

Section 13.4. Motion in space: velocity and acceleration

Definition. If $\mathbf{r}(t) = \langle x(t), y(t), z(t) \rangle$ is a vector function representing the position of a particle at time t , then velocity at time t is

$$\mathbf{v}(t) = \mathbf{r}'(t) = \langle x'(t), y'(t), z'(t) \rangle$$

speed at time t is

$$s = |\mathbf{v}(t)| = \sqrt{[x'(t)]^2 + [y'(t)]^2 + [z'(t)]^2}$$

acceleration at time t is

$$\mathbf{a}(t) = \mathbf{v}'(t) = \mathbf{r}''(t) = \langle x''(t), y''(t), z''(t) \rangle$$

Example 1. The vector function $\mathbf{r}(t) = \langle t^2 + t, t^2 - t, t^3 \rangle$ represents the position of a particle at time t . Find the velocity, acceleration and the speed.

velocity $\mathbf{v}(t) = \mathbf{r}'(t) = \langle 2t+1, 2t-1, 3t^2 \rangle$
 speed $s(t) = |\mathbf{v}(t)| = \sqrt{(2t+1)^2 + (2t-1)^2 + 9t^4} = \sqrt{8t^2 + 9t^4 + 2}$
 acceleration $\mathbf{a}(t) = \mathbf{v}'(t) = \langle 2, 2, 6t \rangle$

Example 2. Find the velocity and position vectors of a particle that has the acceleration $\mathbf{a}(t) = \sin t \mathbf{i} + 2 \cos t \mathbf{j} + 6t \mathbf{k}$ with the initial velocity $\mathbf{v}(0) = -\mathbf{k}$ and initial position $\mathbf{r}(0) = \mathbf{j} - 4\mathbf{k}$.

$$\mathbf{a}(t) = \langle \sin t, 2 \cos t, 6t \rangle, \quad \mathbf{v}(0) = \langle 0, 0, -1 \rangle, \quad \mathbf{r}(0) = \langle 0, 1, -4 \rangle$$

$$\mathbf{v}(t) = \int \mathbf{a}(t) dt = \langle \int \sin t dt, \int 2 \cos t dt, \int 6t dt \rangle$$

$$\mathbf{v}(t) = \langle -\cos t + C_1, 2 \sin t + C_2, 3t^2 + C_3 \rangle$$

Plug in $t=0$: $\mathbf{v}(0) = \langle -1 + C_1, C_2, C_3 \rangle = \langle 0, 0, -1 \rangle$

$$\begin{aligned} -1 + C_1 &= 0 &\Rightarrow C_1 &= 1 \\ C_2 &= 0 \\ C_3 &= -1 \end{aligned}$$

$$\mathbf{v}(t) = \langle -\cos t + 1, 2 \sin t, 3t^2 - 1 \rangle$$

$$\mathbf{r}(t) = \int \mathbf{v}(t) dt = \langle \int (-\cos t + 1) dt, \int 2 \sin t dt, \int (3t^2 - 1) dt \rangle$$

$$= \langle -\sin t + t + K_1, -2 \cos t + K_2, t^3 - t + K_3 \rangle$$

K_1, K_2, K_3 are constants.

Plug in $t=0$: $\mathbf{r}(0) = \langle K_1, -2 + K_2, K_3 \rangle = \langle 0, 1, -4 \rangle$

$$\begin{aligned} K_1 &= 0 & -2 + K_2 &= 1 & K_3 &= -4 \\ K_2 &= 3 \end{aligned}$$

$$\mathbf{r}(t) = \langle -\sin t + t, -2 \cos t + 3, t^3 - t - 4 \rangle$$