathbf{r}$.
The domain of $\mathbf{r}$ consists of all values of $t$ for which the expression for $\mathbf{r}(t)$ is defined.
Example 1. Find the domain of the vector function $\mathbf{r}(t)=\left\langle\sqrt{9-t}, \sqrt{t-2}, \frac{e^{t}}{t-5}\right\rangle$.

Definition. If $\mathbf{r}(t)=<f(t), g(t), h(t)>$, then

$$
\lim _{t \rightarrow a} \mathbf{r}(t)=\left\langle\lim _{t \rightarrow a} f(t), \lim _{t \rightarrow a} g(t), \lim _{t \rightarrow a} h(t)\right\rangle
$$

provided the limits of the component function exist.
Example 2. Find the limit

$$
\lim _{t \rightarrow 0}\left\langle\frac{1-\cos t}{t}, t^{3}, e^{-1 / t^{2}}\right\rangle
$$

Definition. A vector function $\mathbf{r}$ is continuous at $a$ if $\lim _{t \rightarrow a} \mathbf{r}(t)=\mathbf{r}(a)$.
$\mathbf{r}$ is continuous at $a$ if and only if its component functions $f, g$, and $h$ are continuous at $a$.
Space curves. Suppose that $f, g$, and $h$ are continuous real-valued functions on an interval $I$. Then the set $C$ of all points $(x, y, z)$ in space, where

$$
x=f(t), \quad y=g(t) \quad z=h(t)
$$

ant $t$ varies throughtout the interval $I$, is called a space curve. Equations

$$
x=f(t), \quad y=g(t) \quad z=h(t)
$$

are called parametric equations of $\mathbf{C}$ and $t$ is called a parameter.

Example 3. Sketch the curve with the given vector equation.

1. $\mathbf{r}(t)=<1-t, t, t-2>$
2. $\mathbf{r}(t)=<\cos 4 t, t, \sin 4 t>$
3. $\mathbf{r}(t)=<\cos t, \sin t, \sin 5 t>$

Derivatives and integrals. The derivative $\mathbf{r}^{\prime}$ of a vector function $\mathbf{r}$ is

$$
\frac{d \mathbf{r}}{d t}=\mathbf{r}^{\prime}(t)=\lim _{h \rightarrow 0} \frac{\mathbf{r}(t+h)-\mathbf{r}(t)}{h}
$$



The vector $\mathbf{r}^{\prime}(t)$ is called the tangent vector to the curve defined by $\mathbf{r}$ at the point $P$, provided that $\mathbf{r}^{\prime}(t)$ exists and $\mathbf{r}^{\prime}(t) \neq \overrightarrow{0}$. The tangent line to $C$ at $P$ is defined to be the line through $P$ parallel to the tangent vector $\mathbf{r}^{\prime}(t)$. The unit tangent vector

$$
\mathbf{T}(t)=\frac{\mathbf{r}^{\prime}(t)}{\left|\mathbf{r}^{\prime}(t)\right|}
$$

Theorem. If $\mathbf{r}(t)=<f(t), g(t), h(t)>$, then

$$
\mathbf{r}^{\prime}(t)=<f^{\prime}(t), g^{\prime}(t), h^{\prime}(t)>
$$

Example 4. Find the derivative of the vector function $\mathbf{r}(t)=\ln \left(4-t^{2}\right) \mathbf{i}+\sqrt{1+t} \mathbf{j}-4 e^{3 t} \mathbf{k}$.

Example 5. At what point do the curves $\mathbf{r}_{1}(t)=<t, 1-t, 3+t^{2}>$ and $\mathbf{r}_{2}(s)=<3-s, s-2, s^{2}>$ intersect? Find their angle of intersection.

Theorem. Suppose $\mathbf{u}$ and $\mathbf{v}$ are differentiable vector functions, $c$ is a scalar, and $f$ is a real-valued function. Then

1. $\frac{d}{d t}[\mathbf{u}(t)+\mathbf{v}(t)]=\mathbf{u}^{\prime}(t)+\mathbf{v}^{\prime}(t)$
2. $\frac{d}{d t}[c \mathbf{u}(t)]=c \mathbf{u}^{\prime}(t)$
3. $\frac{d}{d t}[f(t) \mathbf{u}(t)]=f^{\prime}(t) \mathbf{u}(t)+f(t) \mathbf{u}^{\prime}(t)$
4. $\frac{d}{d t}[\mathbf{u}(t) \cdot \mathbf{v}(t)]=\mathbf{u}^{\prime}(t) \cdot \mathbf{v}(t)+\mathbf{u}(t) \cdot \mathbf{v}^{\prime}(t)$
5. $\frac{d}{d t}[\mathbf{u}(t) \times \mathbf{v}(t)]=\mathbf{u}^{\prime}(t) \times \mathbf{v}(t)+\mathbf{u}(t) \times \mathbf{v}^{\prime}(t)$
6. $\frac{d}{d t}[\mathbf{u}(f(t))]=f^{\prime}(t) \mathbf{u}^{\prime}(t)$

If $|\mathbf{r}(t)|=c$, where $c$ is a constant, then $\mathbf{r}^{\prime}(t)$ is orthogonal to $\mathbf{r}(t)$ for all $t$.
The definite integral of a continuous vector function $\int_{a}^{b} \mathbf{r}(t) d t=\left\langle\int_{a}^{b} f(t) d t, \int_{a}^{b} g(t) d t, \int_{a}^{b} h(t) d t\right\rangle$
The Fundamental Theorem of Calculus for continuous vector functions says that

$$
\left.\int_{a}^{b} \mathbf{r}(t) d t=\mathbf{R}(t)\right]_{a}^{b}=\mathbf{R}(b)-\mathbf{R}(a)
$$

where $\mathbf{R}$ is an antiderivative of $\mathbf{r}$. We use the notation $\int \mathbf{r}(t) d t$ for indefinite integrals (antiderivatives). Example 6. Find $\mathbf{r}(t)$ if $\mathbf{r}^{\prime}(t)=<\sin t,-\cos t, 2 t>$ and $\mathbf{r}(0)=\mathbf{i}+\mathbf{j}+2 \mathbf{k}$.

